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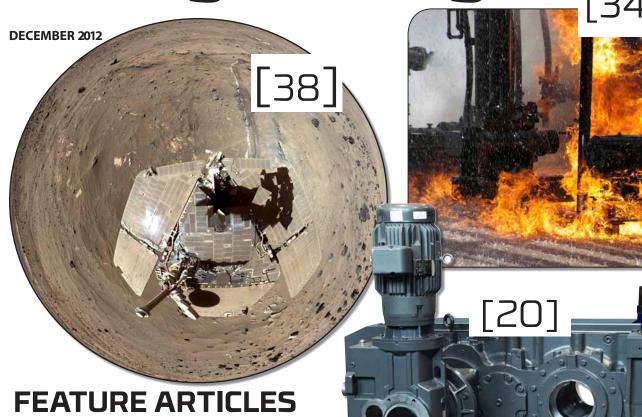


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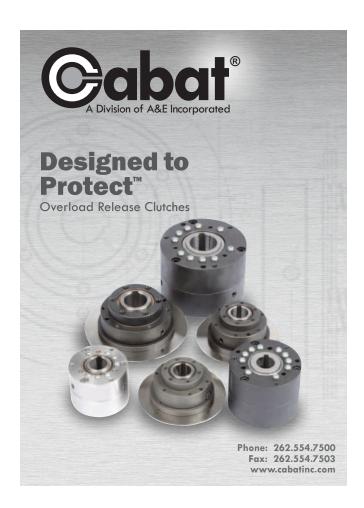
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# **Gears on Mars!**

Forest City Gear employees talk about their work manufacturing gears for the Mars Rover Curiosity in a short documentary web series by Pablo Korona.

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Representatives from Diamond Chain and Motion Industries demonstrate the basic principles behind drive-shaft alignment for chain-and-sprocket drives.

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Explore the operating principles of the Hägglunds hydraulic motor from Bosch Rexroth in this video showing cutaway views of the inner workings of the device, which is suitable for many heavy-duty applications.

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# **New Additions and Updates**

The following companies have recently added premium listings or updated their listings on *powertransmission.com*. For the most current and up-to-date directory of mechanical power transmission component suppliers, visit *www.powertransmission.com/directory/* 

# **Sumitomo**Drive Technologies

Sumitomo Drive Technologies is a business division of Sumitomo Heavy Industries (SHI), one of the largest manufacturers of machinery in Japan, and the global leader in power transmission knowledge and innovation.



Headquartered in Elgin, Illinois, Dunkermotor is the North American sales, technical support and logistics subsidiary of Dunkermotoren GmbH, for 60 years the global quality and value leader in customized, configurable solesource fractional horsepower motion control solutions.



Cabat Inc. located in Racine, WI manufactures a variety of dependable and precise overload/torque limiting release clutches.

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# Power Transmission Engineering

### **Randall Publications LLC**

1840 Jarvis Avenue Elk Grove Village, IL 60007 Phone: (847) 437-6604 Fax: (847) 437-6618

### **EDITORIAL**

# Publisher & Editor-in-Chief

Michael Goldstein publisher@powertransmission.com

### **Managing Editor**

Randy Stott wrs@powertransmission.com

### **Senior Editor**

Jack McGuinn jmcquinn@powertransmission.com

### Associate Editor

Matthew Jaster mjaster@powertransmission.com

# **Editorial Consultant**

Paul R. Goldstein

### ART

### **Art Director**

David Ropinski dropinski@powertransmission.com

### **ADVERTISING**

# Advertising Sales Manager

Dave Friedman dave@powertransmission.com

# Materials Coordinator

Dorothy Fiandaca dee@randallpublications.com

## CIRCULATION

## **Circulation Manager**

Carol Tratar subscribe@powertransmission.com

### **RANDALL PUBLICATIONS STAFF**

### President

Michael Goldstein

Accounting Luann Harrold

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# **Ron Popeil Would Be Proud**

Every year at Christmas, someone in my family receives a gag gift. The more gimmicky and ridiculous the item, the better the joke. Over the years, a number of such items have been gifted and re-gifted so many times that they're now ensconced in family lore. For example, we had an FM-radio/toilet paper holder that made the rounds for several years—until one of my uncles decided to actually install it (much to my aunt's dismay).

But without question, the best of these gifts, and my personal favorite—is the Egg Scambler, a vintage "As Seen on TV" marvel, made by Ronco in the 1970s. We've been trading it back and forth for as long as I can remember.

The Egg Scrambler is sheer engineering genius. A tiny, bent wire pokes a hole in the egg. A motor spins the wire, and-voila-the egg is scrambled inside the shell. No need for bowls or whisks. Just crack it in the frying pan and you're good to go.

Mind you, I've never actually seen whether the Egg Scrambler works. No one in our family has. You see, our Egg Scrambler has never been used. It's still in its original box, wrapped in Cellophane. I think that's part of its appeal. But Ronco has sold a lot of them over the years. In fact, you can still buy them today.

The reason I'm telling you about the Egg Scrambler is not so much to reminisce about childhood memories, but rather because it came to mind when I started thinking about this issue of the magazine—particularly our printed buyers guide. The Egg Scrambler never caught on like some of Ronco's other products—such as the Veg-O-Matic, but it was

originally sold the same way, via the television infomercial.

You all know the schtick. Ron Popeil demonstrates the amazing Veg-O-Matic and all of its slicing and dicing wonders. You're already convinced you need one, when he asks, "How much would you pay for that? \$59.99? \$49.99? How about the low, low price



Image ©1978 Ronco Teleproducts, Inc.



of \$19.99?" And it sounds like a good deal, but he's got another sly trick up his sleeve, in the form of one of the most successful marketing catchphrases of all time: "But Wait! There's More!"

Our Buyers Guide is like that, too. We've compiled a comprehensive list of suppliers of mechanical power transmission components. You'll find their addresses, phone numbers and websites, all broken down by major product categories. I have no doubt that many of you who are buyers and specifiers of gears, bearings, motors, clutches, couplings, brakes and the like will find it an indispensable resource, which you'll refer to over and over throughout the year. And you don't even have to worry about how much you'd pay for it, because it's free.

But Wait! There's More! In fact, the printed buyers guide is only the beginning. Our online Buyers Guide, at www.powertransmission.com, breaks down each product category into subcategories, so you can identify the exact suppliers you need for your mechanical power transmission needs. Plus, many of the top suppliers have premium listings online, which means you can also read detailed descriptions about each company's products and services, and you can contact those suppliers directly through the website.

Products like the Egg Scrambler and Veg-O-Matic were designed to save you time and money. And the same can be said of our Buyers Guide. Finding the right supplier can make all the difference in terms of making your products and/or operations more efficient, more productive, less expensive or of a higher quality.

And while I called the Egg Scrambler sheer engineering genius, the true engineering genius can be found right here in our pages. The Buyers Guide is filled with companies offering the most sophisticated technology available, manufactured to the highest standards. We hope you'll take ad-

vantage. PTE

P.S. I'm pretty sure my sister got the Egg Scrambler last year. I'm guessing that when she has to give it to someone else, she'll be pretty sad. That's why I bought her a set of "Toastabags." You put a slice of cheese between two pieces of bread in the Toastabag. Pop it in your toaster, and you get a grilled cheese sandwich in about a minute. No fuss. No mess. I can't wait to see the look on her face.

# From the Forest City Gear Family To You and Yours...Merry Christmas

During exceptionally busy years like this one we never truly stop thinking about our customers and their gear production challenges. Yet the holiday season reminds us of how blessed we are – for our family and team members, our industry and all our business associates.

From all of us at Forest City Gear: wishing you a very Merry Christmas and may your 2013 be a joyous and prosperous one.



11715 Main Street, Roscoe, IL 61073 815-623-2168



# It's All About the Cliff...

# ...but, selectively speaking—still better long than short!

Brian Langenberg, CFA

We anticipate sluggish near-term growth driven by inventory re-stock, improved residential housing and momentum in particular end markets—e.g. commercial aviation, resource extraction (coal and slowing natural gas) and power transmission and distribution.

Elections have consequences. Posturing was inevitable no matter who won, but decision makers will continue to sit on their hands until D.C. firmly establishes some ground rules regarding tax rates. Meanwhile, we are skeptical of any real improvement in the regulatory environment. If anything, we remain concerned about incremental employment growth (healthcare impact on service-oriented employment growth); availability of qualified labor (public schools: mostly bad; vocational training: not meeting need) and deteriorating infrastructure (roads, bridges, grid).

At the moment the administration thinks, or is at least acting, like it has a mandate for sharply higher taxes with little curtailment in spending. On the other side, Republican senate minority leader Mitch McConnell did not achieve his goal of making President Obama a one-termer, but do recall that he was the guy who stood ground and rallied his party after 2008 when Democrats had the run of the table. It is delu-

sional to think he is going to back down this time around, either. The reality is that, for most people, "who is right" is linked to "how they voted." Regardless—what is required now is a centrist approach with mutual compromise.

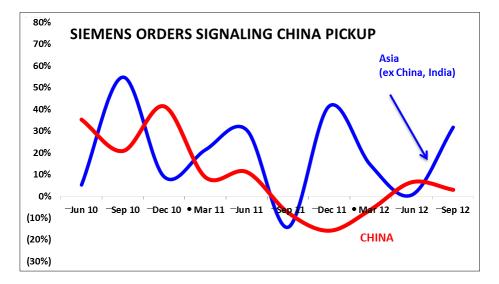
The range of possible outcomes is considerable—and on the road to reaching one we can count on much noise, carping and pundit-infused bloviating from all of the news outlets—with one's political leanings dictating which of them hold our attention. But in the spirit of much-needed, reasoned discourse, here is our view of the range of scenarios:

- "Grand Bargain": 1 percent probability. This would be the smart way to do it, meaning of course it is DOA during a lame duck session. Such a deal would have three components: 1) lower corporate taxes (everyone agrees); 2) higher income tax revenue (Republicans are for reducing deductions, Democrats for higher rates); and 3) entitlement reform—i.e., raising retirement age, means testing benefits (which Dems are unwilling to negotiate).
- Muddle through: 85% probability. Extend most Bush-era tax cuts along with payroll tax relief—and borrow more while hammering out a real budget. This is the easiest

- (read: most politically expedient) thing to do and thus the most likely.
- A Republican rollover: 1%
  probability. This is not going to
  happen; McConnell will see to it
  because the last election was not a
  mandate for more government. Tea
  Party and religious conservatives
  are the party base and nearly half
  the electorate. Senior Republican
  leadership (often an oxymoron)
  will focus on two achievable goals:
  1) fixing the immigration position;
  and 2) ditto the Repubs' senatorial
  candidate vetting process. Both
  will involve educating, and some
  accommodation with, its base.
- Thelma & Louise, a.k.a. Fiscal Cliff: 13 percent probability. This... can happen. And... the odds have increased since November sixth. It does not matter what I think should happen nor what you think should happen. It also doesn't matter what the media, CEOs or Europe think. What *does* matter in this scenario are the goals, agenda and political calculations of just a few players.

We do expect a deal providing sufficient clarity for business decisions to be made. Will such a deal be perfect or enough to deal with long-term issues? As we said, a "Grand Bargain" probability is 1 percent at best in the nearterm. But as long as some sort of palatable deal is brokered there is reason for optimism. That said—and assuming some kind of deal is cut...

China is positioned to accelerate in second-half 2013. The drivers are pretty clear. After putting on the brakes in 2011-2012 to deal with rampant inflation and real estate speculation, coupled with an unusually public and tense "transition year" with respect to leadership, we expect China to step on the gas. We do not take the view that China can, or will, drive the global economy, but it remains a major component. Certain pieces are already in place; easy comparisons—signals that increased raw material purchasesare anticipated and a new political leadership team eager to come out of



the blocks fast and secure power will lead to a growth-oriented agenda.

European exporters would benefit. Even a modest tailwind for motors, drives, and power-related infrastructure could do wonders for the margins of a range of companies and we anticipate China picking up will help.

Signs of improvement already exist. Part of the client work we do here is monitor and analyze key data from over 55 global industrial companies. Several provide regional order detail and, as shown above, the Siemens order patterns are suggesting we are, at worst, in only a lull.

The U.S. economy should continue to improve, albeit gradually. Housing and automotive demand continues to rise. In particular, residential housing growth is slated to grow 11-13 percent for the next couple of years—well below historical norms but consistent with a weak recovery. And though improving home prices could prove to accelerate a turnaround, we suspect the length and depth of this most recent downturn has materially impacted societal views about leverage, debt and home price appreciation for at least the next few years. Still - it's enough to drive continued higher demand for construction/rental equipment and at least maintenance capital spending. Barriers to faster growth remain, as whatever combination of spending cuts and tax increases will serve as a headwind.

The rest of Asia a good leading indicator on China industrial activity and, as noted, the last quarter pick-up in orders suggests that at least modest gains are in our near future. While construction equipment demand will be down for at least 2-3 quarters (we think 3-5), we note that process automation never slowed and we anticipate a pickup in industrial automation (motors, drives), construction-related (low-, medium-voltage) and transportation infrastructure (rail). We think this will serve as a catalyst for not only direct Asian demand but also as a catalyst for

S&P 500	:	1386.4					,
	S&P	500 Earn	ings				
P/E	\$93	\$105	\$112		Price Return		rn
14x	1,302	1,470	1,568		(6%)	6%	13%
15x	1,395	1,575	1,680		1%	14%	21%
16x	1,488	1,680	1,792		7%	21%	29%
17x	1,581	1,785	1,904		14%	29%	37%
18x	1,674	1,890	2,016		21%	36%	45%
SKY IS FA	ALLING	9	S&P 500	<u>lm</u>	ol. Ret.		
5/6/09 A	rmagged	on	683.38		(51)%		
8/19/11 US Downgrade 1123.5 (19)%							
%							
Prob.							
1%	1% Grand Bargain - lower corporate, < loop holes.						
85%	Short-term deal, argue in 2H13						
1%	Obama Steamrolls Mitch McConnell on taxes						
13%		Fiscal Pothole					
100%							

European exporters of heavier capital equipment.

In our view, the markets implicitly assume a "muddle through" agree*ment.* Should we slide well past the New Year without a deal, I suspect markets would start to react in a very material way.

Consensus estimates for the S&P 500 Index are about \$102 in 2012 and \$112 in 2013. However, given estimate revision trends (down) and common sense (acquired via the tread marks on my back from being in the business for 24 years) we will plug in \$105.

In our view, there is a high likelihood of positive returns (pick your flavor as to magnitude) as long as earnings come through and the market P/E holds at about 14X.

There is a small likelihood—but potentially very painful—if it occurred of significant declines.

How significant? Let's eliminate the guesswork and ponder the two worst downdrafts in the past five years:

- 1. The 2009 low (- 51 percent)
- 2. The downgrade of the U.S. by S&P in 2011 (-19 percent)

My sense is that-should we find ourselves come January in "full-cliff,"

extended-free-fall mode-and resulting full recession-that "down" could mean a realistically achievable 20 percent slide. Like most participants in the market, I do not think it will happen.

And so, better long than short **but, selectively.** Our institutional and high-net-worth investor clients know where we stand; i.e.—only on to between hold and those things in which their intrinsic value means you are being "paid to wait" (e.g., General Electric, Tyco International). Or, for those who must be invested, we point also to United Technologies and Dover Corporation as offering "market-plus" returns. PTE

# Brian K. Langenberg, CFA, has been recognized as a

member of the Institutional Investor All-America Research Team, a Wall Street Journal All-Star, and Forbes/Starmine (#1 earnings estimator for industrials). Langenberg speaks and meets regularly



with CEOs and senior executives of companies with over \$1 trillion in global revenue. His team publishes the Quarterly Earnings Monitor/ Survey—gathering intelligence and global insight to support decision-making. You can reach him at Brian@Langenberg-llc.com or his website at www.Langenberg-LLC.com.

# Renishaw

# OFFERS ENCODERS FOR WIND TURBINE BEARINGS

Blade pitch adjustment is one of the most critical functions of wind turbine operation, and the giant bearings in the adjustment mechanism can now be manufactured with accuracy typically reserved for small parts, using a new vertical turn/grind machine from Swedish builder KMT Lidköping. The machine combines advanced motion systems with Renishaw optical and magnetic linear and angle encoders on critical axes to achieve form deviation of less than 1 μm on parts 4,000 mm in diameter.

"This is hard turning and grinding, and is very demanding," said Eive Johansson, KMT Lidköping's chief designer. "Positioning accuracy is very important, with a direct effect on the quality of the finished bearings." Prior to the VTG4000, the company's largest machine could accommodate parts up to 600 mm (24 in.) diameter, but the VTG4000 handles diameters in excess of 4,000 mm (157 in.), the size of the largest wind turbine bearings, while providing much greater accuracy.

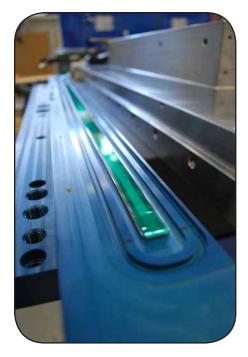
Linear motors on the linear axes make the VTG4000 fast, and firm hydrostatic guideways increase accuracy. "A standard size machine, using ballscrews on the axes, maintains about a 3 µm form deviation," said Johannson. "This machine maintains form deviation of less than 1 µm with

feed resolution in 0.1 µm steps." Linear slides are at the heart of Lidköping machines, and the combination of hydrostatic guideways, air seals and linear motors creates a stiff, accurate, maintenance-free system. "To achieve dynamic stiffness we need high gain, which is linked to the quality of the encoder scales," explained Johansson. "It also makes a big difference that the angle encoders have the scale integrated directly onto the ring."

# **High Quality Improves Control** of Turbine Blades

Pitch bearings allow wind turbine blades to optimize their angle according to wind speed, or create a stall condition in high winds, so the reliability of these bearings is critical to efficient, safe operation.

The multi-tasking VTG4000 is designed to machine these large bearings in a single set up, performing both turning and grinding with two separate heads. The two heads are configured as required, usually grinding/turning or grinding/grinding. The machine's 4.5 m X-axis carries the two heads on opposite sides of the part, and allows both grinding and turning tools to access the outside of the part. With some components weighing more than 35 tonnes, the VTG4000 is very resistant to distortion and thermal variation,



which is aided by closely controlled hydrostatic oil and coolant temperatures. "We've used hydrostatic guideways since the 1970's, and combining them with linear motors gives us a faster, more accurate machine capable of far greater acceleration and deceleration," said plant manager Henrik Jonsson. "When you see that you can move the 25,000 kg rotary axis with your finger, you realize how good the hydrostatic system is."

Johansson first saw the encoders that would end up on the VTG4000 at the EMO show in 2007, and Lidköping put the sensors through rigorous testing. "We compared different scales assembled on our reference slide and selected the one with the best performance," said Johansson. "It was important that the linear encoders have a continuous length of at least 4.5 m, as well as high dirt resistance, and SiG-NUM fit these requirements the best. We have fitted them to all four linear slides, and have had no problems. Our rotary table has the same design principle, with hydrostatic radial and axial bearings, air seals and torque motors. We did the same analysis and chose the SiGNUM angle encoders."

Renishaw's LM10 magnetic angle encoders are fitted to the B-axes of the grinding heads. These encoders are exposed to the harsh conditions of the machine environment, but their





non-contact, non-optical design, and sealing to IP68, protects them from the effects of coolant and swarf. The digital or analog output LM10 allows up to 100 m travel and high-speed operation of up to 25 m/s (4 m/s at 1  $\mu$ m resolution).

All Renishaw encoders feature an integral patented set-up LED that speeds installation and removes the need for complex set-up equipment or oscilloscopes. "One of the best features of the Renishaw encoders is how easy they are to set up," added Johnasson. "With the scale attached and the readhead approximately located, the indicator lights make it very easy to see how well the two elements are aligned."

To accurately set the part in the machine's work-coordinate system, the VTG4000 uses a Renishaw RMP60 radio signal transmission touch probe. After a raw part is placed on the bed, the RMP60 is loaded into the tool changer and used to locate the exact position of key features in a matter of seconds. This data is used to update the coordinate system in-cycle for quick, accurate machining.

# For more information:

Renishaw Inc. 5277 Trillium Blvd. Hoffman Estates, IL 60192 Phone: (847) 286-9953 www.renishaw.com





# Kollmorgen DELIVERS COMPONENTS FOR ELECTRIC

VT BOLT, Virginia Tech University's entry to the 2012 all-electric TTXGP is a 100 percent electric racing motorcycle driven by a low-voltage Kollmorgen AKM 74 AC permanent magnet motor and a Kollmorgen ACS80XL 80V Gen6 drive. The results have been impressive, with the AKM motor and ACS drive enabling VT BOLT to achieve

top speeds in excess of 100 mph with consistently high performance throughout

the duration of each approximately 20-mile race using a 7.5 kilowatt hour battery pack. The VT BOLT was a recent first place winner of all three of its TTX75-cup races including Portland International Raceway, Laguna Seca Raceway and Miller Raceway, solidifying VT BOLT as the 2012 North American TTX75 Cup winner.

Virginia Tech's BOLT was designed to compete in the 75-class (7.5 kWh energy storage) motorcycle division. The idea was to develop a 100 percent electric motorcycle that could perform as fast as possible, while optimizing the energy stored in the battery to achieve maximum performance throughout each race. It also required just the right balance of torque and speed to accommodate the numerous turns common to GP racetracks, but without overconsuming power and compromising performance at the end of each race. Virginia Tech not only had to understand the technology, they needed to integrate the technology into a purpose-built racing machine. The VT BOLT design team turned to Kollmorgen for help and sponsorship.

"Kollmorgen's standard technology platforms are ideal for a wide variety of high-performance applications in that they are easily customized to meet the specific needs of a particular application, and the VT BOLT project was no exception," says Brad Monday, design engineer for vehicle systems, Kollmorgen. "We not only helped the VT BOLT team identify and integrate components into an optimized system, but with our sophisticated application support we were able to provide

insight into how VT BOLT would perform on the track before it was built."

> Kollmorgen worked with the team at Virginia Tech to identify the optimum drive/motor/gearing system that

would enable VT BOLT to leverage the available power of the battery pack to deliver the best performance in terms of con-

sumption and speed, ultimately specifying a Kollmorgen AKM motor and ACS drive.

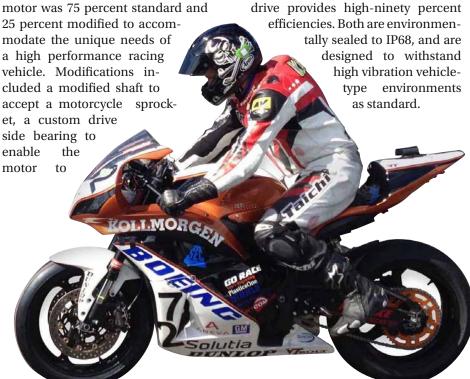
According to Monday, the AKM74

withstand the radial loads exerted on the shaft by the chain, and a modified motor winding to operate at the low voltage required by the 7.5 kWh battery pack.

The ACS80 is a 40 kW, or 54 hp, drive as standard. Kollmorgen delimited the drive for the VT BOLT application to enable higher power output (57.6 kW or 77.2 hp) for the shorter duty cycle and duration of the racing environment. Monday says that the Kollmorgen AC-S80XL 80V Gen6 drive was a perfect fit for VT BOLT because the capabilities needed to deliver the desired performance were inherent in the drive.

"The particular ACS drive used in the VT BOLT motorcycle is commonly used in 4-5 ton forklift vehicles to control traction. For VT BOLT we simply modified the drive interface to accept this application and programmed it to formulate speed, throttle and power regeneration for braking, while also coordinating the rider interfaces through the drive," explains Monday. "Other drives in the ACS family are often used to control steering wheels and brakes, operate hydraulic pumps and perform overall vehicle control; ACS drives are fundamentally flexible enough to be used in an assortment of applications."

The AKM motor provides mid-ninety percent efficiencies and the ACS drive provides high-ninety percent



The motor and controller convert DC power from the battery pack to AC power for the motor. The motor then takes the AC power and converts it to torque and speed to power the motorcycle's drivetrain. The drivetrain consists of two gears and a chain which are connected to the rear wheel of the motorcycle.

"This project was just a lot of fun from start to finish for everyone involved," says Monday. "It was a great opportunity to work with engineering students and to push the limits and boundaries of products to achieve high performance in a unique application. Additionally we get to share the finished product with Kollmorgen associated back at the plant to see and enjoy firsthand."

### For more information:

Kollmorgen 203A West Rock Road Radford, VA 24141 Phone: (540) 633-3545 www.kollmorgen.com

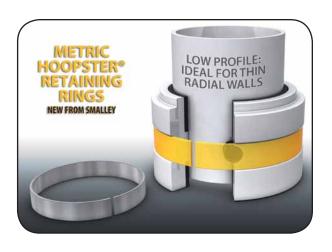
# **Smalley Steel**

OFFERS METRIC HOOPSTER RETAINING RINGS

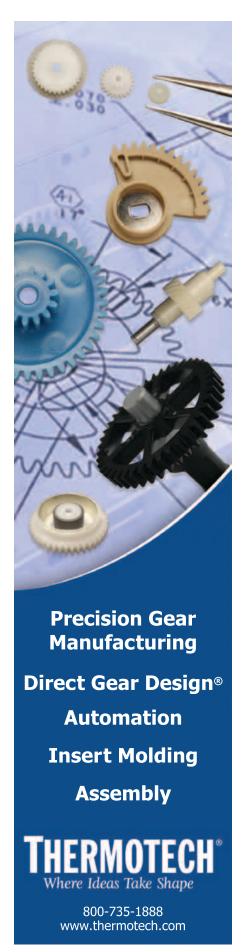
Smalley Steel Ring Company recently announced the launch of the new Metric Hoopster retaining rings. The new Metric Hoopster retaining rings offer an innovative way to retain mechanical components when space is a problem. The Hoopster's minimal radial projection and shallow groove depth allows the Hoopster to fit where regular stamped rings and retaining rings cannot. The Hoopster's low-profile, precision circularity and small radial size allow it to be an unobtrusive component in an assembly. Hoopster retaining rings are suitable for light to heavy loads and are ideal for thin wall tubes. An additional advantage of the Hoopster is its potential for high thrust capacity. The low radial profile will not twist or deform under load as with conventional retaining rings. As an extension to Smalley's popular Hoopster Retaining Rings, the new metric series offers engineers added design flexibility. Over 150 new rings are available from 10 mm to 76 mm in carbon and 302 stainless steel. Hoopster retaining rings are easy to install and remove without any special tools. Specials can be made with no-tooling-charges. Internal housing rings are available with an optional bent end (removal provision) to simplify the process.

### For more information:

Smalley Steel Rings 555 Oakwood Road Lake Zurich, IL 60047 Phone: (847) 719-5900 www.smalley.com







# **Stober Drives**

INTRODUCES EZE SERVOMOTOR

Stober Drives, Inc. of Maysville, Kentucky has introduced its EZF/PY hollow-bore pipe drive into its new product line. Only a few manufacturers in the world manufacture a similar product. The hollow bore servomotor ranges from a zero to 3,000 rpm output speed and 4.2 Nm to 350 Nm stall torque. It features an inside diameter ranging from 28 to 42 mm. The EZF is particularly well-suited for the packaging, printing, general automation, robotics and machine tool industries.

"The EZF-PY servomotor conforms to the high standards we set to continue Stober's heritage of delivering goldstandard products and exceptional service," said Peter Feil, vice president at Stober's Maysville, Kentucky plant. "The EZF will help customers substantially reduce their total cost of operations."

The gear motor eliminates the need for a right angle drive when space is critical, adding increased performance and lowering costs, said Adam Mellenkamp, product manager at Stober.

"The configuration has a hollow shaft that allows for power cables, air cables, data lines and laser beams to



get through the center of the motor," said Mellenkamp. "You can even use liquid cooling to increase torque capacity of the unit. This is our way of helping manufacturers become cleverer, leaner and utilize fewer parts."

The servomotor comes in frame sizes 5 (115 mm square) and 7 (145 mm square)-and an extremely short length: as small as 134 mm. "Everyone knows of a time when they could have used this gear motor," said Mellenkamp. "This product fills a needed niche in motion control."

The EZF/PY provides industrial implementation of tooth-winding using orthocyclic linear winding technology. This feature makes it possible to manufacture the stator windings with the highest possible copper fill factor. The winding technology increases the motor power output by approximately 80 percent; for this reason it is possible to shorten the length of the motor by almost half without reducing power output.

An advantage of the motor is that it is thermally protected by a positive temperature coefficient (PTC) in each phase of production. PTC in the EZF/ PY ensures that electrical resistance increases when outside temperature increases. Once the PTC reaches a certain temperature (145 degrees C.), the monitoring system activates to protect the motor winding from heat damage. A KTY-84 temperature sensor is also available.

The PY also has water or forced-air cooling for a higher-rated power at high ambient temperatures, allowing

> for a 35 percent torque increase. A fan can be added in the field. Due to its weight-saving design, the pipe drive is particularly suitable for applications in which the motor itself is part of a moving axis.

> Rotatable connectors allow for easy connection and cable routing. The motor also features an optional magnetic brake for holding static loads. The brake is engaged when the power is off. The servomotor is designed to

run with most popular servo drives. Stober offers support and sizing recommendations to make proper selec-

### For more information:

Stober Drives, Inc. 1781 Downing Dr. Maysville, KY 41056 Phone: (800) 711-3588 www.stober.com

# Ruland

# OFFERS DIVERSE SERVO COUPLING LINE

Manufacturing Co.. Ruland manufactures a diverse line of servo couplings to provide solutions for applications such as stepper and servo systems, linear actuators, ball screws, lead screws, encoders and valve actuation. Industries including medical, printing, packaging, machine tools, linear motion, semiconductor, and solar benefit from having a variety of couplings to choose from. Each application has performance requirements that must be met for the system to function properly. Understanding the different characteristics of each cou-



pling is critical when making a selection. Rigid couplings have high torque capacity, torsional stiffness, and are zero backlash. Ruland straight bore rigid couplings have precision honed bores for proper fit and alignment. Proprietary Nypatch coating is used on hardware to resist vibration and maintain holding power. Two-piece styles feature opposing screws for balancing, reducing vibration at higher speeds. Ruland rigid couplings are available in carbon steel for highest torque capabilities, aluminum for low inertia, and stainless steel for corrosion resistance. Inch, metric, and inch to metric sizes are available with or without keyways from 1/8 in. to 2 in. and 3 mm to 50 mm.

# For more information:

Ruland Manufacturing Co., Inc. 6 Hayes Memorial Drive Marlborough, MA 01752 Phone: (508) 485-1000 www.ruland.com

# Mitsubishi **Electric**

**UPGRADES INVERTER RANGE** 

Mitsubishi Electric has upgraded the FR-F700-EC range of inverters with a number of functions that meet the specific needs of water and pumping applications. The new functions supported by the upgrade include a pre-charge function, built-in PLC functionality, expandable I/O and a unit calculator for PID control. These enhancements increase the capability, flexibility and scope of the FR-F700-EC, bringing improved control and reducing the cost and complexity of drive installations in many applications by eliminating the need for additional components.

A key issue within many pumping applications is water hammer - the pressure surge that can occur when the flow of water starts or stops suddenly. Aside from the noise of water hammer, the vibration can quickly compromise system life and ultimately lead to break down of pipeline systems. The new pre-charge function eliminates the problem of water hammer and extends system life by gradually filling the pipeline. Flexible adjustment options enable the end of the pre-charge cycle to be controlled by feedback level, terminal input or set time. The FR-F700-EC now also includes built-in PLC functionality, suiting the drive to standalone use in pumping and water applications and eliminating the need for a separate PLC for sequence control operations. The built-in PLC offers a program capacity of 4,000 steps, and the PLC function supports 32-bit instructions to handle 32-bit data. The inclusion of two option ports on the drive enables the I/O to be expanded with analogue and digital inputs and outputs, as well as relay outputs. This





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enhanced I/O can be used to provide feedback inputs for the PLC and control outputs to valves and other components. For enhanced security in the field, the program can be password protected.

The new control keypad supports the ability to display PID values in engineering units allowing for easier set up and monitoring. This is especially useful in pump and fan installations. There are actually 32 different unit settings available, for example, Pascal (Pa), liters per minute (L/M), cubic meters per minute (CM/M) or bar.

With these new functions Mitsubishi Electric has already addressed a number of applications within the pumping and water industry, for example an irrigation system where there were several pipelines of different heights and lengths, but only a single pump and pressure sensor. The built-in PLC function enabled six different PID set points to be stored, and then simply selected by a switch on the cabinet door, providing a simple solution in an application that might once have required substantial inverter and PLC knowhow.

### For more information:

Mitsubishi Electric 5900 A Katella Avenue Cypress, CA 90630 Phone: (714) 220-2500

www.mitusbishielectric-usa.com

# **Automation Direct**

# RELEASES SURESTEP DUAL-SHAFT MOTORS

AutomationDirect has expanded the line of SureStep motion control products. Stepping motors in standard NEMA sizes (17, 23 & 34) now include dual-shaft, bi-polar models with output torques ranging from 61 oz-in. to 1288 oz-in. The motors feature front and rear shafts to allow installation of an encoder, hand crank or a second load



onto a motor; a pigtail cable with locking connector allows for easy hook-up. The motors travel 1.8 degrees per step, providing 200 steps per revolution. Backed with a one-year warranty, the stepping motors are CE- and RoHS-compliant and prices start at \$22. The SureStep motors can be controlled by SureStep microstepping drives, programmed with *SureStep Pro* software.

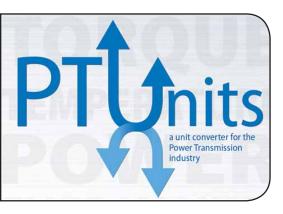
## For more information:

AutomationDirect 3505 Hutchinson Road Cumming, GA 30040 Phone: (770) 889-2858 www.automationdirect.com

# **Sumitomo**

## INTRODUCES MOBILE APPLICATION

Sumitomo Machinery Corporation of America (SMA), U.S. headquarters for Sumitomo Drive Technologies, introduces PT Units, a new Power Transmission Industry mobile application for the iPhone, iPad and iPod Touch. PT Units offers three main functions: converting units, contacting Sumitomo Drive Technologies representatives



and connecting to Sumitomo's web resources. The unit converter quickly and accurately converts between commonly used units of power, torque, force, temperature, fluid volume, mass and length. Additional options available in this function include copying the resulting conversion text and pasting it into other applications, and setting the default units upon launching PT Units. The contact function enables users to locate a Sumitomo Drive Technologies' sales representative by navigating to find their location, or using their device's built in Current Location feature to obtain the representative's contact information. With a data network connection, this information is available for USA, Canada, Mexico, Central America, Caribbean Islands, South America and Japan. This function also enables iPhone users to contact a Customer Service representative via phone or email, and iPod Touch and iPad users via E-mail. The website function allows users with a data network connection to navigate through Sumitomo Drive Technologies' website for product information, industry-

specific information, and white papers. They may also use the provided links to visit the company's Facebook, Twitter and YouTube pages. Designed to assist the power transmission and controls industry, PT Units is available in English, Spanish, Portuguese, French and Japanese.

## For more information:

Sumitomo Machinery Corp. 4200 Holland Blvd. Chesapeake, VA 23323 Phone: (757) 485-8218 www.smcyclo.com



# Steinmeyer, Inc. RELEASES HIGH PRECISION MICRO STAGE

Steinmeyer, Inc. announced a new high precision micro stage, the MT 196LM series. Available in two travel options, of either 100 mm or 200 mm. the MT196-100-2LM and the MT196-200-2LM is suitable for applications in the semiconductor metrology, biomedical, miniature robotics and laser industry. The MT196LM has a footprint of 110 mm × 196 mm, height of 45 mm and, depending on which stage you choose, weighs 4.1 or 4.7 kgs. Manufactured from high strength anodized aluminum, this series of table offers a positional accuracy of 2 µm (micrometer), straightness/flatness runout of  $\pm 5 \,\mu m$  for 100 mm of travel and  $\pm 10 \,\mu m$ for 200 mm of travel with repeatability of ±0.2 μm. Features include: preloaded cross roller bearings, fixed stops, incremental linear encoder with 0.1 µm resolution and a linear piezo motor drive. This product can be provided as a XY stage without any adapter plate. Ultra high vacuum, clean room or nonmagnetic preparation is available on request.



# For more information:

Steinmeyer, Inc. 56 Middlesex Turnpike, Ste. 200 Burlington, MA 01803 Phone: (781) 273-6220 www.steinmeyer.com





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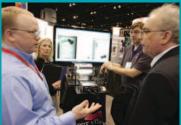
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# The Fundamentals of Specifying and **Selecting Gear Drives**

By Adam Tietyen and Jason Quackenbush (Reprinted with permission from CPSA Journal)

# Introduction

Gear drives deliver power to industrial equipment such as bulk material conveyors, mixers, pumps and paper mills. The reliability that translates into greater uptime and profitability begins by specifying and selecting the proper drives for these critical applications. Many variables-such as service factor, gear drive rating, thermal capacity, speed variation and drive ratio-must be considered when sizing and selecting a gear drive. In addition, specific drive features may provide value-added benefits such as cooler operation or ease of serviceability that help reduce total cost of ownership over the life of the drive—a win for any organization. Here are several major areas of importance to consider when selecting a gear drive.

# **Service Factor**

The service factor (SF), a variable that combines external load dynamics, reliability and life, is used to calculate equivalent horsepower. Application and service duty play an intricate role in determining the proper service factor. Acceptable values of SF are determined by field experience. The American National Standards Institute (ANSI)/American Gear Manufacturers Association (AGMA) Standard 6013-A06 (Metric 6113-A06) for enclosed speed reducers publishes a listing of applications with their recommended service factors.

Once an SF is chosen, the factor is multiplied by the motor nameplate power to establish the size of drive required by the equipment to be driven. A higher SF—or larger gear drive size should be selected when peak running loads are substantially greater than normal operating loads.

Gear drives that are supplied in combination with electric motors may be designated with a service class number such as I, II or III, rather

than a numerical SF. Classes I, II or III are equivalent to SF values of 1.0, 1.41 or 2.0. Service class and service factor are used interchangeably; however, numerical designations are preferred because service class does not accommodate intermediate SF values.

Note that published service factors are only the minimum recommended for a given application. Applications involving unusual or severe loading, or those requiring a higher degree of dependability, should be reviewed with the drive manufacturer. Typical values of SF will not accommodate systems that have serious, critical vibrations or repetitive shock loading. The system designer must identify vibratory or shock loading prior to gear drive selection. These conditions will require changes to be made in the inertia or spring constants of the drive system.

# **Gear Drive Rating**

Published ratings of a gear drive are determined by the mechanical load-carrying capacity of gear tooth elements, rotating shafts and bearings.

For example, the ANSI/AGMA Standard 6013-A06 establishes standards for industrial enclosed gear drives.

The horsepower rating of a gear tooth is less than or equal to the

durability (pitting resistance) of the surface, or strength (bending fatigue) rating, as determined by established AGMA criteria. As the SF is increased, the relationship between gear life (based on pitting resistance) and load is proportional to the increase in SF raised to the 8.78th power. For ex-

DECEMBER 2012

ample, if SF is increased by 30 percent, the gear tooth life will increase 10 times.

Shafts support the gear tooth elements that transmit torque from the motor to the driven machine and also distribute the radial loads to the bearings. While shafts are designed for carrying torsional and bending stresses, they also minimize deflection by maintaining uniform contact across the gear face.

Roller bearings are selected according to bearing manufacturers' recommendations. Bearing life is defined as the number of hours of operation at a constant speed before the first evidence of fatigue develops on either the raceway or rolling elements.

# **Determining Thermal Capacity**

Checking the thermal capacity of a gear drive is extremely important to ensure desired drive performance. Manufacturers' catalogs list thermal horsepower ratings based on a continuous duty cycle at an ambient temperature of 68°F (20°C) and an altitude of up to 2,460 feet above sea level. For other conditions, the thermal horsepower rating must be multiplied by factors provided by the manufacturer for the specific drive under consideration.

The maximum acceptable temperature for an oil sump is 200°F (93°C), according to AGMA standards. However, some manufacturers recommend lower temperatures to increase service life of the lubricant and extend operating life. These temperatures can be achieved with design features that improve cooling, as well as with auxiliary cooling methods.

Thermal capacity can limit selection of a drive if it is less than the nameplate rating of the motor—unless auxiliary



cooling is provided. SF is not involved since heat dissipation is based upon average power consumed—not peak loads.

Gear drives are designed with a variety of internal features to minimize power losses, while yet assuring adequate splash lubrication. These include oil exclusion pans to reduce churning, wipers to collect oil from the rotating gear for distribution to the bearings, and dams to maintain a reservoir at the bearing. Sealing also is critical to dependability. Some manufacturers offer no-leak seals with purge-enabling grease chambers and contact seal designs that eliminate oil leaks while keeping dirt out.

If a gear drive generates heat faster than it can be dissipated, loss of operating life or severe damage can occur. This may take the form of surface distress on the gear teeth or hardening of the oil seals, resulting in leakage. Reducing operating temperatures will increase the oil film thickness at the gear teeth and bearings, thus increasing the life of the equipment.

Heat is generated by a gear drive through frictional loss. The gear lubricant is the carrier of this heat, which is then distributed to the housing and conducted to the outside surface, where it is dissipated. Housing design and configuration can improve heat dissipation.

If the thermal capacity of the gear drive is greater than the motor nameplate rating, and the ambient temperature is below 100°F (38°C), the operating sump temperature should remain below 93°C (200°F). If, on the other hand, the drive is in a confined area and is coated with dirt or waste material, a high probability of distress and a corresponding shorter operating life should be expected.

# **Effect of Speed Variations**

Variable speed applications fall into two load categories: constant torque or constant horsepower. Constant torque occurs when load demand varies proportionally with a change in speed. Gear drives are basically constant torque machines requiring no selection modifications. For a constant horsepower application (load demand is constant regardless of speed) the gear drive must be selected for the slowest speed at which the motor will deliver its rated horsepower capacity. This also applies when a mechanical, electrical or hydraulic speed reduction device is used between a gear drive and a constant-speed AC motor. Variable or multi-speed applications also require special considerations to provide adequate splash lubrication at the slowest speed, but without excessive heating or churning at the higher speed.

Manufacturers' catalogs list input speeds for the high-speed shaft of each type of drive. These generally are based on standard motor speeds. Any input speeds above these limits should be discussed with the manufacturer, as they may exceed the design capabilities of the drive.

# **Finding the Ratio**

To arrive at the specific gear ratio required, divide the motor full-load speed by the revolutions per minute (rpm) of the driven equipment. Exact ratios are determined by dividing the actual number of gear teeth by the mating pinion teeth—both of which are whole numbers. Deviation between AGMA nominal and exact ratios are ±3 percent for a single-reduction gear drive, and ±4 percent for a double-reduction. For applications with variable frequency drives, exact gear ratios become less important. In such cases it is best to select a manufacturer's standard ratios. These will provide lower costs and quicker delivery, with ready availability of off-the-shelf stock spare parts.

# Choosing the Right Size

Manufacturers' catalogs provide input speed, ratio and horsepower rating for use in determining the size of the drive. Other factors that should be considered include: type of unit; initial cost vs. cost of maintenance (total cost of ownership); useful operating life; and spare parts if a marginal selection is made. For example, a 30 percent increase in the initial cost of specifying a gear drive that is one frame size larger could easily represent a 240 percent greater bearing life and 10 times greater gear tooth life. One additional consideration is ease of serviceability. Some drives have a horizontal split

housing that makes them easier to disassemble and reassemble for maintenance of bearings and gearing.

Gear drives are available in a variety of sizes, with various shaft configurations to meet your space requirement. The most popular are parallel-shaft, concentric, and right-angle, with lowspeed shaft either horizontal or vertical to the input shaft centerline. Some drives are available with special features such as backstops, which prevent reverse rotation. The manufacturer's selection procedure that applies to these features should be followed.

Under normal circumstances, reliability is evaluated as part of the SF, which accounts for the effect of the normal statistical distribution of failures found in material testing. Gear teeth designed to AGMA standards are based upon a statistical probability of less than one failure in 100. Most designers recognize that using a higherthan-minimum SF is cheap insurance compared to the costly downtime that results when a process is interrupted due to the failure of a single component. Because drive designs may vary considerably, past experience can only be a guide in determining the proper service factor for a new drive, and the manufacturer's recommendations should be followed.

Maintaining the proper level of oil in the sump, or a steady supply of cool, filtered lubricant, is basic to achieving long service life. To further increase thermal capacity, a shaft-driven fan can be mounted on the drive. This increases air flow along the exterior of the housing to improve heat dissipation. Cool operation also can be achieved through housing designs that improve this dissipation and ensure optimum bearing lubrication. Some manufacturers also offer optional cooling systems to control oil temperatures in the most extreme conditions.

Factors that can affect performance and wear, such as operation in an elevated temperature, can be managed with a consistent, preventive maintenance program followed by immediate corrective action. Manufacturers offer various condition monitoring packages to monitor bearing temperatures, vibration and other measurements, as well as convenient oil sampling ports that allow for lubrication analysis.

For specific details and rating information when researching a gear drive, always refer to the manufacturer's catalogs and technical support advisors to ensure that the drive you select will provide the optimum reliability, ease of service and uptime-with the lowest total cost of ownership. PTE

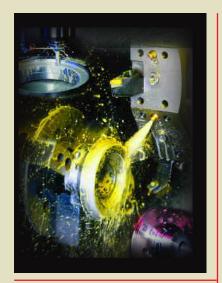
Adam Tietyen, director engineering-product commercialization at Rexnord, has more than 20 years of gear drive design, application and drive system experience. Tietyen is seasoned in gear and coupling applications engineering, with specialization in bulk material handling solutions. Recently he led new gear product engineering and commercialization activities for Rexnord, and currently leads the Rexnord mill products engineering team. Tietyen is a member of the American Gear Manufactures Association (AGMA), the Society for Mining, Metallurgy, and Exploration (SME), and the Conveyor Equipment Manufacturers Association (CEMA).

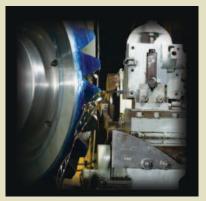
Jason Quackenbush, marketing manager-engineered drives at Rexnord, has 10 years of power transmission sales, marketing and system application experience. Jason's responsibilities have tied to Rexnord and Falk-branded



gear with coupling applications specializing in bulk material handling solutions. Recently, he headed the commercialization activities for the launch of Rexnord's Falk V-Class product line. Quackenbush is a member of the SME.

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# **Designing Drive Systems for Low-Web-Speed Applications**

William B. Gilbert, Siemens Industry, Inc.

This paper will look at the solutions that current drive and motor technology can offer in not only improving tension control but also solving several other issues that are inherent to systems with high ratio gearing.

# **Design Considerations**

Tension control modes. Center-driven winders can be operated in one of three modes of tension control:

- 1. Indirect torque control
- 2. Torque-limiting control
- 3. Speed set-point correction control

Indirect tension control is technically the simplest, but least accurate of the modes. Indirect control does not make use of a tension feedback sensor. The tension control is open-loop, directly based on the tension set-point factored by a measured or calculated diameter. Inertia and friction compensation can be a control feature of this mode.

*Torque-limiting tension control* is closed-loop, based on the tension set-point reference, factored by the actual diameter and compensated by the actual tension error through a PI (tension) control loop as a rotational force. Inertia and friction compensation are normally a control feature of this mode.

Speed set-point correction tension control is closed-loop, based on the actual web speed reference, factored by the actual diameter and compensated by the transformed tension error through a PI (tension) control loop as a speed setpoint addition. Inertia and friction compensation can be a control feature of this mode.

Determining tension control mode. The selection of the winder tension control mode can be influenced by several factors, including machine specifications or design, type of tension sensor used, if any; but normally, the major determining factor will be the compliance of the web material being transported.

The modes of torque control are commonly adapted when the web material has a very low compliance or is "non-extensible;" e.g.-heavy paper, steel, aluminum or other metals. With a non-compliant web the increased system gain of

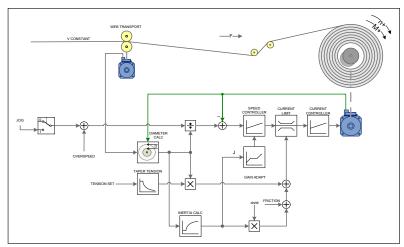


Figure 1 Indirect torque control.

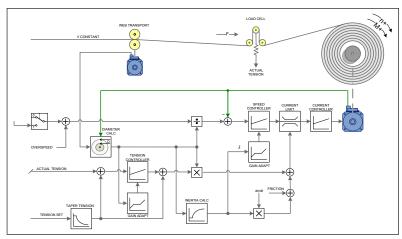


Figure 2 Torque-limiting control (with load cell sensing).

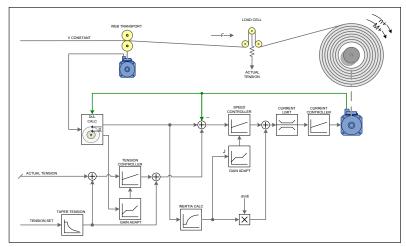


Figure 3 Speed set-point correction control (with load cell sensing).

a speed-controlled system will make the system tend towards instability and much more complex to optimize tuning. The current or torque-regulated modes of control tend to be more stable over a wider range of conditions. When implementing the torque modes consider torque limiting with tension feedback if accuracy is important.

The mode of tension regulation via speed control is ideally implemented when the web is highly compliant or "extensible." In this mode, the added system gain from additional control loop (speed controller) and transformation from force (load cell) to speed (speed loop) to torque (current loop) is a help in meeting the additional system demands.

**Drive-sizing.** In the engineering and design of web-handling drive systems the traditional practice is to optimize the drive and motor sizes as close as possible to the web power requirement. This is accomplished by selecting a mechanical gear ratio that will enable the motor to run as close as possible to its base speed in a web-transporting-driven section (non-winder), and well into the constant power range for center-driven wind or unwind (when an induction motor is used).

The optimum gear ratio is determined by:

• Optimum motor speed rpm/maximum load speed rpm

For a driven section with a fixed diameter roll, the power requirement is determined by the maximum torque requirement at maximum speed. The power requirements for a fixed-diameter transporting roll (sectional drive/pull roll) are from the following:

maximum torque (lbf-in)=(driven roll diameter [in.] /2)\*
maximum web tension [lb.]/(gear ratio\*gearing
efficiency)

maximum speed (rpm) = maximum web speed fpm/ $(\prod^* driven roll diameter [in.])/12)^* gear ratio$ 

The work done by center-driven winds or unwinds is constant power. The torque and speed requirements change throughout the building of the roll. Torque is highest at full roll, with speed the lowest. At the core or smallest diameter, speed is highest and torque is lowest. We can consider the following as the main sizing criteria for a center-driven unwind or rewind:

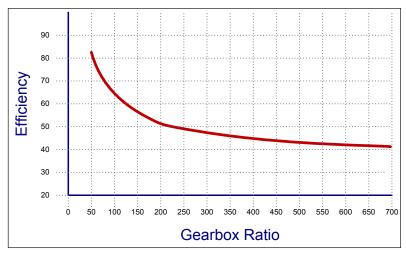


Figure 4 Typical multistage high-ratio gearbox efficiency.

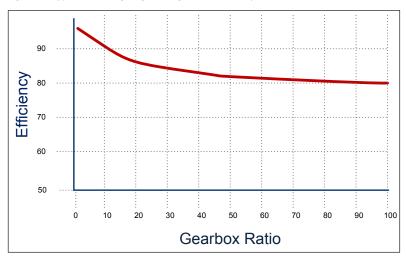


Figure 5 Typical planetary gearbox efficiency.

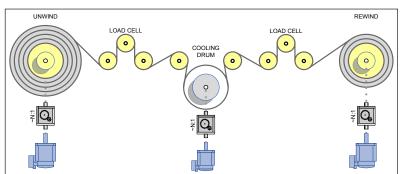


Figure 6 Example: machine configuration.

Example Machine Specifications

W	/EB TENSION		
Min.	1.00	Pli	
Max.	10.00	Pli	

MATERIAL / SPINDLE			
6.75	in.		
20.00	in.		
	6.75		

LINE SPEED			
Min.	0.25	Fpm	
Max	3.00	Fpm	
Jog	12.00	Fpm	

COOLING ROLL			
Dia.	42.0	in.	
Weight	2000.0	lb.	

WEB WIDTH				
Min.	6.00	in.		
Max.	14.00	in.		



maximum torque at full roll (lbfin)=(full roll diameter [in]/2)\* maximum web tension (lb)/(gear ratio\*gearing efficiency)

maximum speed at core (rpm) = maximum web speed (fpm)/( $\prod$ \* core diameter [in])/12)\* gear ratio

Gearbox efficiency. The gearbox selection will determine the efficiency factor component of the torque calculations. Gearbox efficiency is simply the ratio of the output power (power transmitted through the gearbox as usable work) to the input power. As no mechanical device is 100% efficient, this numeric value of efficiency will always be less than one. If a speed reducer were 100%—efficient, all torque being applied to the input shaft would be applied to the output shaft.

gearbox efficiency = (actual output torque/ theoretical output torque )\*100

Typical gearing options are planetary, helical, worm and pulley/timing belt. Generally, planetary gearboxes are limited to 100:1 ratio, with about a maximum ratio of about ~ 8:1 per stage (although there are exceptions to this rule). Efficiencies for planetary gearing can be considered at ~ 90-95% per

For gear ratios over 100:1 the options are typically multistage worm, helical or combination gearboxes (Figs. 4 and 5).

Reference machine example. Consider a machine with: three driven sections; an unwind; a cooling drum as the master and web transport; and a winder. The cooling drum is the system master and is responsible for transporting the web. The unwind and wind spindles are tension-controlled with tension feedback from load cell transducers. The web material being transported is a stainless steel foil. Since the web is non-extendable the mode of tension control for the spindles will be configured as direct torque control.

Power requirements or web hp from the above specifications would be analyzed in the following manner:

> $\max \text{ web hp} = (10 \text{ pli} * 14 \text{ in}) * 12.00$ fpm/33,000 = 0.1508 hp

Considering the very low power requirements of this system, and that industry tends to use synchronous servo motors in the drive systems when pow-

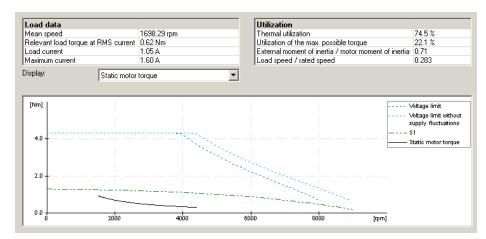


Figure 7 Motor selection/load requirements.

er requirements are at fractional hp and below, we will consider synchronous servo motors for each axis. This type of motor/drive system is common industry practice. Servo motors in this size range will typically have a rated or maximum speed of 4,500 rpm to 6,000 rpm.

Instead of considering power as the sizing criteria, the following sizing examples will select motors based on the criteria of maximum torque requirements at the full roll maximum tension and the maximum speed requirement at maximum speed at core. Since the master (cooling drum) will be speedregulated, as well as the system lead section, the following exercises concentrate only on the unwind and rewind spindles.

# System Design: Unwind/Rewind

# Step 1. Determine the spindle gear ratios (for a power optimized system).

From the maxrpm at the load and the motor base speed, we can determine an optimum gear ratio for a power-optimized system as:

> maximum rpm@core = maximum  $fpm/(\prod * [Core Dia. "/12]) = 12.00/$  $(\prod * [6.75"/12]) = 6.79 \text{ rpm}$

Considering a 4,500 rpm motor, we find an optimized gear ratio as:

4,500 rpm/6.79 rpm = 662.73:1.

For this example we will consider a gearbox ratio of 650:1; this ratio will set the speed at the motor:

maximum motor speed at core (rpm) = maximum web speed/( $[\Pi * core$ diameter»])/12)\* gear ratio fpm/

([[1\*6.75])/12)\*650.00=4,413.90 rpm

minimum motor speed at full roll (rpm) = maximum web speed/( $[\Pi * core]$ diameter»])/12)\*gear ratio 0.100 fpm/ ( $[\prod *20*)/12$ )\*650.00=31.04 rpm

Choices for gearboxes in the range of 650:1 are limited and require selection of a multi-stage gearbox to achieve a ratio of that magnitude. We can consider that the typical efficiency of a multi-stage gearbox with a ratio of 650:1 will be in the area of ~ 33 percent.

# Step 2. Determine the spindle torque requirements.

### maximum torque at core

(lbf-in) = (core diameter/2)\* (maximum web tension/(gear ratio \* gear efficiency); (6.75"/2)\*(140 lb/(650\*0.33)) = 2.20 lbf-in(Note: a system with 90% efficiency would require .807 lbf-in at core)

# Max torque at full roll (lbf-in) = ((full roll diameter/2)\* (maximum web tension/(gear ratio\*gear efficiency)); ((20"/2)\*(140 lb/(650\* $0.33) = 6.53 \, \text{lbf-in}$

(Note: a system with 90% efficiency would require 2.39 lbf-in.)

With these load criteria we can consider a synchronous motor with the minimum of 2.20 lbf-in of torque at the maximum speed at core and 6.53 lbf-in of torque at minimum speed @ full roll. Based on the data, we select a standard motor rated for (1.3 Nm) 11.5 lbf-in at 6,000 rpm (Fig. 7).

# **Issues with High-Ratio Gearing**

**Isolation:** friction losses. The gearbox-related friction losses in efficiency, in effect, isolate the motor from the load. We can see the result of that in how the losses in the high-ratio, multistage gearbox have increased the mo-



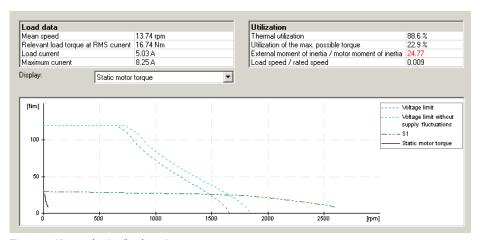


Figure 8 Motor selection/load requirements.

tor torque requirements. It has in fact tripled both the motor and drive size from ~ 2.15 lbf-in to 6.53 lbf-in.

Active torque control component to friction losses. The ratio of the active torque control component to the friction losses should be considered in the design process. Consider that in closed-loop tension control modes only a small component of the tension control signal is active, or supplied, by the tension controller. The majority of the tension set-point is provided from the set-point modified by the actual diameter. Normally we can consider the active portion of the tension component signal at about 5% of the tension torque component. Because the friction losses are not static and will, with time, at a constant speed, also vary with speed and load, the tension control system has to work through the dynamic peaks and valleys of the losses.

The torque required to produce maximum tension without considering loses is 2.15lbf-in. This computes to an active tension control component of 0.05\* max tension control requirement = .05 \* 2.15 in lb = 0.1075 lbf-in.

With friction losses of (6.53 lbf-in -2.15 lbf-in = 4.38 lbf-in) 4.38 lbf-in, we find that the output related to the losses is over 40 times the magnitude of the active tension control component output.  $(4.38 \, \text{lbf-in}/0.1075 \, \text{lbf-in}) = 40.74$ 

For effective tension control in the direct-torque-control mode, the active tension control torque signal should be at least equal or greater to the torque required to overcome the gearbox losses.

Torque ripple-induced tension error. Another concern for effective tension control in the torque-regulated modes is the tension error that can be caused from the motor's inherent torque ripple when factored through the gearbox ratio. Synchronous servo motors can have a typical torque ripple from  $\sim 2.5\%$  to < 1% of M0, or the rated motor torque. In this example the motor selected has a rated torque of 11.5 lbf-in. Considering a torque ripple of 2.5%, the ripple at the motor shaft will be  $\sim .025 * 11.5 lbf-in = .2875 lbf-in$ .

This relates to 650/1\*.02875 lbfin=186.875 lbf-in on the output of the gearbox and 186.875 lbf-in/10 in. (full roll radius)=18.687lb of open=loop tension disturbance on the web at full roll.

Consider also how an oversized motor will add to the open-loop tension error induced by the motor. Additionally, external web tension disturbances will manifest through the system in the same manner.

Back-driven efficiency. High ratio gearing can have a much worse efficiency from the load side in comparison to the input that in effect isolates load changes from output shaft significantly.

**Backlash and compliance.** Any lost motion between motor and load, be it backlash or compliance, will have negative effects on the control of the load. Compliance can cause mechanical resonance that reduces servo response and renders the system unstable and difficult to tune. Torsional compliance acts as a spring and also causes resonances. The larger the shaft diameter the stiffer or lower compliance it will have. The more mechanical sections, meaning couplings, gearbox stages, etc. in the system, the more compliance and backlash present.

**Dynamic performance.** There are always disturbances in a system; they can come from torque ripple, out-ofround rolls, tuning, etc. It is possible for a system that is geared to match the lowest web speed to not have enough dynamic response to compensate for the natural disturbance.

Excess output torque from motor over-sizing. As ratios increase, any additional torque in the selected motor size from optimal can raise the issue of too much output torque at the output of the gearbox. The outcome can be machine damage with web jams or web breaks. (In this example the motor torque requirement was 6.53 lbf-in and the selected motor was 10.5 lbf-in).

### **An Alternative Solution**

Utilizing the lowest possible gearbox ratios, or, if practical, direct-driven motors can help eliminate the issues of load isolation through friction losses, reduce the losses to active tension control component, and reduce torque magnification.

Recommendations for gearing, when required, would be to consider an inline single-stage planetary gearbox or timing belt. When considering a timing belt the limiting factor will be the distance between pulley centers.

Table 1 Encoder resolution: minimum speed regulation			
Encoder Type	Minimum speed (Synchronous Motor)		
Resolver (16 Bit)	20.000	RPM	
1024 Pulse HTL (Square Wave)	10.000	RPM	
2048 Pulse HTL (Square Wave)	5.000	RPM	
4096 Pulse HTL (Square Wave)	2.500	RPM	
2048 Pulse Sin/Cos Encoder (22 bit)	0.250	RPM	
8192 Pulse Sin/Cos Encoder (24 bit)	0.125	RPM	



In most cases ratios in the range of 4:1 or less will be the maximum for timing belt gearing arrangements.

High-resolution motor feedback encoders are the key to improving the low-speed regulation of drive systems. With the introduction of the sin/cos optical encoders feedback resolution has been increased from thousands of counts-per-motor-revolution to ~ 4 million-counts-per-revolution for a 22-bit encoder to 16 million-countsper-revolution for 24 bit encoders. The higher the resolution of the motor feedback sensor, the lower the speed that the drive system can effectively regulate. Table 1 offers a rule of thumb for different encoder technologies and minimum regulated speed.

Considering the same reference specifications on a drive system with a low-ratio, single- stage gearbox with a ratio of 6:1, we determine the following

maximum speed at core

 $(\mathbf{rpm}) = \text{maximum web speed} / ((\prod^* \text{core}))$ diameter")/12)\* gear ratio 12.00 fpm/  $((\prod *6.75")/12)*6.00=40.74 \text{ rpm}$ 

maximum speed at full roll

 $(\mathbf{rpm}) = \max_{\mathbf{m}} \mathbf{m} \mathbf{m} \mathbf{m}$  web speed /  $((\prod^* \mathbf{full})$ roll diameter")/12)\* gear ratio 12.00 fpm /  $((\prod *20")/12)*6.00=13.75 \text{ rpm}$ 

minimum speed at full roll

**(rpm)** = minimum web speed/(( $\prod$ \*full roll diameter)/12)\*gear ratio 0.10 fpm /  $((\prod *20'')/12)*6.00 = .29 \text{ rpm}$ 

maximum torque at core (lbf-in) = ((core diameter/2)\* (maximum web tension/(gear ratio\*gear efficiency)) ((6.75"/2)\*(140lb/(6\*0.96) = 82.03 lbf-in

maximum torque at full roll (lbf-in) = ((full roll diameter/2)\* (maximum web tension/ (gear ratio \*gear efficiency)) ((20" / 2)\*(140 lb/(100\* 0.79)) = 243.06 lbf-in

With these load criteria we can consider a synchronous motor with the minimum of 82.03 lbf-in of torque at the maximum speed at core (40.74 rpm) and 243.06lbf-in of torque at minimum speed @ full roll (0.29 rpm).

Based on the data, we select a standard motor rated for (28 Nm) 247.82 lbf-in of stall torque and (22.5 Nm) 199.15 lbf-in at 2,000 rpm (Fig. 8).

The torque required to produce maximum tension without considering loses is 233.33 lbf-in, giving an active tension control component of 0.05\*maximum tension control requirement = .05\*233.33in lb = 11.67 lbf-in.

With friction losses of (243.06 lbf-in -233.33 lbf-in=9.73 lbf-in), we find that the losses in this example are less than the magnitude of the active tension control component.

A motor is selected with a rated speed torque of (28 Nm) 247.82 lbf-in. Considering a torque ripple of 2.5% we find the ripple at the motor shaft to be  $\sim .025 * 247.82 lbf-in = 6.19 lbf-in.$ 

relates to 6/1\*6.19lbfin=37.17lbf-in on the output of the gearbox, and 37.17/10 in (full roll radius)=3.72lb. of open-loop tension disturbance on the web at full roll.

Selecting low-ratio gearing with increased motor size offers a drive system with a higher level of inherent accuracy and control dynamics. We have gone from a system that had a loss to active tension control component ratio of > 40:1, to a system with a ratio of less than one. And, a system that inherently imparted disturbances of 18.687 lb. of open-loop tension disturbance on the web at full roll to a system that offers 372lb. of open-loop tension disturbance on the web, five times less open loop tension disturbance.

### Conclusions

Considering the lowest practical gear ratio or, if practical, direct-driven motors for web handling at very low-webspeeds, can enhance machine tension control performance significantly. This is accomplished by eliminating the issues of load isolation through friction losses, reducing the losses to active tension control component ratio, and reducing the torque ripple magnifica-

In systems with lower-to-moderate power requirements, the increased cost of the larger drive system in most cases will be offset by the reduced costs of the system gearing.

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William Gilbert is a consulting application engineer with the Motion Control Business of Siemens Industry, Inc. He is responsible for the company's converting industry focus and business development for the U.S. market. Gilbert has over



25 years of experience in motion control and web handling-related industries.

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# **HE QUESTION**

# How can I calculate the diameter of the inner race in bearings?

The inner race diameter for a rolling element bearing is a design parameter, and it is chosen by the bearing producer based on various criteria such as rolling element distance, number and diameter of rolling elements, and what interference fit is supposed to be used for a given bearing type. Different (manufacturers) have different ways and targets when optimizing bearing performance, and hence there is no common way to calculate the diameter the inner race for a given, existing bearing.

Without knowing the need for the inner race diameter, a potential use of that measure is to calculate the frequencies related to the different contacts between rolling elements and raceways, as well as the rotational frequency of the cage with rolling element set. These basic frequencies are typically used when analyzing vibration measurements of machines as a way to trace bearings that become damaged. Since the calculation of these basic frequencies requires the actual pitch and rolling element diameters—as well as the actual contact angle for a given bearing-the internet homepages of the larger bearing producers usually provide help. One example is the SKF bearing frequencies calculator, available online or as freeware via *iTunes*.

The frequencies delivered by such "bearing frequency calculators" are based on basic formulae where the bearing-specific pitch and rolling element diameters are used. By tradition, the four frequencies are often called: "BPFO" (ball pass frequency-outer ring); "BPFI" (ball pass frequency-inner ring); "BSF" (ball spin frequency), referring to the ball. The formulae are, however, valid for roller bearings as well, so the term rolling element diameter is more (precise). The fourth fre-

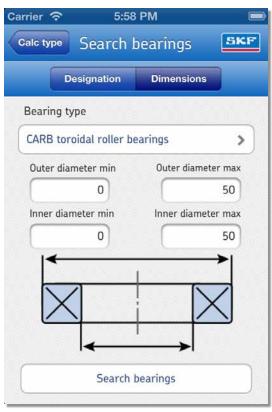
quency derived from the same data is the "FTF" (fundamental train frequency), which is the rotational frequency for the cage with rolling elements.

With a given and disassembled bearing available, the rolling element and the inner race diameters are, typically, relatively easy to measure; the pitch diameter is then the sum of the inner race diameter and one rolling element diameter. If the bearing has a contact angle, however, this is more difficult to measure—in particular for bearings with curved raceways; e.g.-angular contact ball bearings.

Regards, **Hans Wendeberg**  Hans Wendeberg of SKF Sweden focuses on product development and customer-specific application engineering for a number of industries, particularly those involving custom, high-power-density transmissions. He is currently manager of application development, responsible for the development of performance-related application rules for self-aligning bearings, training and troubleshooting.

### For more information:

Hans Wendeberg SKF Sweden SE-41550 Gothenburg, Sweden Phone: +(46) 31-3371942 Cell: +(46) 705-850881 Hans.Wendeberg@skf.com



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# **Effective Management Can Reduce Energy Costs Millwide**

By Keith Masters, ABB business manager, pulp and paper systems

# Introduction

It's as true in pulp and paper as it is in many other industries: the continued rise in energy prices has put a squeeze on margin and profits. Papermakers know that to maintain margin, they must effectively manage their energy costs. But many mills struggle to

Margin **Energy Cost** 

Figure 1 Energy costs impact margin.

find the best ways to reduce what they pay for energy.

Mills can successfully manage energy costs by avoiding price peaks and penalty charges. Other tactics include: using optimal resources to supply electric power; raising plant-wide awareness of energy consumption and its cost; real-time monitoring for early detection of poor performance against set targets; managing electricity purchase prices with accurate consumption plans; and participating in the demand response market.

Software optimizes energy use. An energy management system, such as ABB's Energy Manager, is a good investment for tracking and cutting plant (mill) energy costs. Plants using Energy Manager typically achieve total energy cost reductions of two to five percent. To qualify a program that works for them, mills should look for software that includes both planning and scheduling tools for optimizing energy use and supply; energy balance management tools to assist in procuring energy at the best available prices; and reporting tools to help monitor energy consumption, costs and efficiency. It's also essential that programs use realtime system data.

Planning tools are essential for pre-

dicting energy consumption and calculating a corresponding energy supply schedule. Software can also balance time-varying energy consumption with supply resources.

Energy Manag*er* monitors power schedules in real-time so that deviations or unexpected events can be quickly detected

and reported, thus helping to minimize their costs. The energy planning module automatically recalculates the demand schedule based on changes in process measurements, production plans or user inputs. If an imbalance between predicted power consumption and planned supply is detected, the deviation may be balanced through additional power trading or automated process control.

The Power (Tie-Line) monitoring module predicts total utility consumption within the current billing period by integrating and extrapolating the flow in the tie-line. If the predicted volume exceeds pre-set or calculated alarm limits, alarms will alert the operator to take action.

The system generates reports that help users quickly analyze energy and use. Performance reports can detail everything from the consumption and cost of utilities per hour/day/month/ year, to benchmarking and analysis of load profile and peak demand.

# **Case History Results**

Mayr-Melnh of the Carton Board Group. In 2001, Mayr-Melnhof Carton Board Group, an l, international producer of recycled carton board, implemented plant-wide energy management systems at seven of their carton board plants in Austria, Germany, the

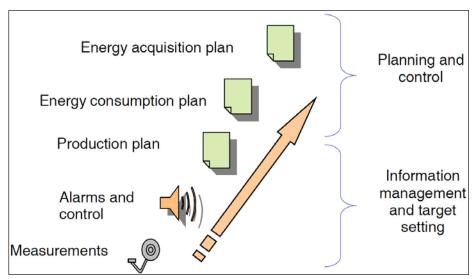


Figure 2 Energy management system functions.

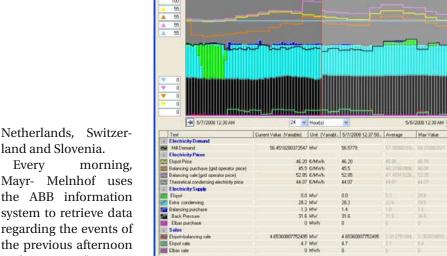


Figure 3 Screen capture example shows how knowing energy demand, prices, supply and sales data can be used to optimize energy resources. This tool is used to balance resources and perform real-time monitoring and

land and Slovenia.

Mayr- Melnhof uses the ABB information and evening. "We use the system to manage energy, water, chemicals, compressed air, production and quality data and statistics," ex-

plains Johan Maier, who is responsible for energy and water management at Mayr-Melnhof. "The Energy Management (software) represents our connection between local processes and offices, and provides a handy instrument for optimizing the process and detecting failures more easily. We are happy with the system and have ordered an upgrade this year in order to obtain further benefits."

**Public Works.** Public Works Government Services Canada (PWGSC) oversees government assets including office buildings and central heating and cooling plants, as well as high-voltage water and sewage distribution systems that vary in size, complexity and age. Its activities include delivering, verifying, planning and reporting on utilities and different grades of fuel for all of these facilities. PWGSC also deals with many different energy suppliers and energy commodities.

PWGSC found that their multiple budgeting, reporting, billing and planning systems could not effectively manage all the required energy and asset management activities. By adding Energy Manager, they could optimize energy costs. The system is capable of collecting real-time data from different energy markets. The Energy Man-

ager suite supports analysis of the cost impact of different combinations of electricity and natural gas purchased from different sources. This will help PWGSC negotiate and purchase different energy commodities directly from suppliers.

The availability of real-time energy data generated at different building complexes allows PWGSC to perform benchmark analysis of the performance of their properties. PWGSC now uses a wide range of reports including energy usage and cost for each building. All of these activities add up to energy savings at PWGSC.

Zellstoff Celgar/Castlegar pulp mill. British Columbia. Canada uses monitoring and reporting features to collect both in-plant energy consumption and the local utility (BC Hydro) data in the real-time format. It is a report-rich system that helps management understand the opportunity cost when they do not sell power to BC Hvdro.

The main goals of the ABB system are to improve the stability and reliability of operations; maximize net revenues from power sales; reduce energy costs; and improve overall coordination of power plant and pulp mill operations. PTE



# **Considering the Mechanical Aspects of ATEX**

By Niilo Nykanen, R+W America

Many engineers and technologists have been aware of electrical ignition sources in hazardous, explosive industrial atmospheres for the last quarter century; this applies to standard design practices both in Europe and North America. During the late 1990s and early 2000s, ATEX 95 Equipment Directive 94/9/EC was implemented in the newly formed European Union to standardize new machine building practices and the maintenance of existing equipment. The ATEX directive is essentially the culmination of best practices utilized in many European nations to avoid accidental ignition of explosive atmospheres during industrial processes. The directive transcends pre-existing national directives and allows for expedited equipment delivery across the EU. ATEX equipment is also becoming a standard design practice across North America. As global trade increases and NEMA manufactures of explosionproof equipment cross paths with IEC manufacturers of ATEX products, parallels have been made to cross-reference items made in the EU and North America for certain applications. This often prompts equipment users to revisit older product design standards in order to help balance the requirements. Shaft couplings provide one example.

For the past 30 years or more, designers have paid due diligence to the electrical aspect of hazardous atmosphere equipment design, but have often ignored the mechanical side. In recent years, the mechanical aspects of ATEX design have increasingly come to light. Not only do electrical power transmission products, but also me-



Type: BKL 150 EEx-2003 EEx cT4/135°C Ser.No.: A 44305 Tech.Ref.No.:2003/003RW

chanical power transmission products need to comply with the ATEX directive. Many electrical engineers and designers forget that both the electrical and mechanical components of the completed assemblies should not be capable of providing an ignition source in a volatile, combustible atmosphere. If an electrical component such as a motor fails and the windings burn up, or the connections melt down, the standard practice for many years has been to isolate these areas with thick material and gasketing.

More recently this consideration has been applied to mechanical parts that transmit power which may fail. Many North American manufacturers have specified that only non-sparking components in mechanical power transmission couplings may be used, such as aluminum or stainless steel. Although both aluminum and stainless steel can produce sparks in the correct conditions (i.e. a high-speed rotating aluminum part hitting an oxidized steel piece at a glancing angle), they are generally much less prone to produce sparks than carbon steels, especially at high speeds. Another design consideration machine builders need to keep in mind when specifying moving components into potentially hazardous atmospheres is how the parts might strike each other if they fail or are installed incorrectly. A simple example is a glancing blow, much like striking a flint against steel in an antiquated attempt to light a fire. Parts that strike each other in a perpendicular



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manner are much less likely to spark in the same manner as a hammer that hits mild steel on an anvil. Eliminating or reducing the potential sparking from mechanical contact or friction (metal to metal or metal to some other type of sparking material) is critical when designing product that may go into an ATEX application. Although this principle is probably a bit newer in the mechanical design world, electrical designers have steered away from anything such as open motor frames and hot surfaces for many years. The bottom line is that any electrical or mechanical device which could be an ignition source for a fire or explosion should not be used in hazardous atmospheres.

When making a coupling selection for a hazardous environment, designers should pay close attention to the possible failure modes and use proper risk assessment principles. Whenever possible, in an explosive atmosphere driving and driven components, couplings, line shafts, etc., should be designed in such a manner that sparking materials cannot deliver glancing blows to each other in a failure mode. At a speed of 4.5 meters-per-second, a 2 kilo-Newton blow can be a very effective ignition source between steel parts. This means that a rotating steel object as small as 100 mm in diameter, moving at 850 or more rpm with a mass

SLE Torque Limiter with clamping hubs and elastomer insert.





R+W EK-ATEX couplings are backlash- free, and the conductive elastomer element is very easily press fit into position (all photos courtesy of R+W).

of 200 or greater grams, could produce a significant ignition source if it happened to crash and stop very quickly:

 $F(N) = 1/2 * m \text{ (kg)} * v (m/s) ^2/s (m),$  $2 kN = 1/2 *.2 kg * 4.5 m/s^2/.001 m$ , 850 rpm = 100 mm DIA @ 4.5 m/s rim speed.

A system designer conducting a failure mode effects analysis (FMEA) must also realize that in some cases a coupling could fail in such a way that the driver and driven hub could lose contact with each other. It is possible that a driven shaft rotating at high speed under its own inertia could produce a static charge. This is due to the fact that most motor and drive line shafts ride in lubricated bearings. Oil and grease do not typically conduct electricity very well. Many electrical transformers are oil filled for this reason. Shafts in electric motors, especially the brush-

> less types, tend to build a static charge for various reasons to include asymmetry in the magnetic circuit of rotating electrical machines. These static charges build up as small areas of high potential around the shaft bearings and periodically discharge. This microcauses

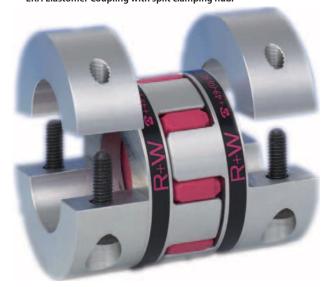
scopic pitting in the bearings and can be a leading cause of bearing failure. Manufacturers often include a grounding brush in ATEX and other NEMA hazardous location motor designs. If a coupling between a driven shaft and motor shaft fails catastrophically and allows the driven shaft to spin freely, arcing could occur in the bearings and air gaps between the remnants of the coupling.

Many mechanical power transmission products already have ATEX certification. As with any other product, just because an industrial power transmission part is certified by an approved body does not necessarily mean that it is the best part for the design of a system. For example, there are many ATEX-certified, flexible diskstyle couplings on the market that are widely used in the petrochemical industry. This is due primarily to the disc coupling having been the original type described in the API (American Petroleum Institute) 671 guidelines for special purpose couplings. There are some specific high-speed compressor applications in this industry with a critical reliance upon specific features of the disc pack coupling. These couplings certainly do offer excellent properties for fatigue resistance, high- speed balance, and prevention of static buildup, due to their all-metal construction. This does not mean that this design is free of all negative properties.

The EKZ Intermediate Spacer is precision molded and wear resistant.

Machine builders must be aware that when using this style of coupling for ATEX applications, it is possible in the event of a disk, hub and/or, spacer failure, that fasteners and broken pieces of disks could impact each other at various angles. In a worst case scenario a piece of the coupling could flail into a guard or other surrounding metal component(s). If the application is high-speed and/or high-inertia, spark(s) could fly in any direction. Fortunately, the designers of these couplings have put years of consideration into special bolting designs and safety catches for spacers which generally work well in failure mode. This design can become quite complex and costly, oftentimes requiring a customer to assemble many components on site. Since this type of coupling is often mistakenly assumed to be the only option for equipment built in accordance with API guidelines, many system designers use it without considering that alternatives, such as approved elastomer jaw couplings, may be better suited to their

EKH Elastomer Coupling with split clamping hub.



actual requirements.

Many ATEXcertified elastomer jaw coupling designs have advanced greatly over the past few decades in terms

of their balance, torque density, ease of installation and reliability over long maintenance intervals. Electrically conductive elements are used in order to eliminate the potential for electrostatic charges to arc from one hub to the next. One advantage that an elastomeric jaw-style coupling has over a disk coupling is that in the event the element fails, it might throw a few pieces of rubber or plastic in the surrounding area (versus metal) which typically would not constitute a significant ignition source. In the case of higher quality machined jaw couplings, very seldom does a whole spider element completely disintegrate at once. The jaws are designed with an inward,

> opening curvature to positively contain most of the large pieces of the elastomeric element in the event of a failure. If the entire element were lost at once, the jaws would impact each other straight on from a very close distance, much like the dowel bolts in a much more complex disk pack coupling. Once the jaws are impacted the motor can continue to turn the load until an operator or maintenance worker recognizes a problem. A jaw coupling



with a failed elastomeric also maintains electrical continuity between the driver and driven hubs. Guarding design in ATEX applications with an elastomeric jaw coupling can be a bit more simplified as well, compared to other couplings. Because there is no metal disk or element that could potentially be thrown in failure mode, the guard can be more suited to simply protect personnel from coming into contact with rotating parts, rather than creating a re-enforced guard to catch pieces of flying metal.

R+W EK-ATEX couplings are backlash-free, and the conductive elastomer element is very easily press fit into position. Due to a proprietary, secondary molding process, the surfaces of the legs of the elastomer element exhibit a very smooth and straight fit with the precision machined curved jaws, resulting in good electrical conductivity versus many other spider couplings on the market. This smooth even fit also means that there is very consistent compression on the entire elastomer when the machine is running. The result is a less likely chance of failure due to uneven compression compared to elastomeric spiders that are simply pulled from their initial molds and installed. The single elastomeric element not only compensates for a bit of angular shaft misalignment, like a single disk-style coupling, but also for axial and lateral/parallel misalignment. Spacer designs facilitate larger amounts of misalignment and offer easy installation over a wide range of distances between shaft ends, which is also typically useful in API-compliant pump package designs. Split clamping hubs ensure a backlash-free frictional connection, addressing keyway wear and/or eliminating keyways completely, and typically require a fraction of the time for installation and removal.

Catastrophic failures due to unforeseen torque overloads do happen in the field. These failures can be induced from resonant vibrations in the final assembly and can be difficult to predict unless a complex array of electronic sensors is in place throughout the machine. One design advantage of the R+W ATEX coupling is that it is also offered with an optional torque limiting feature, certified and approved for

use in explosive atmospheres. This means that in the event of a mechanical overload, the coupling itself actually disengages rather than causing a catastrophic failure. A mechanical ring on the coupling is designed to move slightly in the event of disengagement. This movement can be used to trigger an electrical signal to alert operators to the problem. In many instances, systems are designed so that disengagement will shut a system down so maintenance personnel can repair the cause of the overload before it causes excess damage to equipment.

In conclusion, when designing a mechanical power transmission system for an ATEX environment, one must be very diligent in the proper selection of parts. Just because a part has a certified marking does not necessarily mean it will always be suitable for

application in each of these areas and environments every time. In order to prevent any electro-static discharge, all moving parts should maintain electrical conductivity between each other. All motor and machine frames must be chassis-grounded, with special attention being paid to any fluid flow processes. Possible failure modes must also be considered to minimize the opportunity for sparks to be generated should the unexpected occur. When choosing ATEX parts it should also be noted to find out from a prospective vendor how long they have been producing hazardous location product, when they were certified, and by what agency. Always choose wisely and get multiple opinions from different vendors and agencies when designing your system. **PTE** 

#### For more information:

R+W America 1120 Tower Lane Bensenville, IL 60106 Phone: (888) 479-8728 www.rw-america.com



Niilo Nykanen is employed with R+W America L.P. as an application engineer and quality coordinator. He is a specialist in belt, chain, and, close-coupled drives. Nykanen has continuously worked for ATEX certified



manufacturing companies since the beginning of 2004. He has been designing and building electro-mechanical parts and systems for his entire career, including product destined for oil processing facilities abroad. Nykanen has various collegiate degrees in manufacturing engineering, electro-mechanical technology, HVAC technology, and is a U.S. Army veteran of

# CRUISING WITH CURRIOSITY

PT Components Help Power NASA's Mobile Laboratory

Matthew Jaster, Associate Editor

Since arriving on Mars on August 5, 2012, the Curiosity rover has been methodically checking things off its lengthy two-year to-do list.

This "Cadillac" of Mars rovers—fully loaded with robotic arms, cameras, laser beams and sensors—is currently examining rocks, scooping soil, taking photographs and trying to determine the habitability of the red planet. While these Mars trips aren't exactly breaking news at this point (see Twitter), it doesn't change the fact that scientists, engineers, manufacturers and even technology nerds are still very excited about sending a man-made machine to another planet. This isn't just another been there-done that trip into outer space, we're talking Mars (fourth planet from the sun, second smallest planet in the solar system, location of many a terrible science fiction film).

In order for Curiosity to function properly, the Jet Propulsion Laboratory (JPL) needed PT components that could withstand the harsh environment found on the planet's surface. Companies like Forest City Gear, Kaydon Bearing and Maxon Motors responded by creating parts that will

help make the mobile laboratory's twoyear mission a resounding success.

So what was it like being involved in a space exploration project of this magnitude? Being curious ourselves, we made a couple of phone calls.

# Forest City Gear 2x the Pressure to Succeed

If you've ever visited Forest City Gear (FCG), located in Roscoe, Illinois, owner and operator Fred Young may have asked you to touch a gear in the lobby. Not an unusual request given that the gear shop produces a wide variety of products for military, medical, construction and aerospace projects. But it's not very often that the product in question is heading to another planet.

"I would have people come in and touch the gears and then I'd let them know that their DNA is going to Mars," Young said. "They were all very excited about the idea."

How could you not be?

The gears manufactured at FCG have been utilized in home ice cream machines, basketball hoops in gymnasiums and space stations. After supplying gears for the Spirit

and Opportunity Mars rovers, FCG was older, wiser, and more sophisticated. This was vital when the JPL requested 70+ gears for the Curiosity mission.

"They needed gears for different actuator arms, cameras, x-ray equipment, drilling equipment and lasers," Young said. "JPL was basically turning this vehicle into a mini mobile laboratory to determine the composition of the rocks and the granular structure. Given our experience with the other rovers, I knew our team could handle the request. It was an exciting job."

And one with its own unique set of challenges.

"JPL wanted 100 percent inspection of every dimension, documentation was necessary and all the gears needed to be serialized," Young said. "They tested all the actuators, drilling devices and laser beams under all kinds of strange conditions. There was serious pressure to make sure everything worked properly."

JPL, in fact, sent someone to Roscoe to help with the inspection of the gears since the timetable was so strict. "You basically have a two-week window to launch this thing and if you miss the deadline, you've got to wait around another two years," Young added.

The magnitude of the project didn't really hit home until Young was watching Curiosity arrive on Mars six months after it had left Earth.

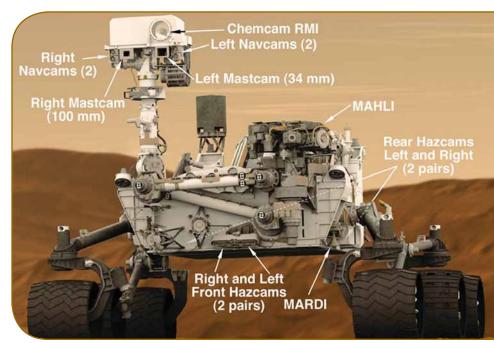
"This thing is going to land on another planet and it damn well better work," he said. To add more pressure, FCG had provided gears for the Sky Crane responsible for lowering the rover to the surface. "We basically had two opportunities to screw up big time if the gears didn't function."

Thankfully, the landing went flawlessly.

While Young jokes that he may be jaded on some of these space projects after participating in more than a few, he's thrilled at the level of excitement found in the FCG staff. Key members like lead gear inspector, Amy Sovina and hobbing set-up technician Kent Blatchford were proud of the work they accomplished. They even shared their stories for a short documentary web series entitled *Our City, Our Story* (www.ourcityourstory.com).

"It gives our staff confidence because it's such a high visibility project," Young adds, "It's exciting, it's challenging and most importantly it's a great learning experience. To imply that we had a major role in this project is a considerable leap of faith, but bottom line, the gears *had* to work and JPL had to select the best ones to make the trip."

Young credits the work done on Spirit and Opportunity as pivotal to the success of the latest Mars mission. "We were told that Spirit and Opportunity were supposed to last six months when, in fact, they lasted six years. The wealth of information



This graphic shows the locations of the cameras on NASA's Curiosity rover (all photos courtesy of NASA).

they get from each mission is vital for planning the next one."

And is FCG ready if JPL calls on them for another mission to Mars?

"We're ready when they are," Young says. "Hopefully everyone at NASA and JPL remembers who we are and that we did a good job for them."

# **Kaydon Bearings** *Meeting Incredibly High Expectations*

Kaydon Bearings, located in Muskegon, Michigan, can't exactly shy away from extreme bearing applications. They've pretty much become the bread and butter of the company's work in the thin section bearing and slewing ring markets.

"We actively seek out the tough challenges such as space applications because they force us to push the envelope and make us a stronger engineering team," said Scott Hansen, vice president manufacturing planning.

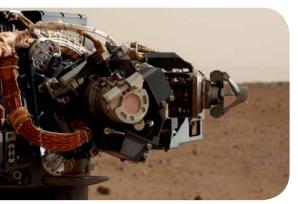
"Kaydon's first space ap-

plication goes back to the 1960s Apollo program. Hamilton Standard had a contract to design a space suit and there were Kaydon Reali-Slim thin section bearings in the joints. The Apollo 15 Lunar rover built by Boeing used Kaydon Reali-Slims for wheel bearings since tapered roller bearings were too heavy."

Additionally, the company has provided bearings for classified government satellite applications, the Hubble Telescope and the International Space Station, rightfully earning its space credibility. After successful trips to Mars on Spirit, Opportunity and the Phoenix Lander, it was not surprising that Kaydon returned to supply bearings for the Curiosity project.

"Kaydon's Bearing Division was called upon to provide bearings for a variety of parts on Curiosity including the robotic arm, the steering actuators for the rover's wheels and in the deployment mechanism for the remote sensing

mast," said Robert Roos, senior product engineer. Since the rover boasted the largest, most advanced scientific payload of any Mars mission yet, it required a bearing capable of handling a multitude of harsh environment



The Mars Hand Lens Imager (MAHLI) is one of the tools on a turret at the end of the rover's

tasks-one like the Reali-Slim thin section bearing.

One pair of duplexed Reali-Slim bearings is in the CHIMRA (Collection and Handling for In-Situ Rock Analysis), one of a number of devices mounted on a turret at the end of the rover's robotic arm. These angular contact bearings with a 3-inch O.D. are a key part of the thwack mechanism that must keep the primary sieve from clogging so that samples can reach the analytical instruments. The screens in the sieves have tiny holes—150 micron and 1 mm—to produce particles of the appropriate size; i.e. like a crushed aspirin. JPL engineers decided early on that thin section bearings were the best way to handle the load in the small space available, and built the design around them.

The other four sets of Kaydon bearings (7-inch O.D., 6-inch bore) support the steering actuators on Curiosity's four corners and relieve some of the load on them. This was critical during the landing. These bearings, like those in the CHIMRA, are angular contact with races and balls of 440C stainless steel and a built-in preload. JPL requested that all be shipped dry, including the phenolic separators, so they could add a space-rated lubricant.

Preparing for the Curiosity project was no different than other bearing applications back on Earth, according to Roos. "We start by looking at size and weight constraints. We try to utilize a standard size if at all possible. Then

> we discuss the various bearing features such as materials, separator or cage type, amount of preload or clearance and lubrication."

> Kaydon then analyzes the loads and speeds to make sure the bearing meets the requirements of the application. "We also take a look at how the bearing fits to the shaft and housing. These can change significantly over the wide temperature range because of differential thermal expansion."

The most unique feature in the bearings used for Curiosity is the lubricant. "A special dry film lubricant was needed because of the extremely cold environment that the bearings need to operate in," Roos said.

Kaydon's engineering team was thrilled when called upon to work on another Mars project.

"I believe the Kaydon team derives a great sense of accomplishment and pride in taking on demanding applications such as space. Really, this is as close to exploration as most of us will ever get and it's really amazing to see the fruits of our work unfold on the surface of another planet," Hansen said.

"These are fun programs to work on," Roos agreed. "It is very rewarding to see something you have designed working exactly as you expected it would. In many applications you never hear back from the customer when everything is working fine. It's nice to actually see the results of your work!"

# **Maxon Motors** The Need for Advanced Encoder **Technology**

While Maxon motors were utilized on Curiosity's little brother, Opportunity, it was Maxon's encoder technology that was needed for the latest mission to Mars. The company realized some exceptions had to be made to participate in the project. The Swiss-based company normally does not sell, share or license its technology. "It's a closely held secret," said Robin Phillips, mmAG research and development. "But for a project of this importance, we made an exception."

"The environmental operating parameters that the IPL needed for the encoders were well outside of the normal range that Maxon works with," said Jeff Randall, sales engineer. "They had to be functional in very cold and very hot environments. Each part had to be "RAD hardened" or screened under tougher and tougher conditions. Many of the electrical components failed during this process. In the end, the parts that were still functional proved that they can survive the tough operating conditions required of them."

Mars applications differ from other encoder applications for several key reasons. "They require operation over



The view of the three left wheels combines two images taken by the rover's Mars Hand Lens Imager.

a very wide temperature range (-130 to 130 degrees Celsius) since they have to survive both Martian nights and a sterilization cycle on Earth," Randall said. "Then there are the vibrations and shock from launch and landing. The biggest difference is that unlike an industrial application, it's not possible to replace a defective part. If something fails in a factory application we can send a replacement, if a motor fails on Mars it causes the loss of a multibillion dollar mission!"

In contrast to the Opportunity and Spirit rovers, Curiosity can travel further distances on its six wheels and run longer without solar energy as a radionuclide battery gives energy for years. The plan is that the rover will explore the immense Gale Crater on Mars for signs of life. This is accomplished with some impressive onboard equipment including a gas chromatograph (to uncover organic compounds) a spectrometer (to analyze rocks) and a twometer-long robotic arm (to collect the rocks).

The Maxon MR Encoder technology is built into the electro mechanic joints of the rover. The magnetic sensors are mounted on the drive shafts and are responsible for controlling the motors. Apart from that, Maxon's development services for the drive systems have also played a part in the 900 kilogram rover being able to carry out its Mars Mission successfully.

"There are 31 brushless motors on Curiosity that have encoder parts from Maxon," Randall said. "These are used for driving and steering the wheels, moving the science arm joints and moving the camera mast."

Looking back now, both Randall and Phillips reflected on the impact the assignment has had on the entire staff and how it will impact Maxon in the

"Maxon likes to take part in these well-known projects. It gives people that work at the factory some pride. There are rover models and displays everywhere at our headquarters in Switzerland. It's nice for the employees to see that their work helps the company support projects like Curiosity," Randall said.

"Applications like this require the latest technology in order to achieve the highest possible power density meaning the maximum possible power out of the smallest volume and the lightest weight," Phillips said. "This is only possible by working closely with other high-tech suppliers so that we have the newest component designs and use the best production tooling for assembly."

# **Science and Progress**

So what is Curiosity up to lately? The Mars rover has recently been digging up samples using its full array of analytical instruments to investigate a drift of sandy soil. While initial buzz had scientists down on Earth extremely excited, the rover has not detected any definitive evidence of Martian organics, according to a NASA press release. With Curiosity only four months in to its two-year mission, there's still plenty of time for breaking news stories.

Overall, NASA says the rover is exceeding expectations with all of its instruments and measurement systems performing well. This is a crowning achievement for Forest City Gear, Kaydon. Maxon and all of the other companies that took part in this historic science experiment.

"You never want to go overboard talking about a project like this. It's hard not to, though, given everything that needs to go right for it to be a success," Young said. "My wife occasionally threatens to send me up to Mars, if I don't pull back a little." PTE

#### For more information:

Forest City Gear 11715 Máin St. Roscoe, IL 61073 Phone: (815) 623-2168 www.forestcitygear.com

**Kaydon Bearings** 



# **Not Just Curiosity**

It may have taken hundreds of man hours to get certain Curiosity components approved by the JPL and NASA. This doesn't mean that engineers at Kaydon, Maxon and Forest City Gear have been locked in their basements for years focusing on Mars. Curiosity is but one project in a rather impressive list of applications that these companies have worked on.

Maxon, for example, has been developing motors for the commercial space industry. "We've had 10 motors on each of the SpaceX's Dragon spacecraft that has been pioneering commercial space cargo transport to the International Space Station," Phillips said.

Kaydon's Reali-Slim bearings are utilized in the hand pieces of the Intuitive Surgical da Vinci robot to transfer the movement of the surgeon's fingers to the robots arms. "We also redesigned the Honda robot ASIMO which uses nine catalog Reali-Slim bearings in inch and metric sizes," Hansen said.

Forest City provided the gears for the America's Cup racing yacht and has been incredibly busy in medical applications including heart pumps, kidney dialysis machines, x-ray positioning equipment and gears for a portable ventilator system. "We make a lot of gears and we have no idea where they actually end up," Young added.

# About This Directory

The 2012 Power Transmission Engineering Buyers Guide was compiled to provide you with a handy resource containing the contact information for significant suppliers of power transmission components.

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**Buyers Guide**Although every effort has been made to ensure that this Buyers Guide is as comprehensive, complete and accurate as possible, some companies may have been inadvertently omitted. If you'd like to add your company to the directory, we welcome you. Please visit www.powertransmission.com/getlisted.php to fill out a short form with your company informa-tion and Buyers Guide categories. These listings will appear online at www.powertransmission.com, and those listed online will automatically appear in next year's printed Buyers Guide.

# **Handy Online Resources**



The Power Transmission Engineering Buyers Guide – The listings printed here are just the basics. Visit our online buyers guide for the most comprehensive directory of suppliers of gears, bearings, motors, clutches, couplings, gear drives and other mechanical power transmission components, broken down into subcategory by type of product manufactured:

#### www.powertransmission.com/directory/



The Gear Industry Buyers Guide – If you manufacture gears or need information on suppliers of machine tools, tooling and services for gear manufacturers, please visit the buyers guide on Gear Technology's website:

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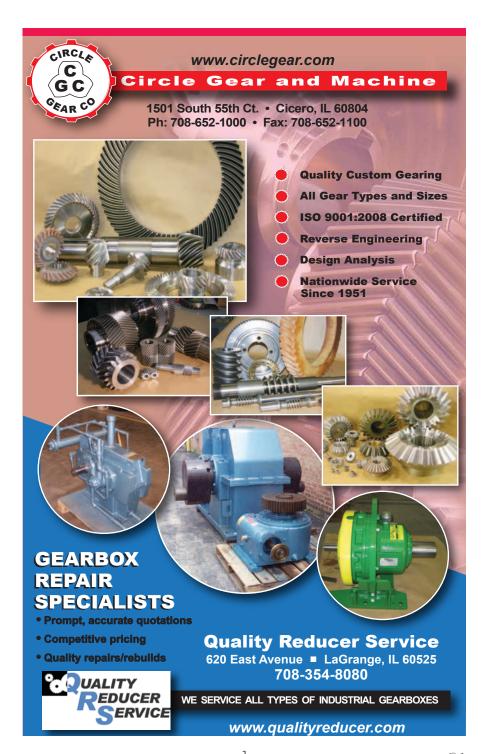
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Boneng Transmission (Suzhou) Co., Ltd.

NO.100 RUYUAN RD. XIANGCHENG DISTRICT SUZHOU 215121, CHINA Phone: +(86) 512-6618 9922 Fax: +(86) 512-6618-9966 info@boneng.com www.boneng.com

**Boneng Transmission USA LLC** 

1670 ENTERPRISE PKWY. TWINSBURG, OH 44087 Phone: (330) 425-1516 Fax: (330) 425-1519 america@boneng.com www.boneng.com/en/index.asp

Bonfiglioli Riduttori S.p.A.

VIA GIOVANNI XXIII, 7/A 40012 LIPPO DI CALDERARA BOLOGNA Phone: +(39) 051-6473-111 Fax: +(39) 051-6473-126

bonfiglioli@bonfiglioli.com www.bonfiglioli.com

Bonfiglioli USA

3541 HARGRAVE DRIVE HEBRON, KY 41048 Phone: (859) 334-3333 Fax: (859) 334-8888 dan.bair@bonfiglioli.com www.bonfiglioliusa.com

Bosch Rexroth USA 14001 SOUTH LAKES DRIVE CHARLOTTE NC 28273 Phone: (800) 739-7684 Fax: (704) 583-0523 info@boschrexroth-us.com www.boschrexroth-us.com

Boston Gear 701 CARRIER DR. CHARLOTTE NC 28216 Phone: (704) 588-5610

Fax: (704) 588-7181 info@altramotion.com www.bostongear.com

Bowman Hollis Mfg 2925 OLD STEELE CREEK ROAD **CHARLOTTE NC 28208** Phone: (704) 374-1500 Fax: (704) 333-5520 sbroadwell@bowmanhollis.com www.bowmanhollis.com

Rowmar IIC

8000 BLUFFTON ROAD FORT WAYNE, IN 46809 Phone: (260) 747-3121 Fax: (260) 747-9601 jstephens@bowmarllc.com www.bowmarllc.com

Brad Foote Gear Works, Inc

A BROADWIND ENERGÝ COMPANY 3250 S. CENTRAL AVE. CICERO, IL 60804 Phone: (708) 298-1100 sergio.gamboa@bwen.com www.bradfoote.com

BRECOflex CO., L.L.C. 222 INDUSTRIAL WAY WEST

P.O. BOX 829 EATONTOWN, NJ 07724 Phone: (732) 460-9500 Fax: (732) 542-6725 info@brecoflex.com www.brecoflex.com

Brelie Gear Company, Inc 2715 S. GLADSTONE PLACE MILWAUKEE, WI 53207

Phone: (414) 481-5488 sjanke@breliegear.com www.breliegear.com

**Brevini Power Transmission - Canada** 

236 GALAXY BLVD. TORONTO ONTARIO M9W 5R8, CANADA Phone: (416) 674-2591 Fax: (416) 674-1478 amurphy@brevini.ca www.brevini.ca

Brevini USA

14141 W. BREVINI DRIVE YORKTOWN, IN 47396 Phone: (765) 759-2300 Fax: (765) 759-2301 info@breviniusa.com www.breviniusa.com

**Brevini Wind USA** 

2400 N. PRIORITY WAY YORKTOWN, IN 47396 Phone: (765) 759-2128 Fax: (765) 759-4728 dale.harder@brevini.com www.breviniwind.com

Brewer Machine & Gear Co.

P.O. BOX 14726 ST. LOUIS, MO 63178-4726 Phone: (314) 534-4021 Fax: (314) 534-4026 info@brewertensioner.com www.brewertensioner.com

**Brighton Laboratories** 

11871 GRAND RIVER BRIGHTON, MI 48116 Phone: (810) 225-9520 Fax: (810) 225-9528 support@brightonlabs.com www.brightonlabs.com

**Broach Masters / Universal Gear** 1605 INDUSTRIAL DRIVE AUBURN, CA 95603 Phone: (530) 885-1939 Fax: (530) 885-8157 info@broachmasters.com www.broachmasters.com

Broaching Technologies, LLC

N63 W22621 MAIN STREET SUSSEX, WI 53089 Phone: (262) 820-1200 Fax: (262) 820-1201 sales@elmassusa.com www.elmassbroaching.com

Broadway Gear 2217 EXECUTIVE DRIVE GARLAND, TX 75041 Phone: (972) 351-8737 info@broadwaygear.com www.broadwaygear.com

Buehler Motor Inc.

860 AVIATION PARKWAY SUITE 300 MORRISVILLE NC 27560 Phone: (919) 380-3333 Fax: (919) 380-3256 sales@buehlermotor.com www.buehlermotor.com

Buffalo Gear, Inc. 3635 LOCKPORT ROAD SANBORN, NY 14132-9704

Phone: (888) BUFF-GEAR Fax: (716) 731-2553 info@buffalogear.com www.buffalogear.com

Butler Gear 12819 WEST SILVER SPRING RD. BUTLER, WI 53007 Phone: (262) 781-3270 Fax: (262) 781-1896 gears@butlergear.com www.butlergear.com

C-B Gear & Machine

4232 MOONEY ROAD HOUSTON, TX 77093 Phone: (281) 449-0777 Fax: (281) 590-9127 sales@cbgear.com www.cbgear.com

Cabat Inc.

5501 21ST STREET RACINE, WI 53401-1616 Phone: (262) 554-7500 Fax: (262) 554-7503 bgreuel@cabatinc.com www.cabatinc.com

Calicut Engineering Works Limited DUMRAON HOUSE, 2ND FLOOR, SUITE#6, 26A, CAMAC STREET,

P. O. BOX #9119, KOLKATA - 700016 WEST BENGAL, INDIA Phone: +(91) 33-2287-1979 Fax: +(91) 33-2287-6072

calicut@hotmail.com www.calicutengineering.com

Capstan Atlantic

10 CUSHING DRIVE WRENTHAM, MA 02093 Phone: (508) 384-3100 Fax: (508) 384-3196 sales@capstanatlantic.com www.capstanatlantic.com

**Carlisle Power Transmission** 

2601 WEST BATTLEFIELD ROAD SPRINGFIELD, MO 65807 Phone: (866) 773-2926 info@carlislebelts.com www.carlisletransportationproducts.

# Carlyle Johnson Machine Co. LLC P.O. BOX 9546 BOLTON, CT 06043-9546

Phone: (860) 643-1531 Fax: (860) 646-2645 info@cjmco.com www.cjmco.com

Carnes-Miller Gear Co., Inc.

P.O. BOX 268 LOCUST NC 28097 Phone: (800) 273-6814 Fax: (740) 888-4554 info@cmgear.com www.cmgear.com

Cattini & Figlio s.r.l. VIA DELL'ECOLOGIA 1 20080 CASARILE

Phone: +(39) 02-90053-1 Fax: +(39) 02 905-80-31 info@cattini.com www.cattini.com

CCVI Bearing 27561 HILLVIEW CT MUNDELEIN, IL 60060 Phone: (847) 540-8196 Fax: (847) 540-9130 evan.poulakidas@ccvi-us.com www.ccvi.com

Centa Corp. 2570 BEVERLY DRIVE #128 AURORA, IL 60502-8588 Phone: (630) 236-3500 Fax: (630) 236-3565 info@centacorp.com www.centa.info

Central Gear & Machine

10 GLENLAKE PARKWAY #130 ATLANTA, GA 30328 Phone: (678) 895-5383 Fax: (678) 222-3401 centralgear4@aol.com www.cgmatlanta.com

Certified Reducer Rebuilders Inc.

MADISON HEIGHTS, MI 48071 Phone: (248) 585-0883 Fax: (248) 589-1166 mrugercrr@aol.com www.certifiedreducer.net

Cerus Industrial

22995 NW EVERGREEN PARKWAY HILLSBORO, OR 97124 Phone: (800) 962-3787 Fax: (503) 643-4925 joe.fogg@cerusindustrial.com www.cerusind.com

Cestari Industrial e Comercial S.A. ROD. MONTE ALTO - VISTA ALEGRE, KM 3

MONTE ALTO SP CEP 15910-000 Phone: +(55) 16-3244-1022

Fax: +(55) 16-3244-1025 cestari@cestari.com.br www.cestari.com.br

Cha Industries, Inc. 1720 WALLACE AVE., UNIT B ST. CHARLES, IL 60174 Phone: (877) 432-7738 Fax: (866) 806-7738 sales@chagear.com www.chagear.com

Challenge Power Transmission (Aust) Pty. Ltd.

B11 SCORESBY INDUSTRY PARK JANINE STREET SCORESBY VICTORIA 3179 AUSTRALIA Phone: +(61) 03-9763-6701 Fax: +(61) 03-9764-5639 aussales@challengept.com

www.challengept.com

Challenge Power Transmission PLC MERRYHILLS ENTERPRISE PARK PARK LANE

WOLVERHAMPTON WV10 9TJ UNITED KINGDOM Phone: +(44) 1902-866116 Fax: +(44) 1902-866117 uksales@challengept.com www.challengept.com

Chengdu Talent Industrial Co., Ltd.

NO.8, JILIDI BEI ROAD, CHENGDU SICHUAN 610031, CHINA Phone: +(86) 28-83836380 Fax: +(86) 28-87609330 tt@ttindustrial.com www.ttindustrial.com

Chenta Gear - USA

26241 ENTERPRISE CT. LAKE FOREST, CA 92630 Phone: (949) 579-2789 Fax: (949) 206-0868 info@gearking.com www.chenta.com

Chongqing Rainbow M&E Co., Ltd.

24f, JIALEZIGUANG BUILDING
NO.498 HONGJIN ROAD
YUBEI DISTRICT, CHONGQING 400020, CHINA
Phone: +(86) 23-67735585
Fax: +(86) 23-67705763 gloriaqian@cqrainbow.com www.cqrainbow.com

Churon Co.

300 LIVLEY AVE. NORCROSS, GA 30071 Phone: (770) 676 0731 Fax: (770) 676 0733 schuron220@aol.com www.churonco.com

CIMA S.p.A. VIA CAIROLI, 8 40050 VILLANOVA DI CASTENASO ITALY Phone: +(39) 051-6032511 Fax: +(39) 051-6053292

salesdept@cimaingranaggi.it www.cimaingranaggi.it

Cincinnati Gearing Systems 5757 MARIEMONT AVE. CINCINNATI, OH 45227 Phone: (513) 527-8600 Fax: (513) 527-8635 gearsales@cst-c.com www.cincinnatigearingsystems.com

Circle Gear & Machine Co. 1501 S. 55TH COURT CICERO, IL 60804

Phone: (708) 652-1000 Fax: (708) 652-1100 cirgear@circlegear.com www.circlegear.com

Cixi Shenglong Synchronous Pulleys INDUSTRIAL ZONE,LONGSHAN TOWN CIXI, NINGBO ZHEJIANG 315311, CHINA Phone: +(86) 574-63785558 Fax: +(86) 574-63785557 Ilm@cn-slw.com www.cn-slw.com

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Clark Gear Works, Inc.

1218 SARATOGA DRIVE CAROL STREAM, IL 60188 Phone: (630) 561-2320 Fax: (630) 293-3444 dppapro@att.net www.clarkgearworks.com

Clarke Engineering Inc. (Clarke Gear Co.) 8058 LANKERSHIM BLVD. NORTH HOLLYWOOD, CA 91605 Phone: (818) 768-0690 Fax: (818) 767-5577 clarkegear@earthlink.net www.clarkegear.com

Classic Gears and Machining

2551 NORTHRIDGE DRIVE KAUKAUNA, WI 54130 Phone: (920) 766-6800 Fax: (920) 766-6815 jeff@classicgears.com www.classicgears.com

Cleveland Gear Co.

3249 E. 80TH STREET CLEVELAND, OH 44104 Phone: (800) 423-3169 Fax: (216) 641-2731 sales@clevelandgear.com www.clevelandgear.com

**Climax Metal Products Company** 

8141 TYLER BLVD. MENTOR, OH 44060 Phone: (800) 542-6552 Fax: (440) 585-5762 sales@climaxmetal.com climaxmetal.com

Cloyes Gear & Products Inc.

6101 PHOENIX AVENUE, SUITE 2 FORT SMITH, AR 72903 Phone: (479) 484-5555 Fax: (479) 484-5501 www.cloyes.com

CMS Vibration Solutions Ltd

**4B EAGLE PARK EAGLE PARK DRIVE** WARRINGTON CHESHIRE WA2 8JA UNITED KINGDOM Phone: +(44) 1925-582-899 Fax: +(44)1925-582-898 info@cmsantivibration.co.uk www.cmsantivibration.co.uk

**CNN Bearings** 

China Bearing (Tianjin) Import & Export Co. Ltd.

2701 ROOM, CITY TOWER YOUYI ROAD, HEXI DIST. TIANJIN 300074, CHINA Phone: +(86) 22-58268034 Fax: +(86) 22-83356222 alyssa@cnnbearing.com www.cnnbearing.com

Cogmatic, Inc. 6601 N. 40TH ST MILWAUKEE, WI 53209 Phone: (414) 353-7500 Fax: (414) 353-7507 mike@cogmatic.com www.cogmatic.com

**Collars and Couplings** 

PO BOX 1168 WEST SPRINGFIELD, MA 01090 Phone: (800) 593-2323 Fax: (877) 474-7005 info@collarsandcouplings.com www.collarsandcouplings.com

Columbia Gear Corp. 530 COUNTY ROAD 50 AVON, MN 56310 Phone: (800) 323-9838 Fax: (320) 356-2131 info@columbiagear.com www.columbiagear.com

Commercial Gear & Sprocket Co. Inc. 618 WASHINGTON STREET E. WALPOLE, MA 02032 Phone: (508) 668-1073 Fax: (508) 668-6625 info@commercialgear.com www.commercialgear.com

Comtec Mfg., Inc. P.O. BOX 940 1012 DELAUM ROAD ST. MARYS, PA 15857 Phone: (814) 834-9300 Fax: (814) 834-2303 sales@comtecmfg.com www.comtecmfg.com

**Cone Drive Gearing Solutions** 

240 EAST 12TH STREET TRAVERSE CITY, MI 49685-0272 Phone: (888) 994-2663 Fax: (888) 907-2663 orders@conedrive.com www.conedrive.com

Conroll Corporation 3302 KITTY HAWK ROAD, SUITE 100 WILMINGTON NC 28405 Phone: (910) 202-4292 Fax: (910) 202-4280 infor@conroll.com www.conroll.com

Control Switches International Inc. 2425 MIRA MAR AVE. LONG BEACH, CA 90815 Phone: (562) 498-7331 Fax: (562) 498-5894 sales\_info@controlswitches.com www.controlswitches.com

**Core Supply LLC** 

1954 N. FAYETTEVILLE ST. ASHEBORO NC 27203 Phone: (336) 672-3000 Fax: (336) 672-2900 admin@coresupplyllc.com www.coresupplyllc.com

Coremo Ocmea S.p.A. VIA GALILEI 12

I-20090 ASSAGO (MI) Phone: +(39) 0248-806-97 Fax: +(39) 0248-819-40 coremo@ocmea.it www.coremo.ocmea.it

**Cori Engineers Private Limited** 

79, VALMIKI STREET THIRUVANMIYUR CHENNAI - 600041 TAMIL NADU, INDIA Phone: +(91) 44-24426950 Fax: +(91) 44-24426951 cori@vsnl.com www.igp-group.com

**Cortec Corporation** 

4119 WHITE BEAR PARKWAY ST. PAUL, MN 55110 Phone: (651) 429-1100 Fax: (651) 429-1122 info@cortecvci.com www.cortecvci.com

Cotta Transmission Company 1301 PRINCE HALL DRIVE BELOIT, WI 53511-4439 Phone: (608) 368-5600 Fax: (608) 368-5605 sales@cotta.com www.cotta.com

Craft Bearing Company, Inc. 5000 CHESTNUT AVE. NEWPORT NEWS, VA 23605 Phone: (757) 247-6000 Fax: (757) 247-6300 info@craftbearing.com www.craftbearing.com

Cross + Morse SHADY LANE

GREAT BARR BIRMINGHAM WEST MIDLANDS B44 9EU UNITED KINGDOM Phone: +(44) 0121-360-0155 Fax: +(44) 0121-325-1079 sales@crossmorse.com www.crossmorse.com

Cryotron Magnadrives A-104, SAI SNEHA INDUSTRIAL ESTATE, PHATAK ROAD, BHAYANDER EAST, DISTT THANE MUMBAI - 401105, INDIA Phone: +(91) 22-28191473 Fax: +(91) 22-28190433 cryotron@satyam.net.in www.cmdindia.com

#### **CUI Inc**

20050 SW 112TH AVENUE TUALATIN, OR 97062 Phone: (800) 275-4899 Fax: (503) 612-2383 sales@cui.com www.cui.com

Currie Enterprises 382 N. SMITH ST. CORONA, CA 92880 Phone: (714) 528-6957 Fax: (951) 549-0267 travis@currieenterprises.com www.currieindustrial.com

#### Curtis Machine Co. Inc.

P.O. BOX 700 2500 EAST TRAIL STREET DODGE CITY KS 67801 Phone: (620) 227-7164 Fax: (620) 227-2971 curtis@curtismachine.com www.curtismachine.com

# Custom Gear & Machine Inc.

5466 EAST ROCKTON ROAD ROSCOE, IL 61073 Phone: (815) 389-6065 Fax: (815) 389-4548 sales@cgearinc.com www.cgearinc.com

#### Custom Machine & Tool Co. Inc.

301 WINTER STREET, UNIT I HANOVER, MA 02339 Phone: (781) 924-1003 Fax: (781) 924-5154 info@cmtco.com www.cmtco.com

#### **Custom Motors Inc.**

PO BOX 632 212 10TH ST. NORTH MOUNTAIN LAKE, MN 56159 Phone: (507) 427-2920 Fax: (507) 427-2256 lisa.anderson@custom-motorsinc. com

#### **Cutes Corporation**

NO. 2-22, NAN YUAN RD. CHUNG LI CITY (320) TAOYUAN, TAIWAN Phone: +(886) 3-4612333 Fax: +(886) 3-4526227 sales@cutes.com.tw www.cutes.com.tw

www.custom-motorsinc.com

#### Cyclo-Index

1129 W. FAIRVIEW AVE. CARTHAGE, MO 64836 Phone: (417) 358-6136 Fax: (417) 358-8629 info@cycloindex.com www.cycloindex.com

#### **D&D Power Transmission Products**

26199 JEFFERSON AVE. MURRIETA, CA 92562 Phone: (951) 600-4468 Fax: (951) 600-4475 sales@powerdrive-belt.com www.powerdrive-belt.com

#### D.G. Steel & Son Engineering Ltd.

BARNBROOK GEAR WORKS BROOK STREET BURY LANCASHIRE BL9 6AF UNITED KINGDOM

Phone: +(44) 0161-764-4862 Fax: +(44) 0161-761-1233 dgsteel@btconnect.com www.dgsteel.com

Daemar Inc. 861 CRANBERRY COURT OAKVILLE ONTARIO L6J 6J7, CANADA Phone: (905) 847-6500 Fax: (905) 847-6943 sales@daemarinc.com www.daemar.com

Daido Corporation of America 1031 FRED WHITE BLVD. P.O. BOX 7659 PORTLAND, TN 37148 Phone: (615) 323-4020 Fax: (615) 323-4015 info@daidocorp.com www.daidocorp.com

#### Dalton Bearing Service, Inc.

P.O. BOX 1363 DALTON, GA 30722 **Phone: (706) 226-2022** Fax: (706) 226-2032 sales@daltonbearing.com www.daltonbearing.com

#### **Danaher Motion**

203A WEST ROCK ROAD RADFORD, VA 24141 Phone: (540) 633-3549 Fax: (540) 633-0294 www.danahermotion.com

Darbar Belting
1, PRASTHAN-1 NEAR SAYONA CITY ROAD GHATLODIA AHMEDABAD - 380061, INDIA Phone: +(91) 98-2502-3086 darbarbelting@gmail.com www.darbarbelting.co.in

# **Datasyst Engineering & Testing Services,**

Inc. S14 W33511 HIGHWAY 18 Phone: (800) 969-4050 Fax: (262) 968-3050 sales@datasysttest.com www.datasysttest.com

Daubert Cromwell 12701 S. RIDGEWAY AVE. ALSIP, IL 60803 Phone: (708) 293-7750 Fax: (708) 293-7765 info@daubertcromwell.com www.daubertcromwell.com

### Davall Gears Ltd.

TRAVELLERS LANE WELHAM GREEN HATFIELD HERTFORDSHIRE AL9 7JB UNITED KINGDOM Phone: +(44) 0-1707- 2831-00 Fax: +(44) 0-1707-2831-11 info@davall.co.uk

### www.davall.co.uk David Brown Gear Systems Ltd.

PARK ROAD LOCKWOOD HUDDERSFIELD YORKSHIRE HD4 5DD UNITED KINGDOM Phone: +(44) 0-1484-465-500

Fax: +(44) 0-1484 465-501 uk@davidbrown.com www.davidbrown.com

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Dee Bee Enterprise C-1/4 URMI APARTMENTS, FATEHGUNJ VADODARA - 390002 GUJARAT, INDIA Phone: +(91) 265-2794341 Fax: +(91) 265-2794341 dbe@deebee-enterprise.com www.deebee-enterprise.com

#### **Del-Tron Precision Inc.**

5 TROWBRIDGE DRIVE BETHEL, CT 06801 Phone: (203) 778-2727 Fax: (203) 778-2721 deltron@deltron.com www.deltron.com

Deliner Brakes AB 8334-H ARROWRIDGE BLVD. CHARLOTTE NC 28273 Phone: (401) 515-4657 Fax: (401) 515-4542 glenn.scott@dellner-brakes.com www.dellner-brakes.com

#### **Delroyd Worm Gear**

2221 NIAGARA FALLS BLVD. NIAGARA FALLS, NY 14302 Phone: (716) 731-5180 Fax: (716) 731-9329 jay.dubell@delroyd.com www.delroyd.com

#### Delta Dynamics Inc.

7580 MACDONALD ROAD DELTA BC V4G 1N2, CANADA Phone: (604) 940-1015 Fax: (604) 940-1029 info@deltadynamics.com www.deltadynamics.com

# Delta Gear Company 345 SUN VALLEY CIRCLE

FENTON, MO 63026 Phone: (636) 343-0311 Fax: (636) 343-0285 sales@dgc-atc.com www.dgc-atc.com

Delta Gear Inc. 36251 SCHOOLCRAFT LIVONIA, MI 48150 Phone: (734) 525-8000 Fax: (734) 525-8400 tony.w@delta-gear.com www.delta-gear.com

#### Delta Inspection

36251 SCHOOLCRAFT LIVONIA, MI 48150 Phone: (734) 525-8000 Fax: (734) 525-8400 sales@delrecorp.com www.deltainspection.org

Delta Research Corp. 32971 CAPITOL STREET LIVONIA, MI 48150 Phone: (734) 261-6400 Fax: (734) 261-0909 sales@delrecorp.com www.deltaresearch.com

DePe Gear Company Ltd UNIT 1, GROVE ROAD IND. ESTATE GROVE ROAD FENTON STOKE ON TRENT STAFFORDSHIRE ST4 4LG UNITED KINGDOM Phone: +(44) 0-1782 594114 Fax: +(44) 0-1782 594115 sales@depe.co.uk www.depe.co.uk

### Desch Canada Ltd.

240 SHEARSON CRESCENT CAMBRIDGE ONTARIO N1T 1J6, CANADA Phone: (519) 621-4560 Fax: (519) 623-1169 desch@desch.on.ca www.desch.de

### **Diamond Chain Company**

402 KENTUCKY AVENUE INDIANAPOLIS, IN 46225 Phone: (800) 872-4246 Fax: (317) 613-2243 sales@diamondchain.com www.diamondchain.com

DieQua Corp. 180 COVINGTON DRIVE BLOOMINGDALE, IL 60108 Phone: (630) 980-1133 Fax: (630) 980-1232 info@diequa.com www.diequa.com

# Dimatic Die & Tool Co. P.O. BOX 12037 OMAHA NE 68112-0037 Phone: (402) 571-7300 Fax: (402) 571-0153

dimatic@dimatic.com www.dimatic.com

Dings Company 4740 W. ELECTRIC AVENUE MILWAUKEE, WI 53219 Phone: (414) 672-7830 Fax: (414) 672-5354 www.dingsbrakes.com

# Discovery Technology International, Inc. 6968 PROFESSIONAL PARKWAY EAST SARASOTA, FL 34240

Phone: (941) 907-4444 Fax: (941) 907-4512 info@discovtech.com www.discovtech.com

#### **DN Sales Australia**

P.O. BOX 987 NORTH LAKES QLD 4509 AUSTRALIA Phone: +(61) 7-3491-6474 Fax: +(61) 7-3491-7944 dnsales@bigpond.com www.dnsales.com.au

#### Donkers Design Solutions

492 JOSEPH ST. NEW HAMBURG ONTARIO N3A 2H2, CANADA Phone: (519) 957-2217 john@donkersdesigns.com www.donkersdesigns.com

# Drive Lines Technologies Ltd. 45 MURDOCK ROAD

BEDFORD BEDFORDSHIRE MK41 7PQ UNITED KINGDOM Phone: +(44) 01234-360689 Fax: +(44) 01234-345673 sales@drivelines.co.uk www.drivelines.co.uk

Drive Systems 1522 5TH AVENUE SE PO BOX 2747 DECATUR AL 35602 Phone: (256) 340-4200 Fax: (256) 340-4201 www.drive-sys.com

# Drive Systems Technology Inc.

24 MARLBOROUGH LAN GLEN MILLS, PA 19342-1519 Phone: (610) 358-0785 Fax: (610) 358-2776 geardoctor@verizon.net www.gear-doc.com

#### **Duff-Norton**

9415 PIONEER AVE. CHARLOTTE NC 28273 Phone: (704) 588-4610 Fax: (704) 588-1994 duffnorton@cmworks.com www.duff-norton.com

Dunkermotoren USA Inc. 2511 TECHNOLOGY DRIVE SUITE 105

ELGIN, IL 60124 Phone: (224) 293-1300 Fax: (224) 293-1301

john.morehead@dunkermotoren.com www.dunkermotor.com

3119 SCIOTO DARBY EXECUTIVE CT. HILLIARD, OH 43026 Phone: (800) 770-2358 Fax: (614) 777-9448 jim@durabelt.com www.durabelt.com

Durabond Slides 5627 AIRLINE HIGHWAY FRUITPORT, MI 49415 Phone: (231) 865-1800 Fax: (231) 865-1802 www.durabondslide.com

2-7-13, FUKUURA KANAZAWA-KU YOKOHAMA 236-0004 Phone: +(81) 45-780-5570 Fax: +(81) 45-701-6830 overseas@dymco.co.jp www.dymco.co.jp

Dynamic International Enterprise Ltd.

ROOM NO. 3604 & 3605 BUILDING A, NEW CENTURY PLAZA NO.288 EAST ZHONGSHAN ROAD NANJING JIANGSU 210002, CHINA Phone: +(86) 25-8429-3027 Fax: +(86) 25-8429-3184 lindali@njzenith.com www.china-power-transmission.com

**Dynamic Structures and Materials, LLC** 

114 SE PARKWAY CT., STE. 160 FRANKLIN, TN 37064 Phone: (615) 595-6665 Fax: (615) 595-6610 salesinfo@dynamic-structures.com www.dynamic-structures.com

Dynex/Rivett Inc. 770 CAPITOL DR. PEWAUKEE, WI 53072 Phone: (262) 691-2222 Fax: (262) 691-0312 sales@dynexhydraulics.com www.dynexhydraulics.com

**Econobelt and OTC Gears** 

125 RAILROAD AVENUE GARDEN CITY PARK, NY 11040-5016 Phone: (516) 437-6700 Fax: (516) 328-3343 QTCGearsSupport@qtcgears.com www.econobelt.com

EIC Industry Group 53 GREEN POND ROAD SUITE 3 ROCKAWAY, NJ 07866 Phone: (973) 983-1988 Fax: (973) 983-2688 support@eicind.com www.eicind.com

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**Electro Steel Engineering Company** 

38 NAGDEVI CROSS LANE GROUND FLOOR MUMBAI MAHARASHTRA 400003, INDIA Phone: +(91) 22-3435361 Fax: +(91) 22-23412111 tanaygupta@hotmail.com www.indiamart.com/tyginc

**Electromatic Engineers Pvt. Ltd** 

8-B SAHELI MARG
UDAIPUR RAJASTHAN 313001, INDIA
Phone: +(91) 294 2526933
Fax: +(91) 294 2526525
electromatickol@hotmail.com www.clutchesbrakes.com

**Electronic Machine Parts** 

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**COCENTAINA ALICANTE 03820** Phone: +(34) 9665-002-23 Fax: +(34) 9665-001-53 comercial@engranajes-masia.com www.engranajes-masia.com

Equipment Concepts 400 LINDEN AVE DAYTON, OH 45403 Phone: (937) 258-1755 Fax: (937) 258-1755 franer@frognet.net www.equipment-concepts.com

Eskridge 1900 KANSAS CITY ROAD OLATHE KS 66061 Phone: (913) 782-1238 Fax: (913) 782-4206 sales@eskridgeinc.com www.eskridgeinc.com

Essential Power Transmission Pvt. Ltd. 6 HYTEX INDUSTRIAL ESTATE S.V. ROAD MUMBAI 400068, INDIA Phone: +(91) 2228488742 Fax: +(91) 2228488147

esenpro@bom3.vsnl.net.in www.esenpro.com

Excel Enterprises
203, DDA COMPLEX
LAL MARKET, H-BLOCK
NEW DELHI DELHI 110018, INDIA Phone: +(91) 11-28542680 info@excelenterprises.biz www.excelenterprises.biz

Excel Gear, Inc. 11865 MAIN STREET ROSCOE, IL 61073 Phone: (815) 623-3414 Fax: (815) 623-3314 chinn@excelgear.com www.excelgear.com

Excel Industrial Gears Pvt. Ltd. 45/46, PODAR CHAMBERS S.A. BRELVI ROAD

MUMBAI 400023, INDIA Phone: +(91) 22 65073549 Fax: +(91) 22 22661545 excelpiv@mtnl.net.in www.excelpiv.com

Exlar Corporation 18400 WEST 77TH STREET CHANHASSEN, MN 55317 Phone: (952) 368-3434 Fax: (952) 368-4877 info@exlar.com www.exlar.com

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2250 ESTES AVE ELK GROVE VILLAGE, IL 60007 Phone: (847) 981-1500 Fax: (847) 809-6318 fagorusa@fagor-automation.com www.fagor-automation.com

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3920 WEST POINT BLVD. WINSTON-SALEM NC 27103 Phone: (336) 659-3400 Fax: (336) 659-9323 sales@fairchildproducts.com www.specontransmission.com

Federal Gear 38134 WESTERN PARKWAY WILLOUGHBY, OH 44094 Phone: (440) 946-4327 Fax: (440) 946-8018 info@federalgear.com www.federalgear.com

Festo Corporation 395 MORELAND ROAD HAUPPAUGE, NY 11788 Phone: (800) 99-FESTO Fax: (800) 96-FESTO customer.service@us.festo.com www.festo.com/usa

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Fife Corporation

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First Gear Engineering & Technology 7606 FREEDOM WAY FORT WAYNE, IN 46818 Phone: (260) 490-3238 Fax: (260) 490-4093 greg@first-gear.com www.first-gear.com

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FK Bearing Corp. NO71-87, LIANTANG, NORTH INDUSTRIAL ZONE, JIMEI XIAMEN FUJIAN 361021, CHINA Phone: +(86) 592-6689006 Fax: +(86) 592-6689007 Ijz@fk-bearing.com www.fk-bearing.com

Flexocon Engineers Private Limited ABAKASH APARTMENT, FLAT 1C, 14 MIG HOUSING ESTATE, SODEPUR KOLKATA WEST BENGAL 700110, INDIA Phone: +(91) 33-25230864 Fax: +(91) 33-25230866 flexocon@gmail.com www.flexoconindia.com

**FMC Engineering** 

P.O. BOX 31115 HOUSTON TX. 77231 Phone: (713) 988-7700 sales@fmcengineering.com www.fmcengineering.com

Force Control Indutries 3660 DIXIE HIGHWAY FAIRFIELD, OH 45014 Phone: (513) 868-0900 Fax: (513) 868-2105 tstoner@forcecontrol.com www.forcecontrol.com

Forest City Gear Co. 11715 MAIN STREET

**ROSCOE, IL 61073** Phone: (815) 623-2168 Fax: (815) 623-6620 rmikel@fcgear.com www.fcgear.com

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Formsprag Clutch 23601 HOOVER RD. WARREN, MI 48089 Phone: (586) 758-5000 Fax: (586) 758-5204 formsprag.clutch@formsprag.com www.formsprag.com

FSI Technologies Inc. 668 WESTERN AVE. LOMBARD, IL 60148

Phone: (630) 932-9380 Fax: (630) 932-0016 info@fsinet.com www.fsinet.com

Fusion Babbitting Co, Inc 4540 W. BURNHAM ST. MILWAUKEE, WI 53219 Phone: (800) 613-5118 mmckindley@sbcglobal.net www.fusionbabbitting.com

Future Technologies, Inc. 2490 MIDLAND ROAD BAY CITY, MI 48706-9469 **Phone: (989) 686-6200** Fax: (989) 686-3070 davidl@futuretechnologies.com www.futuretechnologies.com

FYH Bearing Units USA, Inc. 13201 FYH DRIVE HUNTLEY, IL 60142 Phone: (847) 487-9111 Fax: (847) 487-9222 sblair@fyhusa.com www.fyhusa.com

Gajra Gears Pvt. Ltd. STATION ROAD DEWAS MP 455001, INDIA Phone: +(91) 7272-421000 Fax: +(91) 7272-421001 gautam@gajra.com www.gajra.com

**Galil Motion Control** 3750 ATHERTON ROAD ROCKLIN, CA 95765 Phone: (916) 626-0101 galil@galilmc.com www.galilmc.com

GAM Gear 901 E. BUSINESS CENTER DRIVE MOUNT PROSPECT, IL 60056 Phone: (847) 649-2500 Fax: (847) 649-2501 marketing@gamweb.com www.gamweb.com

**Gates Corporation** 1551 WEWATTA ST **DENVER, CO 80202** Phone: (303) 744-5473 Fax: (303) 744-4910 gates@powertransmission.com www.gates.com

Gayatri Gear Industries 73,74 ASHAPURA ESTATE, RAMOL CHOKDI,PH-IV,GIDC,VATVA MAHMEDABAD GUJARAT 382445, INDIA Phone: +(91) 7925840180 Fax: +(91) 7925840180 info@gayatrigear.com www.gayatrigear.com

Gear Design & Service Pty. Ltd. 355 SETTLEMENT ROAD THOAMSTOWN VICTORIA 3074 AUSTRALIA Phone: +(61) 3 9465 6355 Fax: +(61) 3 9465 6744 sales@geardesign.com.au www.geardesign.com.au

Gear Manufacturing Inc. 3721 E. MIRALOMA AVE ANAHEIM, CA 92806 Phone: (714) 792-2895 Fax: (714) 792-2870 info@gearmfg.com www.gearmfg.com

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Gear Technology 10671 CIVIC CENTER DRIVE RANCHO CUCAMONGA, CA 91741 Phone: (909) 476-0343 Fax: (909) 476-0344 geartech5@earthlink.net

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Gear Works - Seattle, The P.O. BOX 80886 500 SO. PORTLAND ST. SEATTLE, WA 98108 SEE OUR AD P86 Phone: (206) 762-3333 Fax: (206) 762-3704 jmagnuson@thegearworks.com www.thegearworks.com

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GearTec Inc. 4245 HAMANN PKWY. WILLOUGHBY, OH 44094-5623 Phone: (440) 953-3900 Fax: (440) 953-3906 jimw@geartec-ohio.com www.geartecinc.com

GearVisions, Inc. 38310 WILLOUGHBY PARKWAY WILLOUGHBY OHIO 44094 Phone: (440) 951-4327 Fax: (440) 951-6230 marketing@gearvisions.com www.gearvisions.com

Genemax Industrial Inc. 33, SHIN-YI ROAD, AN-PING INDUSTRIAL DISTRICT, TAINAN 702, TAIWAN TAINAN 702, TAIWAN Phone: +(886) 62637999 Fax: +(886) 62637950 info@gmx.com.tw www.gmx.com.tw

George Lane & Sons Ltd BANNERLEY ROAD GARRETTS GREEN BIRMINGHAM WEST MIDS B33 OSL UNITED KINGDOM Phone: +(44) 121-784-5525 Fax: +(44) 121-783-6988 info@georgelane.co.uk www.georgelane.co.uk

Gerhardt Gear Co. Inc. 133 EAST SANTA ANITA AVE. BURBANK, CA 91502 Phone: (818) 842-6700 Fax: (818) 842-1458 gears@gerhardtgear.com www.gerhardtgear.com

**Ghatge Patil Industries** UČHGOAN KOLHAPUR MAHARASTRA KOLHAPUR MAHARASTRA 416007, INDIA Phone: +(91) 231-2608000 corporate@gpind.com www.gpind.com

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GKN Driveline HAUPTSTRASSE 130 LOHMAR GERMANY 53797 **GERMANY** Phone: +(49) 2246 100 2239 davide.trinca@gkndriveline.com www.gkndriveline.com

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Gleason K2 Plastics 8210 BUFFALO ROAD BERGEN, NY 14416 Phone: (585) 494-2470 Fax: (585) 494-2474 kkremmin@gleason.com www.k2plasticsinc.com

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GMN Bearing Usa, Ltd. 12633 SHILOH CHURCH ROAD HOUSTON, TX 77066 Phone: (800) 323-5725 Fax: (888) 858-8678 sales@gmnbt.com

www.gmnbt.com

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GMN Paul Miller Industrie GmbH & Co. KG AUBERE BAYREUTHER STRABE NURNBERG BAYERN 90411 GERMANY Phone: +(49) 911 5691-0 Fax: +(49) 911 5691-587 info@gmn.de www.gmn.de

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GTA Gear Technology & Applications BV P.O. BOX 127 SOMEREN N-B 5710 AC NETHERLANDS Phone: +(31) 4934-938-42 Fax: +(31) 4934-916-42 info@gta.nl www.gta.nl

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Halifax Rack & Screw Cutting Co. Ltd. 3786 HOPPER HILL ROAD CINCINNATI, OH 45255 Phone: (513) 688-0065 Fax: (513) 688-1361 info@halifaxrs.com www.halifaxrs.com

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Phone: +(31) 5347-532-32 Fax: +(31) 5347-702-85 sales@hankamp.nl www.hankamp.nl

Hansen Motor Corporation 901 SOUTH FIRST STREET PRINCETON, IN 47670-2369 Phone: (812) 385-3415 Fax: (812) 385-3013 sales@hansen-motor.com www.hansen-motor.com

Harbin High Tech Machinery International Co., Ltd.

RM 801 NO.209 CHANGJIANG RD HRB HLJ 150090, CHINA Phone: 8645187222760 Fax: 8645187222797 leon@ht-machinery.com www.ht-machinery.com

Harmonic Drive LLC 247 LYNNFIELD STREET

PEABODY, MA 01960 Phone: (978) 532-1800 Fax: (978) 532-9406 info@harmonicdrive.net www.harmonicdrive.net

Haumea Srl

VIA TREDICI NOVEMBRE 56A VILLAFRANCA DI FORLI' FORLI'FC 47122 ITALY Phone: +(39) 9543 779518 Fax: +(39) 0543 751119 info@haumea.com www.haumea.com

Havlik Gear

455 SHELDON DRIVE CAMBRIDGE ONTARIO N1T 2B7, CANADA Phone: (519) 624-6240 Fax: (519) 624-4119 havlik@sympatico.ca www.havlikgear.com

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SITTERTALSTRASSE 3 ST. GALLEN SG 9014 SWITZERLAND Phone: +(41) 71 223 2687 Fax: +(41) 71 223 2687 info@hoffmann-tech.ch www.hoffmann-tech.ch

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**Howdon Power Transmission Limited** 

PAGANHILL LANE CAINSCROSS STROUD GLOS GL5 4JT UNITED KINGDOM Phone: +(44) 1453 750814 Fax: +(44) 1453 765320 sales@howdon.co.uk www.howdon.com

HPB Motion Control Co. Ltd. 4F, NO.120, SEC.1, SAN MIN RD. PAN CHIAO TAIPEI 100, TAIWAN Phone: +(886) 2-89645666 Fax: +(886) 2-89641537 motion@msa.hinet.net www.hpb-industry.com

Huco Dynatork

MERCHANT DRIVE
HERTFORD HERTFORDSHIRE SG13 7BL UNITED KINGDOM
Phone: +(44) 1992501900 Fax: +(44) 1992509890 david.proud@altramotion.com www.huco.com

IADA Ltd

ALGORES WAY CAMBRIDGE CAMBRIDGESHIRE PE13 2TQ UNITED KINGDOM Phone: +(44) 116 239 5099 sales@iadaltd.co.uk www.iadaltd.co.uk

IAI America, Inc. 2690 W. 237TH STREET TORRANCE, CA 90505 Phone: (310) 891-6015 Fax: (310) 891-0815 info@intelligentactuator.com

www.intelligentactuator.com

9400 WEST 55TH MERRIAM KS 66203 Phone: (913) 261-2148 ibtinfo@ibtinc.com www.ibtinc.com

**IDC-USA** 

933 WESTERN DRIVE INDIANAPOLIS, IN 46241 Phone: (317) 244-9200 Fax: (317) 244-4600 info@idc-usa.com www.idc-usa.com

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Igus Inc.

P.O. BOX 14349 EAST PROVIDENCE RI 02916 Phone: (800) 521-2747 Fax: (401) 438-7270 webmaster@igus.com www.igus.com

IMO USA Corp. 101 INNOVATION DRIVE MC QUEEN PARK SUMMERVILLE, SC 29483 Phone: (843) 695-6220 americas@goimo.com www.imo.us

Indiana Tool/Indiana Gear 6100 MICHIGAN ROAD PLYMOUTH, IN 46563 Phone: (574) 936-2112 Fax: (574) 936-2112 dkneidig@itamco.com www.itamco.com

**Industrial Clutch** 

515 FREDERICK STREET WAUKESHA, WI 53186-5607 Phone: (262) 547-3357 Fax: (262) 547-2949 info@indclutch.com www.indclutch.com

Industrial Clutch Parts Ltd. UNIT 11 BINGSWOOD IND EST WHALEY BRIDGE HIGH PEAK SK23 7LY UNITED KINGDOM

Phone: +(44) 1663 734627 Fax: +(44) 1663 733023 chris@icpltd.co.uk www.icpltd.co.uk

Industrial Friction Materials Ltd.

OUSTIAI FICTION MATERIAIS LTG.
UNIT 7, EAST MOORS BUSINESS PARK,
EAST MOORS ROAD,
OCEAN PARK
CARDIFF SOUTH GLAMORGAN CF245JX
UNITED KINGDOM
Phone: +(29) 20499111
Fax: +(29) 20490111
Fax: +(29) 204900111

info@industrialfriction.com www.industrialfriction.com

**Industrial Gears Watteeuw** KAMPVELDSTRAAT 51

8020 00STKAMP **BELGIUM** Phone: +(32) 5082-6907 Fax: +(32) 5082-6974 sales@watteeuw.be www.watteeuw.be

**Industrial Indexing Systems** 

626 FISHERS RUN VICTOR, NY 14564 Phone: (585) 924-9181 Fax: (585) 924-2169 tinae@iis-servo.com www.iis-servo.com

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Industrial Pulley & Machine Co, Inc. P.O. BOX 35 EAST CENTER ST. WEST MANSFIELD, OH 43358 Phone: (937) 355-4910 Fax: (937) 355-2001 sales@industrialpulley.com www.industrialpulley.com

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Innovative Rack & Gear

365 BALM CT. W00D DALE, IL 60191 Phone: (630) 766-2652 Fax: (630) 766-3245 info@gearacks.com www.gearacks.com

Insco Corp. 412 MAIN STREET GROTON, MA 01450 Phone: (978) 448-6368 Fax: (978) 448-5155 sales@inscocorp.com www.inscocorp.com

Intech Corporation 250 HERBERT AVENUE CLOSTER, NJ 07624 Phone: (201) 767-8066 Fax: (201) 767-7797 info@intechpower.com www.intechpower.com

Intecno USA 509 10TH ST ALTON IOWA 51003 Phone: (712) 540-9080 usaoffice@transtecno.com www.intecno-srl.com/eng/index.htm

Intellidrives, Inc 28 CRICKET DRIVE HOLLAND, PA 18966 Phone: (215) 728-6804 Fax: (215) 745-9459 admin@intellidrives.com www.intellidrives.com

**Interinar Electronics** 

14322 SKY FLOWER LN TAMPA, FL 33626 Phone: (727) 271-0869 sales@interinar.com www.interinar.com

International Distribution Alliance, Inc.

1125 MILFORD AVENUE ROCKFORD, IL 61109 Phone: (815) 227-9010 Fax: (815) 227-9012 sales@idamotion.com www.idamotion.com

InvenSense

1197 BORREGAS AVENUE SUNNYVALE, CA 94089 Phone: (408) 988-7339 Fax: (408) 988-8104 eelam@invensense.com www.invensense.com

ISC Companies 12905 HIGHWAY 55 WEST MINNEAPOLIS, MN 55441 Phone: (763) 559-0033 Fax: (763) 559-3148 c.bursack@isccompanies.com www.isccompanies.com

Italgear S.r.l.

VIA PARINI, 18 CASALECCHIO DI RENO (BOLOGNA) 40033

Phone: +(39) 0515-904-90 Fax: +(39) 0516-132-163 info@italgear.com www.italgear.com

**ITW Heartland** 

1601 36TH AVENUE ALEXANDRIA, MN 56308 Phone: (320) 762-0138 Fax: (320) 762-1571 andy.quist@itwheartland.com www.itwheartland.com

Jahnel - Kestermann Gmbh & Co. Kg HUNSCHEIDTSTR. 116 44789 BOCHUM, GERMANY BOCHUM GERMANY 44789 **GERMANY** Phone: +(49) 234 339 238

Fax: +(49) 234 339 330 sales@jake-gear.com www.jake-gear.com

Jason Industrial Inc.

340 KAPLAN DRIVE FAIRFIELD, NJ 07004 Phone: (973) 227-4904 Fax: (973) 227-1651 inquiries@jasonindustrial.com www.jasonindustrial.com

JinHang Precision Bearing Co.,Ltd INDUSTRY AND TECHNOLOGY ZONE OF LUOYANG CITY

LUOYANG HENAN 471000, CHINA Phone: +(86) 379 62226263 Fax: +(86) 379 62226263 lyjh@lyjhbearing.com www.lyjhbearing.com

JVL Industri Elektronik A/S

**BLOKKEN 42** BIRKEROED 3460 DENMARK Phone: +(46) 45 82 44 40 Fax: +(45) 45 82 55 50 jvl@jvl.dk www.jvl.dk

K & L Clutch & Transmission 3529 RAIDER DRIVE HURST, TX 76053

Phone: (817) 267-0129 kandlclutch@gmail.com www.klclutch.com

K+S Services

15677 NOECKER WAY SOUTHGATE, MI 48195 Phone: (734) 374-0400 Fax: (734) 759-0082 rniesyto@k-and-s.com www.k-and-s.com

**Kamar Industries** 

P.O. BOX 619 BUFFALO, NY 14213 Phone: (716) 549-5534 Fax: (716) 549-6595 info@kamarindustries.com www.kamarindustries.com

Kapsyn Manufacturing Company AUJLA ROAD, PO MANSOORWAL DONA, KAPURTHALA PUNJAB 144601, INDIA Phone: +(91) 1822 237209 Fax: +(91) 1822 233452 kapsyn@vsnl.com www.kapsyn.com

**Kavlico Corporation** 

14501 PRINCETON AVENUE MOORPARK, CA 93021 Phone: (805) 523-2000 Fax: (805) 523-7125 sales@kavlico.com www.kavlico.com

Kaydon Corporation Bearings Division 2860 MCCRACKEN STREET MUSKEGON, MI 49441 Phone: (231) 755-3741 Fax: (231) 759-4102 bearings@kaydon.com www.kaydonbearings.com

**KB Controls** 

8803 SORENSEN AVE. SANTA FE SPRINGS, CA 90670 **Phone: (562) 907-7650** Fax: (562) 907-7650 sales@kb-controls.com www.kb-controls.com

Kbk Antriebstechnik Gmbh

info@kbk-antriebstechnik.de KLINGENBERG BAVARIA 63911 Phone: +(49) 9372-130-486-0 Fax: +(49) 9372-134-730 s.karpstein@kbk-antriebstechnik.de www.kbk-antriebstechnik.de

Kilian Manufacturing Corp. P,O. BOX 6974

1728 BURNET AVE. SYRACUSE, NY 13217 Phone: 315-432-0700 Fax: 315-432-1312 dom.leo@kilianbearings.com www.kilianbearings.com

Kinefac Corporation 156 GODDARD MEMORIAL DR. WORCESTER, MA 01603 Phone: (508) 754-6891 Fax: (508) 756-5342 sales@kinefac.com www.kinefac.com

KISSsoft, USA, LLC 3719 N. SPRING GROVE ROAD JOHNSBURG, IL 60050 Phone: (815) 363-8823 Fax: (815) 363-8823 info@kisssoft.com www.kisssoft.com

Klam America Corportation

5502 PEARL STREET DENVER, CO 80216 Phone: (800) 852-5445 Fax: (303) 297-3815 rich@klamamerica.com www.klamamerica.com

Kleiss Gears, Inc. 390 INDUSTRIAL AVENUE

GRANTSBURG, WI 54840 Phone: 715-598-4492 Fax: 715-463-5996 drichter@kleissgears.com www.kleissgears.com

Kluber Lubrication North America L.P.

32 INDUSTRIAL DRIVE LONDONDERRY NH 03053 Phone: (603) 647-4105 Fax: (603) 647-4106 info@us.kluber.com www.kluber.com

**Kraft Power Corporation** 

199 WILDWOOD AVE WOBURN, MA 01801 Phone: (800) 969-6121 Fax: (781) 933-7812 gainfo@kraftpower.com www.kraftpower.com

KTR Corp.
122 ANCHOR ROAD
MICHIGAN CITY, IN 46360
Phone: (219) 872-9100 Fax: (219) 872-9150 ktr-us@ktr.com www.ktrcorp.com

Lab Threads & Gear Works, Inc.

515 MAIN STREET YALESVILLE, CT 06492 Phone: (203) 949-9097 Fax: (203) 949-9697 seolabthreads@gmail.com www.labthreads.com/

Lafert North America 5620 KENNEDY RD. MISSISSAUGA ONTARIO L4Z 2A9, CANADA Phone: (800) 661-6413 Fax: (905) 629-2852 sales@lafertna.com www.lafertna.com

Lange Machinery Group NO. 65 NORTH JIANXIN ROAD JIANGBEI DISTRICT CHONGQING 400020, CHINA Phone: +(86) 23-67698698 Fax: +(86) 23-67698691 manager@langemachinery.com www.langemachinery.com

Lee Linear 727 SOUTH AVE. PISCATAWAY, NJ 08854 Phone: (800) 221-0811 Fax: (732) 968-7080 www.leelinear.com

Link Gear & Machine Company 3101 FALLS CLIFF ROAD

P.O. BOX 4886

BALTIMORE MD 21211

Phone: (410) 467-0878 Fax: (410) 467-6891 link@linkgear.com www.linkgear.com

Linn Gear

100 N 8TH ST. P.O. BOX 397 LEBANON, OR 97355 Phone: (541) 259-1211 Fax: (541) 259-1299 sales@linngear.com www.linngear.com

LM76 Linear Motion Bearings 140 INDUSTRIAL DRIVE E. LONGMEADOW, MA 01028 Phone: (800) 513-3163 Fax: (413) 525-3735 mquinn@lm76.com www.LM76.com

**Lnt India** 

P**51** 

A - 69, J F F COMPLEX JHANDEWALAN, NEW DELHI - 110 055 NEW DELHI DELHI 110 055, INDIA Phone: +(91) 11-23621566 Fax: +(91) 11-23621266 enquiry@Intindia.co.in www.lntindia.co.in

Luoyang Goldeng Slewing Ring Co.,Ltd LUOYANG DONGMAGOU INDUSTRIAL AREA LUOYANG HENAN 471600, CHINA

Phone: (86) 379-68626962 Fax: (86) 379-64873963 lygoldeng4@slewingring.net www.slewingring.net/

LYC North America Inc 2600 KESLINGER ROAD UNIT H GENEVA, IL 60134 Phone: (630) 262-0601 sales@lycbearings.com lycbearings.com

Mach III Clutch Inc. 101 CUMMINGS DRIVE WALTON, KY 41094 Phone: 859-291-0849 info@machiii.com www.machiii.com

**Magnetic Sensors Corporation** 

1365 N MCCAN STREE ANAHEIM, CA 92806 Phone: (714) 630-8380 bhilborn@magsensors.com www.magsensors.com

Magnetic Technologies Ltd P.O. BOX 257

43 TOWN FOREST RD OXFORD, MA 01540 Phone: (508) 987-3303 Fax: (508) 987-2875 sales@magnetictech.com www.magnetictech.com

Magnum Manufacturing

39140 WEBB DRIVE WESTLAND, MI 48185 Phone: (734) 727-0560 sales\_info@magnum-mfg.com magnum-mfg.com

Magtrol, Inc. 70 GARDENVILLE PARKWAY BUFFALO, NY 14224 Phone: (716) 668-5555 Fax: (716) 668-8705 magtrol@magtrol.com www.magtrol.com

Maguire Technologies 71 FERRY ROAD SALISBURY, MA 01952 Phone: (978) 462-0701 Fax: (978) 463-3708 cdsm1@verizon.net www.maguiretech.com

**Marc Industries** 

130 J.P. TOWER, TAGORE ROAD, RAJKOT RAJKOT GUJARAT 360002, INDIA Phone: +(91) 281-2483151 Fax: +(91) 281-2464814 marcind@rediffmail.com www.marcbearings.com

Marine Specialties, Inc. 1903 COTEAU ROAD HOUMA LA 70364

Phone: (985) 580-1672 Fax: (985) 580-1616 chris@marinespecialties-inc.com

www.marinespecialties-inc.com

**Mark Elektriks** 

15, GULTEKDI INDUSTRIAL ESTATE PUNE MAHARASHTRA 411037, INDIA Phone: +(91) 20 66016312 Fax: +(91) 20 66016311 markelektriks@vsnl.net www.markelektriks.com

Marland Clutch

449 GARDNER ST. SOUTH BELOIT, IL 61080 Phone: 630-455-1752 Fax: 630-455-1794 info@marland.com www.marland.com

Marples Gears, Inc.

728 W. SANTA ANITA STREET SAN GABRIEL, CA 91776 Phone: (800) 276-GEAR Fax: (626) 570-9286 info@marplesgears.com www.marplesgears.com

Marshall Wolf Automation Inc.

923 SOUTH MAIN STREET ALGONQUIN, IL 60102 Phone: (847) 658-8130 sales@wolfautomation.com www.wolfautomation.com

Marswell Engineering Ltd. 2/F., BLOCK C, WANG YIP CENTRE, 18 WANG YIP STREET EAST, YUEN LONG, NEW TERRITORIES HONG KONG

Phone: +(852) 2557 9635 Fax: +(852) 2897 5690 enquiry@marswell.com www.marswell.com

Martin Sprocket & Gear 3100 SPROCKET DRIVE ARLINGTON, TX 76015 Phone: (817) 258-3000 Fax: (817) 258-3333 mail@martinsprocket.com www.martinsprocket.com

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HACKENSACK, NJ 07601 Phone: (201) 343-8983 Fax: (201) 343-2132 main@masterbond.com www.masterbond.com

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201 W. MCBEE AVE SUITE 303 GREENVILLE, SC 29601 Phone: (864) 312-5102 Fax: (864) 312-5119 info@master-pt.com www.master-pt.com

Matrix International

EAST MILL RD. BRECHIN ANGUS DD9 7EP UNITED KINGDOM Phone: +(44) 1356602000 sales@matrix-international.com www.matrix-international.com

Maurey Manufacturing Corporation 410 INDUSTRIAL PARK DRIVE

HOLLY SPRINGS MS 38635 Phone: (800) 284-2161 Fax: (662) 252-6364 chuckl@maurey.com www.maurey.com

MAV S.p.A. VIA VENEZIA 12 BOSENTINO TRENTINO 38040 Phone: +(39) 0461845151 Fax: +(39) 0461845150

info@mav.it www.mav.it

Mavilor Motors, S.a. C/EMPORDA 11-13

SANTA PERPETUA DE MOGODA BARCELONA E-08980 SPAIN Phone: +(34) 935 743 690 Fax: +(34) 935 743 570 mavilor@mavilor.es www.mavilor.es

**Maxon Precision Motors Inc** 101 WALDRON RD

FALL RIVER, MA 02720 Phone: (508) 677-0520 Fax: (508) 677-0530 info@maxonmotorusa.com www.maxonmotorusa.com

Mayr Corp. 4 NORTH STREET WALDWICK, NJ 07463 Phone: (201) 445-7210 Fax: (201) 445-8019 info@mayrcorp.com www.mayrcorp.com

McInnes Rolled Rings 1533 EAST 12TH STREET ERIE, PA 16511 Phone: (814) 459-4495 Fax: (814) 459-8443 sales@mcrings.com www.mcinnesrolledrings.com

Means Industries, Inc. 3715 E. WASHINGTON RD. SAGINAW, MI 48601

Phone: (989) 754-1433 Fax: (989) 771-3396 info@meansindustries.com www.meansindustries.com

Measurement Specialties 1000 LUCAS WAY HAMPTON, VA 23666 Phone: (757) 766-1500 Fax: (757) 766-4297 www.meas-spec.com

MECA & Technology Machine Inc. 1281 PARKVIEW ROAD GREEN BAY, WI 54304

Phone: (920) 336-7382 Fax: (920) 336-2983 sales@mecagb.com www.mecagb.com

Mechanical Drives & Belting 2915 E. WASHINGTON BLVD.

LOS ANGELES, CA 90023 Phone: (800) 464-2358 sales@mechdrives.com www.mechdrives.com

Mechanical Power Inc. 135 KERRY LANE WAUCONDA, IL 60084 Phone: (800) 695-6767 Fax: (847) 487-0080 mpi@mechanicalpower.net www.mechanicalpower.net

Merit Gear Corp. 810 HUDSON STREET ANTIGO, WI 54409 Phone: (715) 623-2307 Fax: (715) 627-2558 larry.steffens@meritgear.com www.meritgear.com

MGT - Magnetic Gearing & Turbine Corp. P.O. BOX 51 KARUAH NSW 2324 AUSTRALIA Phone: +(61) 2 49 973 452 Fax: +(61) 2 49 973 073 sales@mgt.com.au www.mgt.com.au

Mico Incorporated 1911 LEE BOULEVARD NORTH MANKATO, MN 56003 Phone: (507) 625-6426 Fax: (507) 625-3212 micomail@mico.com www.mico.com

Micro Ingranaggi Standard sas VIA DEL COMMERCIO, 29 BUCCINASCO MILANO 20090 Phone: +(39) 0248-401-364 Fax: +(39) 0248-403-899 microingranaggi@mdsnet.it www.microingranaggi.it

Midwest Brake

26255 GROESBECK HWY WARREN, MI 48089 Phone: (586) 775-3000 Fax: (586) 775-3040 sales@midwestbrake.com www.midwestbrake.com

Midwest Gear & Tool, Inc.

15700 COMMON RD. ROSEVILLE, MI 48066 Phone: 586-779-1300 Fax: 586-779-6790 midwestgear@sbcglobal.net www.powertransmission.com/cop-

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**Midwest Motion Products** 10761 AHERN AVE SE WATERTOWN, MN 55388 Phone: (952) 955-2626 Fax: (480) 247-4096 sales@midwestmotion.com www.midwestmotion.com

Mijno Precision Gearing

406 N. PROSPECT AVE PARK RIDGE, IL 60068 Phone: (847) 698-9041 Fax: (847) 698-9040 mijno@aol.com www.mijno.com

Milltex Engineering Company B 18/39 , JATPURA , NEAR BUS STAND KAPURTHALA PUNJAB 144601, INDIA Phone: +(91) 1822-309829 Fax: +(91) 1822-232909 milltex@rediffmail.com www.beltingworld.com

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www.milwaukeegear.com

Ming Chang Traffic Parts Mfg. NO. 13 INDUSTRY 4TH ROAD, INDUSTRY DIST. PING TUNG CITY, TAIWAN PING TUNG TAIWAN 900, TAIWAN Phone: +(886) 87228056 Fax: +(886) 87229920 mccchain@ms15.hinet.net www.mccchain.com.tw

Mini Gears (Stockport) Ltd.

INI GEATS (STOCKPORT) LTG.
TOP GEAR HOUSE
BLETCHLEY ROAD
HEATON MERSEY INDUSTRIAL ESTATE
STOCKPORT SK4 3ED
UNITED KINGDOM
Phone: +(44) 161 432 0222
Fax: +(44) 161 432 0444 enquiries@minigears.co.uk www.minigears.co.uk

Mini-Broach Machine Company 1266 MAIN STREET

P.O. BOX 129 ASHBY, MA 01431 Phone: (978) 386-7959 minib@net1plus.com www.minibroach.com

Minsk Gear Works UL. DOLGOBRODSKAYA, 17

www.mgw.by

220038, MINSK BELARÚS MINSK BELARUS **BELARUS** Phone: +(375) 172 35 52-11 Fax: + (375) 172 30 22 22 mgw@mail.ru

Mitsubishi Electric Automation, Inc. 500 CORPORATE WOODS PARKWAY VERNON HILLS, IL 60061 Phone: (847) 478-2100 Fax: (847) 478-2396 marcomm@meau.com

www.meau.com

MMB Bearing Co. Inc. 163 ROLLING HILL ROAD MOORESVILLE NC 28117 Phone: (800) 526-2353 Fax: (888) 999-9017 sales@mmbbearings.com www.mmbbearings.com

Modern Linear Inc. PO BOX 186 CORTE MADERA, CA 94976 Phone: (415) 924-7938 Fax: (415) 927-2360 info@modernlinear.com www.modernlinear.com

Moore Gear & Mfg. Co., Inc.

#2 HAWTHORNE DRIVE P.O. BOX 49 HERMANN, MO 65041 Phone: (573) 486-5415 Fax: (573) 486-3487 info@mooregear.com www.mooregear.com

**Motion Industries** 

1605 ALTON RD BIRMINGHAM AL 35210 Phone: (800) 526-9328 Fax: (205) 957-5290 www.motionindustries.com

Moventas Ltd.
P.O. BOX 20100
1615 BISHOP STREET NORTH
CAMBRIDGE ONTARIO N1R 8C8, CANADA Phone: (519) 621-6390 Fax: (519) 621-7660 clay.williams@moventas.com www.moventas.com

MROSupply
2915 EAST WASHINGTON BLVD.
LOS ANGELES, CA 90023 Phone: (888) 671-2883 Fax: (888) 671-3319 kievforyou@gmail.com www.mrosupply.com

MT Tool & Manufacturing 1118 LUNT AVENUE SCHAUMBURG, IL 60193 Phone: (847) 985-6211 tom@mttoolinc.com www.ourmachinist.com

MultiProducts Company Inc.

5301 21ST STREET RACINE, WI 53406 Phone: (877) 444-1011 Fax: (262) 554-3711 www.multiproducts.com

**NAC Harmonic Drive** 

4720 SALISBURY ROAD JACKSONVILLE, FL 32256 Phone: (904) 493-6496 Fax: (904) 339-9241 info@nacharmonicdrive.com www.nacharmonicdrive.com

Nachi America Inc. 715 PUSHVILLE ROAD GREENWOOD, IN 46143 Phone: (317) 535-5527 Fax: (317) 535-3659 pjamerson@nachiamerica.com www.nachiamerica.com

#### NAMCO

9168 - 35 AVE. EDMONTON AB T6E 6N9, CANADA Phone: (780) 463-5602 info@namco.ca www.namco.ca

#### Nanjing Cyd Precision Mach. Manu. & Sales Cent

4-304, 169 QIQINGMEN STR., NANJING, 210017, CHINA NANJING JIANGSÚ 210017, CHINA Phone: +(86) 139 139 75656 Fax: +(86) 25 86413490 wangjia@cydgears.com.cn www.cydgears.com.cn

## Nanjing Excellence Industrial Co., Ltd. 67 DAGUANG ROAD NANJING JIANGSU 210001, CHINA

Phone: +(86) 25-84601675 Fax: +(86) 25-84605330 nancy@excel-ind.com www.excel-ind.com

#### Nav Auxichem Pvt. Ltd

158 LEATHER COMPLEX JALANDHAR PUNJAB 144021, INDIA Phone: +(91) 181-2650616 Fax: +(91) 181-2650109 navauxichem@vsnl.net www.perfectbelting.com

Navyug Electric Motors & Pumps Ltd #4, PH II, GIDC, VATVA, AHMEDABAD, GUJARAT, INDIA AHMEDABAD GUJARAT 382445, INDIA Phone: +(91) 79 65230103 Fax: +(91) 79 25893435 sales@navyugelectricmotors.com www.navyugelectricmotors.com

#### NDE Power Transmissions

NDE BUILDINGS, ALDBOURNE ROAD WORKS, COVENTRY CV1 4EQ UNITED KINGDOM Phone: +(44) 2476 222272 sales@ndepower.com www.ndepower.com

Neelkanth Beltings D-94, SPORTS & SURGICAL GOODS COMPLEX, KAPURTHALA ROAD JALANDHAR PUNJAB 144 021, INDIA Phone: +(91) 181 2650862 Fax: +(91) 181 2650625 info@neelkanthbeltings.com www.neelkanthbeltings.com

Netshape Technologies, Inc. 8751 OLD STATE ROAD 60 SELLERSBURG, IN 47172 Phone: (812) 248-9273 solutions@netshapetech.com www.netshapetech.com

#### New Allenberry Works (Deepak Industries Ltd.)

14/7, MATHURA ROAD FARIDABAD FARIDABAD HARYANA 121003, INDIA Phone: +(91) 129-6451260 Fax: +(91) 129-2275525 gj@nawgears.com www.allenberrygears.com

## **New England Belting Company**

27 MILL STREET BERLIN, CT 06037 Phone: (860) 828-4444 Fax: (860) 828-4525 info@newenglandbelting.com www.newenglandbelting.com

#### New Power Electric (USA) LLC 726 S, CASINO CENTER BLVD. #207 LAS VEGAS, NV 89101-6743

Phone: (626) 616-8999 Fax: (626) 616-8999 service@usa-newpower.com www.usa-newpower.com

New Torque, Inc. 4909 11TH AVE. S. MINNEAPOLIS, MN 55417 Phone: (800) 966-8325 shotton@clutches-brakes.com www.clutches-brakes.com

## **Nexen Group Inc**

560 OAK GROVE PARKWAY VADNAIS HEIGHTS, MN 55127 Phone: (800) 843-7445 Fax: (651) 286-1099 info@nexengroup.com www.nexengroup.com

### **Ngt Specialty Valves**

P.O BOX 5223 ELM GROVE, WI 53122 Phone: (262) 782-6125 contact@ngtvalves.com www.ngtvalves.com

Niagara Gear Corp. 941 MILITARY ROAD BUFFALO, NY 14217-2590 Phone: (716) 874-3131 Fax: (716) 874-9003 info@niagaragear.com www.niagaragear.com

#### **Niebuhr Gears**

LA COURSVEJ 8 **IKAST 7430** DENMARK

Phone: +(45) 96605050 rni@niebuhr.dk www.niebuhr.dk

#### Nissei Corporation of America

11107-J SOUTH COMMERCE BLVD. CHARLOTTE NC 28273 Phone: (704) 583-0008 Fax: (704) 504-0608 gearsales@nissei-usa.com www.nissei-usa.com

#### NKE Austria GmbH

ENNSER STRASSE 41A STEYR-GLEINK UPPER AUSTRIA A4407 ALISTRIA Phone: +(43) 7252 86667 Fax: +(43) 7252 86667-59 office@nke.at www.nke.at

#### Nord Gear Corp.

PO BOX 367 WAUNAKEE, WI 53597 Phone: (888) 314-6673 Fax: (800) 373-6673 info.us@nord.com www.nord.com

Nordex Inc. 426 FEDERAL ROAD BROOKFIELD, CT 06804 Phone: (203) 775-4877 Fax: (203) 775-6552 info@nordex.com www.nordex.com

#### North American Clutch & Driveline

P.O. BOX 15130 ROCKFORD, IL 61115 Phone: (815) 282-7960 Fax: (815) 282-9160 sales@naclutch.com www.naclutch.com

#### North American Clutch Corp. (NORAM)

4360 N. GREEN BAY AVE. P.O. 090228 MILWAUKEE, WI 53209 Phone: (866) 337-5906 Fax: (414) 267-4024 jeffh@noram-clutch.com www.noram-clutch.com

Northern Tool and Gear Co. Ltd. JOHN STREET WEST ARBROATH ANGUS DD11 1RT UNITED KINGDOM

Phone: +(44) 1241-872-626 Fax: +(44) 1241-873-636 amassie@ntgear.co.uk www.ntgear.co.uk

## **Norwin Electronics Limited**

UNIT 6 STATION ROAD SANDY BEDFORD SG19 3HB UNITED KINGDOM

Phone: +(44) 1767 651485 sales@norwin.co.uk www.norwin.co.uk

#### **Novotec Argentina SRL**

AV. VELEŽ SARFIELD 1560 CAPITAL FEDERAL BUENOS AIRES 1285 ARGENTINA Phone: +(54) 11-4303-8989

Fax: +(54) 11-4032-0184 info@novotecargentina.com www.novotecargentina.com

Nu-teck Couplings Pvt. Ltd. B-1,C13 BHOSARI INDUSTRIAL ESTATE PUNE MAHARASHTRA 411026, INDIA Phone: +(91) 20 27120103 info@nuteckcouplings.com www.nuteckcouplings.com

# NUM Corp. - Schneider Electric 603 E. DIEHL RD., SUITE 115 NAPERVILLE, IL 60563 Phone: (630) 505-7722

Fax: (630) 505-7754 sales@num-usa.com www.num-usa.com

#### **Nuttall Gear**

2221 NIAGARA FALLS BLVD. NIAGARA FALLS, NY 14302 Phone: (716) 731-5180 Fax: (716) 731-9329 info@nuttallgear.com www.nuttallgear.com

#### **OEM International Inc.**

575 ROUTE 73 NORTH BUILDING B-3 WEST BERLIN, NJ 08091 Phone: (800) 636-2329 Fax: (856) 768-8717 sales@oeminternational.com www.oeminternational.com

#### **OEP Couplings, a Division of Oren Elliott Products**

128 W VINE STREET P.O. BOX 638 EDGERTON, OH 43517 Phone: (419) 298-2306 Fax: (419) 298-3545 sales@oepcouplings.com www.oepcouplings.com

#### **Oerlikon Fairfield**

US 52 SOUTH P.O. BOX 7940 LAFAYETTE, IN 47903-7940 Phone: (765) 772-4000 Fax: (765) 772-4001 Marketing@fairfieldmfg.com www.oerlikon.com/fairfield

#### Oerlikon Graziano SpA VIA CUMIANA 14

10098 RIVOLI TORINO ITALY

Phone: +(39) 011 96701 Fax: +(39) 011 9594803 www.oerlikon.com/graziano

Ogura Industrial Corp. P.O. BOX 5790 SOMERSET, NJ 08875-5790 Phone: (732) 271-7361 Fax: (732) 271-7580 oguranj@ogura-clutch.com www.ogura-clutch.com

#### Omni Gear & Machine Corp.

90 BISSEL STREET JOLIET, IL 60432-3052 Phone: (800) 876-7216 Fax: (815) 723-9207 info@omnigear.us www.omnigear.us

#### Ondrives Ltd

FOXWOOD IND PK FOXWOOD ROAD CHESTERFIELD DERBYSHIRE S41 9RN UNITED KINGDOM Phone: +44 1246 455500 Fax: +44 1246 455522 sales@ondrives.com www.ondrives.com

Ongears - Ondrives Export Gears FOXWOOD IND PK FOXWOOD ROAD CHESTERFIELD DERBYSHIRE S41 9RN UNITED KINGDOM Phone: +(44) 1246 455500 Fax: +(44) 1246 455522 sales@ondrives.com www.ongears.co.uk

Ontario Drive & Gear Ltd. 3551 BLEAMS ROAD P**59** NEW HAMBURG ONTARIO N3A 2J1, CANADA Phone: (519) 662-2840 Fax: (519) 662-2127 info@odg.com www.odg.com

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Power Transmission Engineers
I - 31, MAHALAXMI APARTMENTS MUKTANAND, KARELIBAG BARODA GUJARAT 390018, INDIA Phone: +(91) 265 2462258 Fax: +(91) 265 2462258 info@ptegears.com ptegears.com

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Fax: (262) 542-1592
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4701 NIMTZ PARKWAY SOUTH BEND, IN 46628-6151 Phone: 574-234-4116 Fax: 574-239-2158 pshah@schafergear.com www.schafergear.com

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MADISON, NJ 07940 Phone: (973) 884-1755 sales@sensorprod.com www.sensorprod.com

Sensor Technology Ltd.

APOLLO PARK IRONSTONE LÂNE, WROXTON, BANBURY OXFORDSHIRE 0X15 6AY UNITED KINGDOM Phone: +(44) 0-1869-238400

Fax: +(44) 0-1869-238401 www.sensors.co.uk

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Shivam Autotech Ltd.

303, 3RD FOOR, SQUARE ONE, SAKET NEW DELHI 110017, INDIA Phone: +(91) 01149242100 admn@shivamautotech.com www.shivamautotech.com

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MADHAVPURI HILLS, ROAD NO.3 CHANDANAGAR HYDERABAD ANDHRA PRADESH 500 050,

Phone: +(40) 64563771 skgupta@skgsons.com www.skgsons.com

Smalley Steel Ring Company 555 OAKWOOD ROAD LAKE ZURICH, IL 60047

Phone: 847-719-5900 Fax: 847-719-5999 info@smalley.com www.smalley.com

Smart Manufacturing Technology - SMT

CHARTWELL HOUSE 67-69 HOUNDS GATE NOTTINGHAM NG1 6BB UNITED KINGDOM Phone: +(44) 115 941 9839 Fax: +(44) 115 958 1583 info@smartmt.com www.smartmt.com

SmartMotor AS JARLEVEIEN 8 TRONDHEIM NORWAY 7041 NORWAY Phone: +(47) 73982500 Fax: +(47)73982501 mail@smartmotor.no www.smartmotor.no

SMMA - The Motor and Motion Association

POST OFFICE BOX P182 S. DARTMOUTH, MA 02748 Phone: (508) 979-5935 Fax: (508) 979-5845 info@smma.org www.smma.org

Sokhi Heli-Wom Gears Pvt. Ltd. 61/22 SITE-4 SAHIABABAD INDUSTRIAL AREA GHAZIABAD U.P 201010, INDIA Phone: +(91) 01204344400 Fax: +(91) 01204168468 sokhi@gearboxindia.com www.gearboxindia.com

Sond Gears Pvt. Ltd. 27-R INDUSTRIAL AREA B LUDHIANA PUNJAB 141003, INDIA Phone: +(91) 1612-531218/532135 Fax: +(91) 1612-532715/534313 info@sondgears.com www.sondgears.com

Source Engineering Inc. 3283-H DE LA CRUZ BLVD SANTA CLARA, CA 95054 Phone: (408) 980-9822 Fax: (408) 980-1860 rick@sei-automation.com www.sei-automation.com

South Bend Gear LLC

3801 SCHAFER GEAR DRIVE SOUTH BEND, IN 46628 Phone: 574-968-0273 Fax: 574-239-2158 pmorrison@southbendgear.com www.southbendgear.com

Southern Gear & Machine Inc. 3685 NW 106TH STREET MIAMI, FL 33147-1030

Phone: (305) 691-6300 allanarch@southerngear.net www.southerngear.net

Specialty Motions, Inc. 1801 RAILROAD ST. CORONA, CA 92880 Phone: (800) 283-3411 sales@smi4motion.com www.smi4motion.com

Spinea

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OKRAJOVA 33 PRESOV 08001 SLOVAKIA

Phone: +(421) 905570006 info@spinea.sk www.spinea.sk

Spline Gauges PICCADILLY

TAMWORTH STAFFORDSHIRE B78 2ER UNITED KINGDOM Phone: +(44) 1827 872771

sales@splinegauges.co.uk www.splinegauges.co.uk

**SPN Schwaben Praezision** 

GLASHUETTER STR. 2-6 NOERDLINGEN GERMANY 86720 **GFRMANY** 

Phone: +(49) 9081-214-0 Fax: +(49) 9081-214-111 info@spn-hopf.de www.spn-hopf.de/index. php?lang=en

Sprint Electric Ltd.

UNIT C2

RUDFORD INDUSTRIAL ESTATE

ARUNDEL WEST SUSSEX BN18 OBD UNITED KINGDOM

Phone: +(44) 1243 558080 Fax: +(44) 1243 558099 info@sprint-electric.com www.sprint-electric.com

Sprockets Australia Pty. Ltd. PO BOX 114

YARRAVILLE MELBOURNE VIC 3013 AUSTRALIA Phone: +(61) 3-9687 8177 Fax: +(61) 3-9687 8035

sales@sprocketsoz.com.au sprocketsoz.com.au

SRG Bearings International Ltd. ROOM1012, TAK HAY BLDG, TAK CHEONG STREET, YAU TSIM HONG KONG 241000 HONG KONG Phone: +(852) 30756210

Fax: +(852) 31828510 sales@srg-bearings.com www.srg-bearings.com

SSJ Italy VIA PASTEUR 16/10 REGIO EMILIA RE 42100

> Phone: +(39) 0522 552 237 Fax: +(39) 0522 552 237 sales@ssjitaly.com www.ssjitaly.com

SSS Clutch Co.

610 WEST BASIN ROAD NEW CASTLE DE 19720 Phone: (302) 322-8080 Fax: (302) 322-8548 engineering@sssclutch.com www.sssclutch.com

ST Gear & Machine LLC 5304 HOPE LANE HOUSE SPRINGS, MO 63051 Phone: (636) 677-5552 Fax: (636) 677-3652 tim@stgearandmachine.com www.stgearandmachine.com

Stafford Manufacturing Corp.

PO BOX 277 NORTH READING, MA 01864 Phone: (800) 695-5551 Fax: (800) 649-5101 sales@staffordmfg.com www.staffordmfg.com

**Standard Machine** 

868-60TH STREET EAST SASKATOON SK S7K 8G8, CANADA Phone: (306) 931-3343 Fax: (306) 931-4741 info@hamiltongear.com www.hamiltongear.com

Star Gears

503 SOHAM VASANT COMPLEX MAHAVIR NAGAR KANDIVALI - WEST MUMBAI MAHARASTRA 400067, INDIA Phone: +(91) 9920790777 stargears@gmail.com www.stargears.in

STD Precision Gear and Instrument

318 MANLEY STREET SUITE #5 WEST BRIDGEWATER, MA 02379 Phone: (508) 580-0035 Fax: (508) 580-0071 www.stdgear.com

Stearns Division / Rexnord Industries Inc. 5150 S. INTERNATIONAL DRIVE

CUDAHY, WI 53110 Phone: (414) 272-1100 Fax: (414) 277-4364

raymond.mazurek@rexnord.com stearns.rexnord.com

Steelmans Broaches Pvt Ltd 183 AJIT NAGAR PATIALA PUNJAB 147001, INDIA Phone: +(91) 175-2218031 Fax: +(91) 175-2212963 info@steelmans.com www.steelmans.com

Steinmeyer Inc.

56 MIÓDLESEX TURNPIKE SUITE 200 BURLINGTON, MA 01803 Phone: (781) 273-6220 Fax: (781) 273-6602 jskaltsas@steinmeyer.com www.steinmeyer.com

Stellar Technology, Inc. 237 COMMERCE DRIVE AMHERST, NY 14228

Phone: (716) 250-1900 sales@stellartech.com www.stellartech.com

**Stephenson Gobin Transmissions** 

HIGH ETHERLEY BISHOP AUCKLAND COUNTY DURHAM DL14 OHY UNITED KINGDOM

Phone: +(44) 1388832252 enquiries@stephensongobin.com www.stephensongobin.com

Sterling Instrument

2101 JERICHO TURNPIKE NEW HYDE PARK, NY 11040 Phone: 516-328-3300 Fax: 516-326-8827 sdp-sisupport@sdp-si.com www.sdp-si.com

Stieber Clutch

HATSCHEKSTR 36 HEIDELBERG 69126 GERMANY Phone: 49(0)62213047.0

Fax: 49(0)6221304731 sales@stieber.de www.stieber.de

**Stock Drive Products** 

2101 JERICHO TURNPIKE NEW HYDE PARK, NY 11040 Phone: (516) 328-3300 Fax: (516) 326-8827 sdp-sisupport@sdp-si.com www.sdp-si.com

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4200 HOLLAND BOULEVARD CHESAPEAKE, VA 23323 Phone: (757) 485-3355 Fax: (757) 487-3193 customercare@suminet.com

www.smcyclo.com

Supreme Gear Co.

17430 MALYN BLVD. FRASER, MI 48082 Phone: (586) 294-7625 Fax: (586) 294-7648 info@supremegear.com www.supremegear.com

Suzhou Asia Pacific Metal Co., Ltd.

NO.4 XINGWANG ROAD SUZHOU JIANGSU 215132, CHINA Phone: +(86) 136-16204136 Fax: +(86) 512-88186188 sales@szapmc.com www.szapmc.com

SYX Bearing ROOM 907 NO. 350 SOUTH SHANXI RD. SHANGHAI 200001, CHINA Phone: +(86) 21-63517217 export@syxbearing.com www.syxbearing.com

T.E.A. Machine Components

2281 F DABNEY RD. RICHMOND, VA 23139 Phone: (804) 342-0004 Fax: (804) 342-0006 sales@teausa.net www.teausa.net

Taiwan Precision Gear Corp. NO. 136-2, ALLEY 5, LANE 123, SHOU PI FENG YUENG CITY TAICHUNG 420, TAIWAN Phone: 886-4-25351329 Fax: 886-425351467 tpgcorp@ms13.hinet.net www.tpg-tw.com

Taiwan United Gear Co., Ltd. NO.7-1, LN. 1156, NANQING RD., LUZHU TOWNSHIP, TAOYUAN COUNTY 338, TAIWAN Phone: +(886) 3-352-0605 Fax: +(886) 3-321-7598 sales@tugc.com.tw tugear.com.tw/about-us.php

Taizhou Heri Autoparts Co. Ltd. ROOM 1707, NO 127 CHANGSHOU ROAD SHANGHAI 200060, CHINA Phone: +(86) 21 62773282 Fax: +(86) 21 62773283 office@heri-sh.com www.heri.net.cn

**Tapeswitch Corporation** 100 SCHMITT BLVD

FARMINGDALE, NY 11735 Phone: (800) 234-8273 Fax: (631) 630-0442 marketing@tapeswitch.com www.tapeswitch.com

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440 NORTH FIFTH AVE. CHAMBERSBURG, PA 17201 Phone: 8888296637 Fax: 7172646420 info@tbwoods.com www.tbwoods.com

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18880 DAN STREET DETROIT LAKES, MN 56501 Phone: (218) 847-9582 Fax: (218) 847-1052 info@team-ind.com www.team-ind.com

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766 NORTH RIVER RD. WARREN, OH 44483 Phone: 330-847-7000 sales@technico.com www.technico.com

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TWENTEPOORT WEST 15 ALMELO OV 7600 AA NETHERLANDS Phone: 0031 546 536300 Fax: 0031 546 536310 sales@tecnotion.com www.tecnotion.com

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5100 NORTH IH-35 ROUND ROCK, TX 78681 Phone: (404) 229-8738 Fax: (512) 248-5617 sales@tecowestinghouse.com www.tecowestinghouse.com

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9812 WHITHORN DR. HOUSTON, TX 77095 Phone: (281) 855-2218 Fax: (281) 859-8825 motors@telcointercon.com www.telcointercon.com

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SHANGHAI 200241, CHINA Phone: +(86) 021-61517512 Fax: +(86) 021-61212665 thb-cathy@thb-bearings.com www.thb-bearings.com

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Toffac Ingranaggi S.p.A. VIA VITTORIO VENETO, 113/115 PIOVE DI SACCO PADOVA 35028

Phone: +(39) 0499-700-188 Fax: +(39) 0495-841-907 sales@toffac.com www.toffac.com

Toledo Gearmotor A Bluffton Motor Works

Company 5439 ROAN ROAD SYLVANIA, 0H 43560 Phone: (800) 488-7072 Fax: (419) 885-3799

customerservice@toledogear.com www.toledogear.com

Tolomatic, Inc. 3800 COUNTY ROAD 116 HAMEL, MN 55340 Phone: 800-328-2174 Fax: 763-478-8080 sales@tolomatic.com www.tolomatic.com

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C-36 FOCAL POINT PATIALA PUNJAB 147003, INDIA Phone: +(91) 175-2232808 Fax: +(91) 175-5001405 toolmasters@gmail.com www.tool-masters.com

#### Top Machinery & Equipment (Zhengzhou) Ltd

10-1509#, 73 WEILAI ROAD, ZHENGZHOU HENAN 450008, CHINA Phone: +(86) 371 65523361 Fax: +(86) 371 65614031 export@top-rol.com www.top-rol.com

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VIA BIZZARRI 6 CALDERARA DI RENO BOLOGNA 40012 Phone: +(39) 0517-289-35 Fax: +(39) 0517-289-37 tramec@tramec.it www.tramec.it

Transmission Machinery Co. Ltd.
NO. 1-6, SHYHHORNG NEWVILLAGE, HSIAO

SHAN HUA CHENG TAINAN 741, TAIWAN Phone: +(886) 6 5831177 transtec@seed.net.tw www.transcyko-transtec.com

Transmotec AB

POLYGONVÄGEN 49 187 66 STOCKHOLM SWEDEN Phone: +(46) 8 792 35 30 Fax: +(46) 8 792 35 20 inquiry@transmotec.com www.transmotec.com

Transply Inc. P.O. BOX 7727

YORK, PA 17404 Phone: (717) 767-1005 Fax: (717) 767-9410 sales@transply.com www.transply.com

Triumph Gear Systems - ACR Industries 15375 23 MILE ROAD MACOMB, MI 48042-4000 Phone: (586) 781-2800 Fax: 586-677-8134 solutions@triumphgroup.com www.triumphgroup.com

Trojon Gear Inc. 418 SAN JOSE STREET DAYTON, OH 45403 Phone: (937) 254-1737 Fax: (937) 254-3029 timwhite@trojon-gear.com www.trojon-gear.com

TSS Rotterdam B.V.

P.O. BOX 12012 ROTTERDAM 3004 GA THE NETHERLANDS Phone: +(31) 10 4624500 Fax: +(31) 10 4626240 info@tssr.nl www.tssr.nl/products/item230

Tsubaki of Canada Limited 1630 DREW ROAD MISSISSAUGA ON L5S 1J6, CANADA Phone: (905) 676-0400 Fax: (905) 676-0904 agawaran@tsubaki.ca www.tsubaki.ca

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1-1-3, KANNABIDAI KYOTANABE KY0T0 610-0380 **JAPAN** Phone: +(81) 774-64-5023 Fax: +(81) 774-64-5212 pt.com@tsubakimoto.com

tsubakimoto.com

Turbo Power

116 CANAL DRIVE FRIENDSWOOD TEXAS 77546 Phone: (281) 585-5635 Fax: (309) 213-0126 turbopower@houston.rr.com www.turbopower.info

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Twiflex Limited

104 THE GREEN TWICKENHAM MIDDLESEX TW12 5AQ - UK UNITED KINGDOM Phone: 442088941161 Fax: 442088946056

sales@twiflex.com www.twiflex.com

U.S. Gear

9420 STONY ISLAND AVE. CHICAGO, IL 60617 Phone: (773) 375-4900 Fax: (773) 375-4557 usgear@flash.net www.usgear.com

U.S. Tsubaki Power Transmission, LLC

301 EAST MARQUARDT DRIVE WHEELING, IL 60090 Phone: (847) 459-9500 Fax: (847) 459-9520 tiffanydelahanty@ustsubaki.com www.ustsubaki.com

Ultra Motion

22355 ROUTE 48, #21 CUTCHOGUE, NY 11935 Phone: (631) 298 9179 Fax: (631) 298 6593 info@ultramotion.com www.ultramotion.com

Unigear Industries 20375 CLARK GRAHAM BAIE D'URFE QUEBEC H9X 3T5, CANADA Phone: (514) 457-7700 roberth@unigear.com www.unigear.com

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NR. KUVADAVA ROAD, 1ST FLOOR,
RAJKOT GUJARAT 360003, INDIA
Phone: +(91) 281 2450300 Fax: +(91) 281 2450300 unisoftp@gmail.com www.taperlockpulley.com

United Gear & Assembly Inc.

1700 LIVINGSTONE ROAD HUDSON, WI 54016 Phone: (715) 386-5867 Fax: (715) 386-6473 sales@ugaco.com www.ugaco.com

V2 Engineering Systems 45, 3RD MAIN, MARUTHI LAYOUT, VASAN-THAPURA, BANGALORE KARNATAKA 560061, INDIA Phone: +(91) 8032471858

engineering@v2engineeringsystems.com

www.v2engineeringsystems.com

Valley Gear & Machine Inc. 514 CHICKORY STREET

BAD AXE, MI 48413 Phone: (888) 269-8177 Fax: (989) 269-7686 vgear@avci.net www.valley-gear.com

Vardhman Bearings D-103 VASANT AISHVARYA MATHURADS EXTENSION ROAD KANDIVLI MUMBAI MAHARSHTRA 400067, INDIA Phone: +(91) 22-28627454 Fax: +(91) 22-28634892 vardhmanbearings@123india.com www.vardhmanbearings.com

VCST LP

INDUSTRIEZONE SCHURHOVENVELD 3025 3800 ST.-TRUIDEN SINT-TRUIDEN LIMBURG 3800 **BFI GIUM** Phone: +(32) 11 67 02 11 Fax: +32) 11 67 05 62 krispeetermans@vcst.be www.vcst.be

**Venture Products International** 

27 MULVANEY STREET **ASHEVILLE NC 28803** Phone: (828) 285-0495 info@ventureproducts.com www.ventureproducts.com

VFFS Services, Inc. 2206 N. MAIN STREET SUITE 280 WHEATON, IL 60187 Phone: (630) 660-9650 www.bervina.com

Vibracoustics Ltd UNIT 1 BROOK HOUSE

**CROSS STREET** SYSTON LEICESTER LEICESTERSHIRE LE7 2JG UNITED KINGDOM Phone: +44 (0) 116 2605700 Fax: +44 (0) 116 2605707 mail@vibracoustics.com www.vibracoustics.com

Vision International

127-227, KARMA ESTATE, NR.TRIKAMPURA PATIA, GIDC VATVA. AHMEDABAD GUJARAT 382445, INDIA Phone: +(91) 9374160151 Fax: +(91) 7940084543 netexim@gmail.com www.engimech.com

Vision Quality Components, Inc. 1433 INDUSTRIAL PARK ROAD CLEARFIELD, PA 16830

Phone: (614) 833-4489 Fax: (614) 837-9549 ernie@visionqci.com www.visionaci.com

VL Motion Systems Inc. 2316 DELAWARE AVE. #229 BUFFALO, NY 14216-2687 Phone: 1-866-267-8077

Fax: 1-888-217-7926 Info@vlmotion.com www.vlmotion.com

Voith Turbo GmbH & Co. KG

VOITHSTR. 1 74564 CRAILSHEIM GERMANY GERMANY Phone: +(49) 7951 32-409 Fax: +(49) 7951 32-480 startup.components@voith.com www.voithturbo.com/startupcomponents

Volta Belting 11 CHAPIN ROAD PINEBROOK, NJ 07058 Phone: (973) 276-7905 Fax: (973) 276-7908 pierrec@spc-volta.com voltabelting.com

Vortex Engineering Works
PLOT B-3, PHASE-II, M.I.D.C.
DOMBIVLI - 421 204
THANE MAHARASHTRA 421204, INDIA
Phone: +(91) 251-2871339
Fax: +(91) 251-2870044
sales@vortex-clutch.com www.vortex-clutch.com

VW Broaching Service Inc. 3250 W. LAKE ST. CHICAGO, IL 60624 Phone: (773) 533-9000 Fax: (773) 533-0763 sales@vwbroaching.com www.vwbroaching.com

W.M. Berg DIVISION OF REXNORD 5138 S. INTERNATIONAL DRIVE P.O. BOX 100558 CUDAHY, WI 53110 Phone: (414) 747-5800 Fax: (414) 747-5801 wmberg customer service @wmberg.com www.wmberg.com

Warner Electric

449 GARDNER ST. S. BELOIT, IL 61080 Phone: (815) 389-3771 Fax: 815-389-2582 info@warnerelectric.com www.warnerelectric.com

**Warner Linear** 

6593 REVLON DR. PLANT 1 BELVIDERE, IL 61008 Phone: 800-825-6544 Fax: 815-547-7206 info@warnerlinear.com www.warnerlinear.com

Waukesha Bearings W231 N2811 ROUNDY CIRCLE E SUITE 200 PEWAUKEE, WI 53072 Phone: (262) 506-3000 Fax: (262) 506-3001 sales@waukbearing.com www.waukbearing.com

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TIVOLI PARK, BUNGALOW NO. 5, 225 B A.J.C. BOSE ROAD KOLKATA WEST BENGAL 700020, INDIA Phone: +(91) 33-22837389 / 32918313 Fax: +(91) 33-22836080 wellmanwacoma@wellmanwacoma.com www.wellmanwacoma.com

Wesson Bellowtek Ltd.

NO.6, 10TH STREET; HANGZHOU ECONOMIC & TECHNOLOGIC DEVELOPMENT AREA HANGZHOU ZHEJIANG 310018, CHINA Phone: +(86) 571 8282 9400 Fax: +(86) 571 8516 4185 sales@bellowtek.com www.bellowtek.com

Whittet-Higgins Company 33 HIGGINSON AVE

PO BOX 8 CENTRAL FALLS, RI 02863 Phone: (401) 728-0700 Fax: (401) 728-0703 info@whittet-higgins.com www.whittet-higgins.com

Wichita Clutch

2800 FISHER RD. WICHITA FALLS, TX 76302 Phone: 940-767-2000 Fax: (940) 723-3436 wichita.info@wichitaclutch.com www.wichitaclutch.com

Wichita Company Limited UK AMPTHILL ROAD

BEDFORD BEDFORD BEDFORDSHIRE MK429RD UNITED KINGDOM Phone: +44 1234 350311 Fax: +44 1234 350317 clutch@wichita.co.uk www.wichita.co.uk

Wilson Machine Co. Ltd.

2299 LAPIERRE STREET LASALLE QC H8N 1B7, CANADA Phone: (514) 365-4101 Fax: (514) 365-7511 wilsonmachine@wilsonmachine. www.wilsonmachine.com/

Windsor Exports MANDEEP ESTATE BEHRAMPUR ROAD KHANDSA GURGAON HARYANA 122001, INDIA Phone: +(91) 124-4323900 Fax: +(91) 124-4323998/999 gearindia@india.com www.gearindia.com

Winzeler Gear 7355 W. WILSON AVENUE HARWOOD HEIGHTS, IL 60706 Phone: (708) 867-7971 Fax: (708) 867-7974 jwinzeler@winzelergear.com www.winzelergear.com

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BARTLETT, IL 60103 Phone: (630) 540-5300 Fax: (630) 736-6100 info@wittenstein-us.com www.wittenstein-us.com

**WMH Transmissions Ltd** 

24 CAVENDISH, LICHFIELD ROAD INDUSTRIAL ESTATE TAMWORTH STAFFORDSHIRE B79 7XH UNITED KINGDOM Phone: +(44) 1827 310311 Fax: +(44) 1827 307118 sales@wmh-trans.co.uk www.wmh-trans.co.uk

Wolee Bearings 31TH CAOSEAN ROAD **HUSHAN TOWN** CIXI ZHEJIANG 315302, CHINA Phone: +(86) 574-81351007 Fax: +(86) 574-63838786 info@stainlesssteelbearing.com www.stainlesssteelbearing.com

Worldwide Electric Corp.

1 GROVE ST # 201B PITTSFORD, NY 14534 Phone: 800-808-2131 Fax: (800) 711-1616 www.worldwideelectric.net

WPT Power Corporation

PO BOX 8148 WICHITA FALLS, TX 76307 Phone: (940) 761-1971 Fax: (940) 761-1989 mckelvey@wptpower.com www.wptpower.com

Wyko - London & Overseas Supplies UNIT G, CRACKLEY WAY PEARTREE LANE **DUDLEY DY2 0UW** UNITED KINGDOM Phone: +(44) 1384 246230 Fax: +(44) 1384 246240 landos@wyko.co.uk www.wykó.co.uk

Xtek, Inc. 11451 READING RD. CINCINNATI, OH 45241 Phone: (513) 733-2800 Fax: (513) 733-2989 david.treglia@xtek.com www.xtek.com

Xubi Engranajes S.I.

POLIGONO INDUSTRIAL UMANSORO S/N AZKOITIA GUIPUZKOA 20720 SPAIN Phone: +(34) 943 85 03 58 Fax: +(34) 943 85 00 74

xubi@xubi.com www.xubi.com

**Xuzhou BeiLai Engineering Machinery** Co., Ltd

NO 1. XINDA ROAD ,THIRD INDUSTRIAL PARK DISTRICT OF TONGSHAN , XUZHOU CITY, CHINA XUZHOU JIANGSU 221112, CHINA Phone: +(86) 516-85656717 Fax: +(86) 516-85851577 xzbl99@126.com

Xuzhou Topware Slewing Bearings Co.,ltd ZHANGJI MINE-COAL SQUARE 13# XUZHOU JIANGSU 221140, CHINA

Phone: +(86) 516 85366778 Fax: +(86) 516 85366777 sales@xztopware.com www.xztopware.com

www.xzbeilai.com

Yager Gear Enterprise Co. Ltd. NO. 57, SHIGU LANE, GUOZHONG ROAD DALI DISTRICT TAICHUNG CITY 412, TAIWAN Phone: +(886) 4-2407-6223 Fax: +(886) 4-2407-6218 sa02@yagergear.com www.yagergear.com

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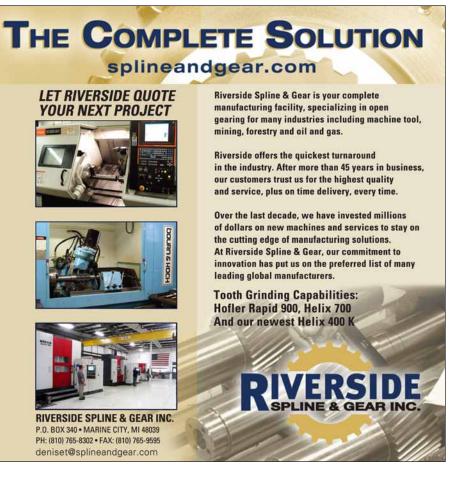
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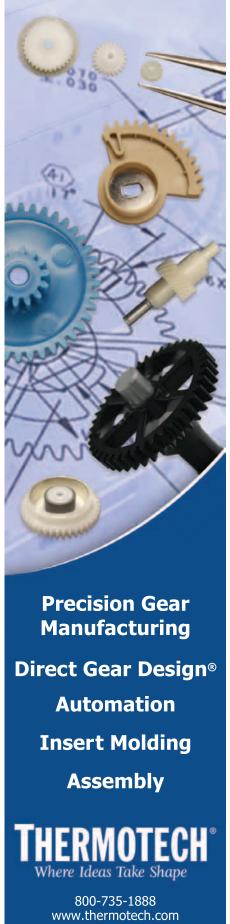
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## Siemens Industry, Inc.

KICKS-OFF ENERGY INITIATIVE, ACQUIRES LMS

Siemens Drive Technologies has kicked off its Integrated Drive Systems initiative to highlight the energy efficiency benefits of its comprehensive and custom engineered product and service offerings, including gearboxes, couplings, motors and drives through a single source. The program offers end users, EPCs and OEMs the ability to reduce operational costs and improve engineering effectiveness. Siemens plans to focus its integrated drive systems program on vertical markets for oil and gas and mining and cement industries. Additionally, Siemens will support integrated drive systems in other markets, such as metals, power generation, water/wastewater, pulp and paper and general manufacturing. Doug Keith, president of Siemens Drive Technologies Division, highlighted several benefits of integrated drive systems. "Our integrated drive systems help to simplify the vendor process to maximize existing design specifications, yet ensure that projects are engineered without a waste of dollars, time and resources. Additionally, we are able to increase the speed and implementation of project development and commissioning, enhance design efficiencies and ensure the best, and most appropriate, components throughout the system," says Keith.

Siemens will support its Integrated Drive Systems initiative with a global team of trained and certified industry experts who handle consultation and proposals, delivery, installation, maintenance and service. The company will incorporate PM@Siemens within the offering, an extensive global training and certification program with methodology based on the essential success factors for project management. And, the company can fully support customized configurations for integrated drive systems; with its localized manufacturing and service footprint, customer needs are quickly

Siemens Drives Technologies Division has four primary U.S. manufacturing facilities, including Elgin, Illinois for gearboxes and couplings; Norwood, Ohio for motors; New Kensington, Pennsylvania. for medium voltage drives; Alpharetta, Georgia, for low voltage and traction drives; and Houston, Texas for sales support.

In other news, Siemens recently expanded its portfolio of industry software by acquiring LMS International NV (Leuven, Belgium), a provider of test and mechatronic simulation for complex products. "The mechatronic simulation will become more and more important for intelligent and competitive product development and production processes. With the acquisition of LMS we are entering a leading position in this software segment as well, and can significantly boost the pace and power of our clients' innovation," said Siegfried Russwurm, member of the Siemens AG Managing Board and CEO of the Industry Sector. The purchase price for LMS amounts to approximately 680 million euro. The transaction is subject to approval by regulatory authorities. With more than 1,200 employees and revenues of around 140 million euro for the first nine months of 2012 (January 1 to September 30), LMS is a global partner to some 5,000 companies in the automotive, aerospace and other industries. The privately held company is supporting all of the Fortune 500 automotive and aerospace manufacturers and their tier-one suppliers with a combination of mechatronic simulation software, testing systems and engineering services.

LMS offers a complete software platform to model, simulate and test vehicles, aircraft and other complex products, optimizing their acoustics, vibrations, oscillations, fatigue strength and dynamics. The business activities of LMS are to be integrated into the product lifecycle management (PLM) software portfolio within the Siemens Industry Automation Division. "With the acquisition of LMS, we are expanding our portfolio of industry software in an area that is critical for many customers. They will now be able to simulate, test, optimize and produce their products in a unified, consistent data environment. This will make them faster, more efficient, more flexible and more cost effective," explains Anton S. Huber, CEO of the Industry Automation Division.



## **Bosch Rexroth**

OPENS NEW CHINA PLANT

Bosch Rexroth has taken a new plant into operation in Wujin, China, which employs approximately 1,200 associates. In order to react to the special regional requirements even faster, the local development activities will be bundled in an internal R&D center starting in 2013. Overall, the company will invest €83 million in the expansion of its presence in the region. Bosch Rexroth produces hydraulic, linear motion technology, and pneumatics components and systems in Wujin.

"Our 'local for local' strategy will help us tap additional market segments that could not be reached from Germany. In the long run, this will also ensure higher utilization at the German plants," said Dr. Bertram Hoffmann, member of the board of Bosch Rexroth AG, before numerous representatives from politics and the economy. "But in addition to production, we will also establish an R&D center in Wujin, mainly for industrial automation," affirmed Fo Wai Lau, managing director of Bosch Rexroth in China. Here, engineers are developing regional variants based on the German product platforms that meet the requirements of the company's local customers.

Bosch Rexroth has been present in China for more than 30 years and is continuously expanding the local value creation. Last year, the company has made almost €1billion in sales in China and has thus more than quadrupled its business volume since 2005. The company employs a total of about 3,900 staff in China. Most of the components and systems from the new plant with a total area of about 70,000 square meters are supplied to the largest global market for all kinds of machines.



One focus, for example, is on system solutions for more energy efficiency. Machine concepts developed in close collaboration with Chinese manufacturers consume up to 50 percent less energy while offering the same level of productivity. All experts agree that China will be achieving clearly higher growth rates than Europe or America over the next decade.

The plant in Wujin is part of Bosch Rexroth's global growth strategy. Over the past years, the company has, for example, also expanded its capacities in North and South America, Eastern Europe and India.

"We are striving to achieve a balanced revenue distribution among the markets of the triad to be able to better compensate for regional fluctuations," said Hoffmann.

## **Parker Aerospace**

FORMS JOINT VENTURE WITH GE AVIATION

Parker Aerospace and GE Aviation recently announced that they have reached an agreement to form a joint venture, Advanced Atomization Technologies, LLC, to enhance the development and manufacture of commercial aircraft engine fuel nozzles. This represents a critical addition to the comprehensive GE fuel management team. The 50-50 joint venture — created specifically to produce fuel nozzles for current and future GE Aviation commercial engine platforms (including aerospace and aero-derivative engines) — will be located in the Parker Gas Turbine Fuel Systems Division facility in Clyde, New York. The joint venture will employ approximately 300 skilled assemblers, technicians, engineers, and other professionals in the production of advanced fuel nozzles and related products for GE Aviation. (No financial information on the joint venture has been disclosed.) "GE and Parker Aerospace are both world-class aviation businesses and this joint venture will allow us to further evolve our existing relationship and offer best-in-class design, manufacturing and program management for these critical components," said Mike Sims, GE Aviation Combustor General Manager. Continuing its long history in the Clyde community, the facility will be a center of excellence in lean manufacturing and fuel-nozzle development. Leanne Collazzo, current site leader of the Parker facility, has been named the general manager for the new Advanced Atomization Technologies, LLC. "Parker is excited to enter into a joint venture with GE Aviation to ensure the future of the Clyde facility through growth and increased synergy with our customer," said Manuel Bajaksouzian, General Manager of the Parker Aerospace Gas Turbine Fuel Systems Division. Pairing Parker's fuel nozzle technology and GE's advanced TAPS combustion technology will dramatically reduce engine emissions while increasing fuel efficiency; two of the most important elements for enhanced engine performance. Joint development and manufacturing expertise will result in superior fuel nozzles in future products. GE Aviation is currently developing a new family of engines for the aerospace industry including LEAP (in partnership with Snecma), GE9X and Passport. These important new programs are expected to fuel growth for the joint venture and generate strong production orders and a robust services business.

#### REPORTS TOTAL 2012 MANUFACTURING ORDERS UP

October U.S. manufacturing technology orders totaled \$459.16 million according to the Association for Manufacturing Technology (AMT). This total, as reported by companies participating in the United States Manufacturing Technology Orders (USMTO) program, was down 31.3 percent from September and down 0.1 percent when compared with the total of \$459.41 million reported for October 2011. With a year-todate total of \$4,753.68 million, 2012 is up 5.3 percent compared with 2011. These numbers and all data in this report are based on the totals of actual data reported by companies participating in the USMTO program.

"Orders continue to be on pace for a record-setting year, and a monthly drop was fully expected in the month following IMTS," said Douglas K. Woods, AMT president. "While manufacturing continues to play a strong role in economic recovery, our main concern heading toward the end of the year is that lawmakers do what's necessary to avoid the fiscal cliff, and the implications it could have on the broader economy."

The USMTO report, compiled by the trade association representing the production and distribution of manufacturing technology, provides regional and national U.S. orders data of domestic and imported machine tools and related equipment. Analysis of manufacturing technology orders provides a reliable leading economic indicator as manufacturing industries invest in capital metalworking equipment to increase capacity and improve productivity. U.S. manufacturing technology orders are also reported on a regional basis for five geographic breakdowns of the United States:

## **Northeast Region**

Manufacturing technology orders in the Northeast Region in October totaled \$63.69 million, down 19.7 percent from September's \$79.27 million and down 3.6 percent when compared with the October 2011 figure. At \$640.83 million, 2012 year-to-date is down 5.7 percent when compared with 2011 at the same time.

## **Southern Region**

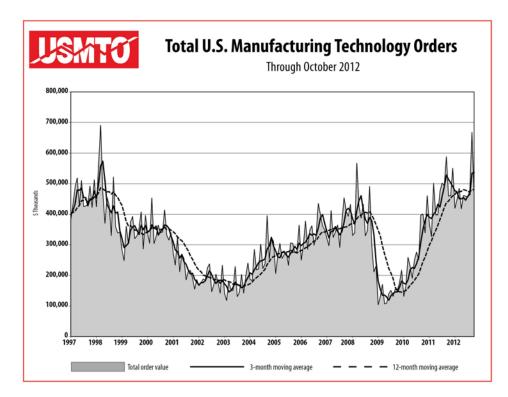
Southern Region manufacturing technology orders totaled \$60.69 million in October, down 41.1 percent from the \$102.99 million total for September but 12.8 percent higher than the total for October 2011. The year-to-date total of \$683.23 million is 15.3 percent more than the comparable figure for 2011.

## **Midwest Region**

At \$162.75 million, October manufacturing technology orders in the Midwest Region were down 20 percent when compared with the \$203.33 million total for September but up 10.3 percent when compared with October a year ago. With a year-to-date total of \$1,530.30 million, 2012 is up 4.9 percent when compared with 2011 at the same time.

## **Central Region**

October manufacturing technology orders in the Central Region totaled \$124.77 million, 30.2 percent lower than September's \$178.71 million and down 8.8 percent when compared with the October 2011 figure. At \$1,341.76 million, the 2012 year-to-date total was 6.8 percent more than the comparable figure for 2011.



## **Western Region**

Western Region manufacturing technology orders in October stood at \$47.27 million, down 54.6 percent from the September total of \$104.07 million and 14.3 percent lower than the figure for October 2011. The \$557.56 million year-to-date total was 5.7 percent above the total for the same period in 2011.

## Vacon

#### TABLISHES SINGAPORE REGIONAL CENTER

Global AC drives manufacturer Vacon has established a regional center in Singapore. The new center started operations in August 2012. Vacon's regional center in Singapore ensures that Vacon's entire product portfolio and service network offering are available to customers in the region. The center is also in charge of effective sharing of best practices, know-how and the professional personnel that the company already has in the Middle East, India, South East Asia and Pacific region. This will open up new opportunities for Vacon to gain market share and increase volumes in this region with its huge population and great market potential.

"As a major world trade node with a business-friendly economy, Singapore was a logical location for Vacon to establish a regional center. We are at the heart of the region which is one of Vacon's major growth areas," says Olli Tevä, Vacon's vice president for Middle East, India, SEA, Pacific. "Singapore has also a rich supply of skilled and experienced workers, which will help us to continuously improve our customer service in the region. As many of Vacon's global customers have their regional offices in Singapore, it will help us in building seamless cooperation with them. This also reflects Vacon's values: keeping customers and partners at the heart of Vacon's operations," concludes Tevä.

## **IECC**

#### PRAISES INDUSTRIAL EFFICIENCY LEGISLATION

The Industrial Energy Efficiency Coalition (IEEC) praised House passage of H.R. 6582, the American Energy Manufacturing Technical Corrections Act. "There are huge gains in industrial energy efficiency that we are leaving on the table by not addressing the inefficiencies in many manufacturing and industrial processes," said Paul Hamilton, chair of the IEEC. "Policies such as this are helping to understand and tackle these industrial energy efficiency opportunities." The bill directs the Department of Energy (DOE) to establish collaborative research and development partnerships with other programs to support the use of innovative manufacturing processes and to support applied research for development, demonstration, and commercialization of new technologies and processes to improve industrial efficiency. "Ensuring that all industrial energy-saving technologies are fully incorporated into the Department of Energy's activities is critical," Hamilton said. Energy intensive manufacturers have long been aware of the cost of inefficient energy use and have made major investments in sensors, controls, and automation to reduce their energy costs. "The challenge now is to drive awareness and deployment of these energy efficiency opportunities across the entire manufacturing sector, especially into the less energy intensive sites which represent some 150,000 facilities across the United States," said Bruce Quinn, a founding member of the IEEC.

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## **PTDA**

Wraps Up 2012 with Successful Industry Summit

The PTDA Industry Summit, held on October 18-20, 2012 in Dallas, Texas, featured more than 700 participants for two-and-a-half days of networking opportunities and good old-fashioned Texas-style fun. The event kicked off with a Motion Control Showcase featuring 18 exhibitors displaying their products to existing and potential customers. This was followed by the First-Timer Event, which gave seasoned experts the chance to offer Industry Summit newcomers advice and tips for making the most of the conference. Also on the conference's opening night, a Next Gen After Party offered attendees age 40 and under the opportunity to catch up with peers and participate in a mixology competition.

To better promote peer-to-peer networking, the Industry Summit featured a Distributor Forum and a Manufacturer Forum. In each of these forums, distributors and manufacturers separately tackled issues that affect the distributor-manufacturer relationship. Nearly 120 manufacturers exhibited at MD-IDEX (Manufacturer-Distributor Idea Exchange), where supply chain partners met face to face in over 600 scheduled and open appointments and engaged in focused, one-on-one group discussions about how to work together.

The conference came to a close with a unique Dallas experience as every delegate had the opportunity to see Cowboys Stadium from a viewpoint usually reserved for the NFL players-from the field. Attendees began their evening by entering the stadium through the Miller Lite Club, the same way the Cowboys enter the stadium on game day. A reception was held right on top of the Cowboys Lone Star at the 50-yard line, and sponsor logos lit up the enormous DiamondVision screen. Attendees showed off their team pride by wearing jerseys from their favorite teams. Admittedly, not all of the jerseys were from the NFL, but team

rivalries were most evidentincluding Chicago Bears and Detroit Lions fans.

Dinner featured outstanding Texas barbecue items served right on the field. During and after dinner, two Dallas Cowboys Cheerleaders posed for photos with attendees and their guests. Attendees also had an opportunity to show off their skills by run-

ning an agility drill, throwing footballs or kicking one through the uprights.

## **PTDA 2012 Industry Summit** at a Glance

- Themed "Big Ideas to Steer Your Business."
- Total attendance was 715, which included 570 industry delegates.
- Overall delegate participation was up 9 percent over 2011 attendance. Additionally, distributor attendance showed an increase over last year of 12 percent for individual delegates and 10 percent for companies represented, compared to 2011 numbers.
- International delegates from Argentina, Belgium, Canada, France, Germany, Italy, Japan, Mexico, the Netherlands, Trinidad and Tobago, and the United Kingdom attended.

## **Industry Summit Highlights**

Opening keynote address by Scott Klososky, "Trends, Technology & Taking the Lead."

- Second keynote address by Alan Beaulieu of the Institute for Trend Research, "The Beaulieu Report."
- Workshop: "The Changing Sales Model" by Scott Klososky.
- Workshop: "Knowledge Transfer and the Emerging Generations" by Bob Wendover of the Center for Generational Studies.

## **Next Stop: Spring Leaders** Conference

The PTDA will be hosting its annual Spring Leaders Conference March 21-23, 2013, in San Antonio, Texas. The



Spring Leaders Conference includes: committee meetings for PTDA volunteers and elected directors, a general educational session for all PTDA members and the Leadership Development Conference. Featured in the general educational session is Kevin Boyle. president, Industrial Distribution Consulting, LLC, a widely recognized expert in the field of distributor and manufacturer business relationships. Boyle's interactive program, "Building Profitable Partnerships Between Distributors and Manufacturers Through Understanding," enables participating supply chain partners to dig into the details of how to improve through true value-added programs and hot-button issues.

Randy Disharoon, a strategic account manager with Rexnord Industries, LLC, and former U.S. Navy nuclear engineer and trainer, will be leading the day-long Leadership Development Conference component of the PTDA 2013 Spring Leaders Conference. Disharoon's program, "Developing Leaders for What's Next in the PT/MC Distribution Sales Channel," prepares up-and-coming leaders for changes in the marketplace, communications strategies and the world of globalization with sessions, self-evaluations and interactive exercises participants will undertake together and separately to bring out the best leadership qualities in each other.

To register for the Spring Leaders Conference, visit www.ptda.org/springleadersconference. PTE

## January 21-24-Automate 2013. McCormick

Place, Chicago. Automate is the largest solutions-based showcase of automation technologies in North America. Formerly the International Robots, Vision & Motion Control Show, which dates back to 1977, Automate now demonstrates the full spectrum of automation technologies and solutions for a broad array of industries. The show is held once every two years. Companies that provide integration of automation, robotics and machine vision will show actual demonstrations of systems at the show. This allows attendees to see live demos solving challenges they face in their industry, and also to learn from solutions used in other industries that may be beneficial to them. The rest of the show features the latest automation, robotic, vision and motion control technologies and systems on display from leading global suppliers. A comprehensive educational conference accompanies the Automate show. Featuring a broad array of classes from beginner to advanced skill levels, the conference offers something for all attendees—they can take one class or four full days of training. ProMat, a material handling and logistics show, is co-located with Automate 2013. For more information, visit www.automate2013.com.

## February 7–8–Motor and Drive Systems 2013. Orlan-

do, Florida. Motor & Drive Systems 2013 is an international conference focused on the latest growth trends and technical advancements impacting motor and drive systems. Join hundreds of peers and potential business partners and discover how new technologies are improving performance, energy efficiency and providing cost savings in a variety of applications. This annual conference will feature more than 25 presentations on new motor and drive technologies and design considerations. motion control, power electronics/ modules and components. Sessions will also cover market trends and growth areas as well as regulatory and safety issues. The event serves technical and management professionals involved in all sectors of motor, drive and motion control technologies including OEMs, end users, integrators and dealers. The conference provides the best forum to learn from leading motor and drive system manufacturers on new technologies entering the market and what's ahead. Newsworthy additions to the 2013 show include new motor technologies and applications, an OEM design engineer panel, magnetic manufacturer panel, regulatory and safety issues and design and development of motor and drive systems. For more information, visit www.e-driveonline.com.

## March 12–14—Gearbox **CSI-Forensic Analysis of** Gear and Braking Fail-

**ures.** Hyatt Regency Baltimore on the Inner Harbor, Baltimore, Maryland. Determining the cause of a failure in a gearbox is like a "whodunnit" mystery. What caused the failure: The bearings, a gear, the lubrication or a shaft problem? Where do you start, and how can you tell? Instructors Raymond Drago and Joseph Lenski, Jr. from Drive Systems Technology, Inc. will help gear designers gain a better understanding of various types of gears and bearings. Learn about the limitation and capabilities of rolling element bearings and the gears that they support so you can properly apply the best gear-bearing combination to any gearbox, whether simple or complex. A certificate will be awarded upon completion of the seminar. For more information, visit www.agma.org.

## March 19-21—AeroDef Manufacturing 2013.

Long Beach, California. AeroDef Manufacturing is an exposition and technical conference for the aerospace and defense manufacturing industry. Produced by the Society of Manufacturing Engineers (SME), in partnership with industry OEMs, the show's mission is to foster innovation across the extended enterprise to reduce costs, expedite production times and maintain manufacturing competitiveness in the global economy. AeroDef showcases the industry's most advanced technologies across an innovative floor plan designed to facilitate interaction and business relationships between exhibitors and buyers looking for integrated solutions. Keynote speakers and panelists come from the highest level of government and business. They come to share their vision of the potential of technology, collaboration and public policy to transform manufacturing - concepts that attendees can actually experience on the exposition floor. AeroDef is co-located with Composites Manufacturing 2013. For more information, visit www.aerodefevent.com.

## March 21-23-PTDA **Spring Leaders Confer-**

ence. Hotel Contessa, San Antonio, Texas. The three components of the Spring Leaders Conference include governance meetings for PTDA committees, the Leadership Development Conference and a General Educational Session. Kevin Boyle, president of Industrial Distribution Consulting, LLC, will present a three-hour interactive workshop focused on the power transmission distribution channel. Randy Disharoon, strategic account manager of Rexnord Industries, LLC will present a workshop on developing leaders in the PT/MC distribution sales channel. For more information, visit www.ptda.org.



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# e more you rock and roll

## The concept is simple enough.

Take the traditional rocking chair, the one you'd find on a front porch or the corner of the living room, and give it a 2012 twist. iRock is a power-generating rocking chair that can also charge your iPhone or iPad.

iRock is equipped with a generator that transforms the rocking motion into power. If that's not enough technology for you to digest, the chair also comes equipped with a set of speakers built into the backrest. The more you rock, the more battery life you're giving to your smartphone or tablet device.

In the old days, the only constructive thing you could do on a rocking chair was whittle wood or take a nap.

Developed by Micasa Lab in Zurich, the iRock makes the age-old oak rocking chair significant again. It boasts a self-sufficient iPad dock and sound station. For the furniture enthusiast, the chair is handcrafted out of Swedish

pine wood and comes in five different colors.

While we applaud its ingenuity, the iRock project didn't get off the ground so well. According to the company's website, it was a challenge at first to get the generator to work. The Micasa team originally used rubber bands

and springs to increase the effect of the movement but ended up with a solution using a winding mechanism that is "geared up" to run the generator.

Essentially, the engineering team explored how to collect energy, particularly from movement and friction, and harness it in some form (a 60 minute rocking session, for example, can recharge an iPad up to 35 percent).

In spending many long nights attempting to solve the power generation issues, the Micasa engineers came up with similar mechanisms that can

be applied to doors, drawers and stairs. Soon, something as simple as closing a door might be able to support power generation.

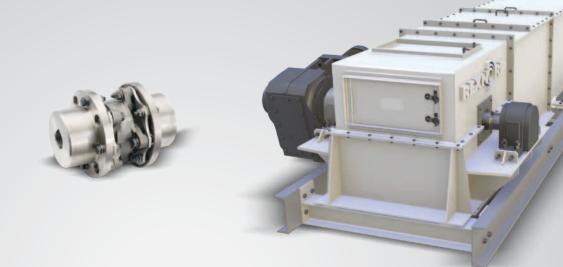
#### And the drawbacks?

Currently the iRock is only compatible with Apple devices. If you're an Android user--well, you're just another guy/gal sitting in a rocking chair. The price tag, (iRock retails for \$1,300 online) also seems a bit steep. For that kind of money, the Power Play team would like the iRock to heat the house or perhaps power a flat screen television.

Still, the iRock hands down beats typical gift-giving fare like the necktie, Argyle socks or a Wisconsin cheese platter.

We publish in Chicago Bears country, after all! PTE





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